

Introduction to visibility and model fitting tips

*Erasmus Summer School
The 2010 VLTI summer school
April 17 - April 22*

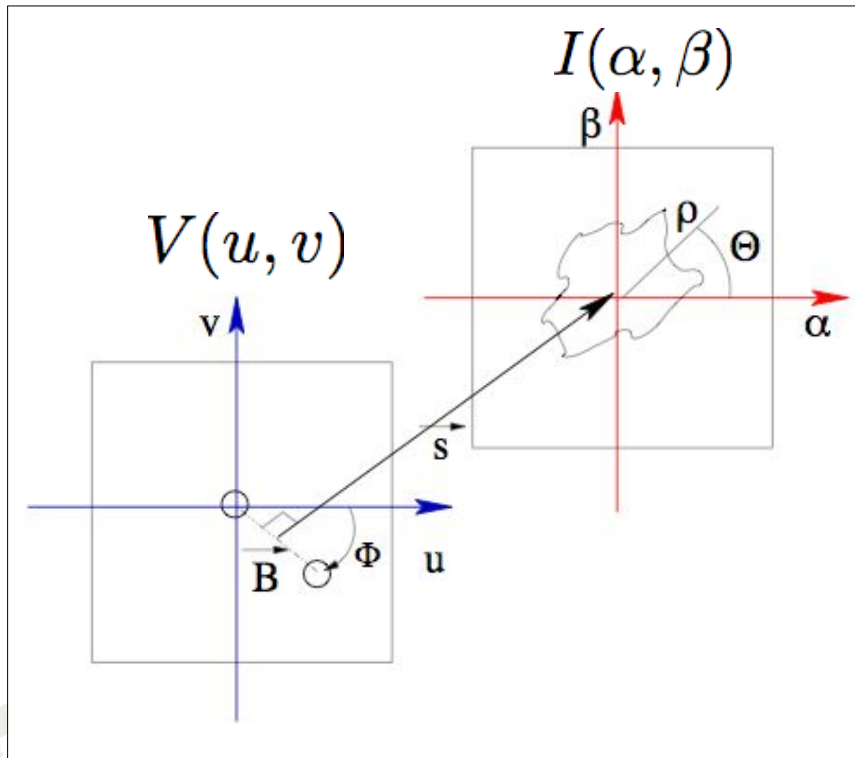
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based on the presentation of J.P. Berger & D. Segransan
at the Goutelas Summer school (2006)

What is "visibility" ?

A practical application of the Van-Cittert / Zernike theorem



The VCZ theorem links:

the intensity distribution of an object in the sky plane (far field)

to the complex Fourier-transform, measured in the array plane.

$$V(u, v) = \frac{\int \int I(\alpha, \beta) \exp^{-2i\pi(\alpha u + \beta v)} d\alpha d\beta}{\int \int I(\alpha, \beta) d\alpha d\beta}$$

This relation is a normalized **Fourier transform** (i.e. total flux does not matter).

Spatial frequency coordinates $\mathbf{u} = \mathbf{B}_x / \lambda$, $\mathbf{v} = \mathbf{B}_y / \lambda$

where B_x and B_y stand for projected baselines coordinates on the x and y axes of telescope

Visibility and single dish telescope

Example : resolved binary star (HIP 4647) observed at the Special Astronomical Observatory (Zelentchouk)

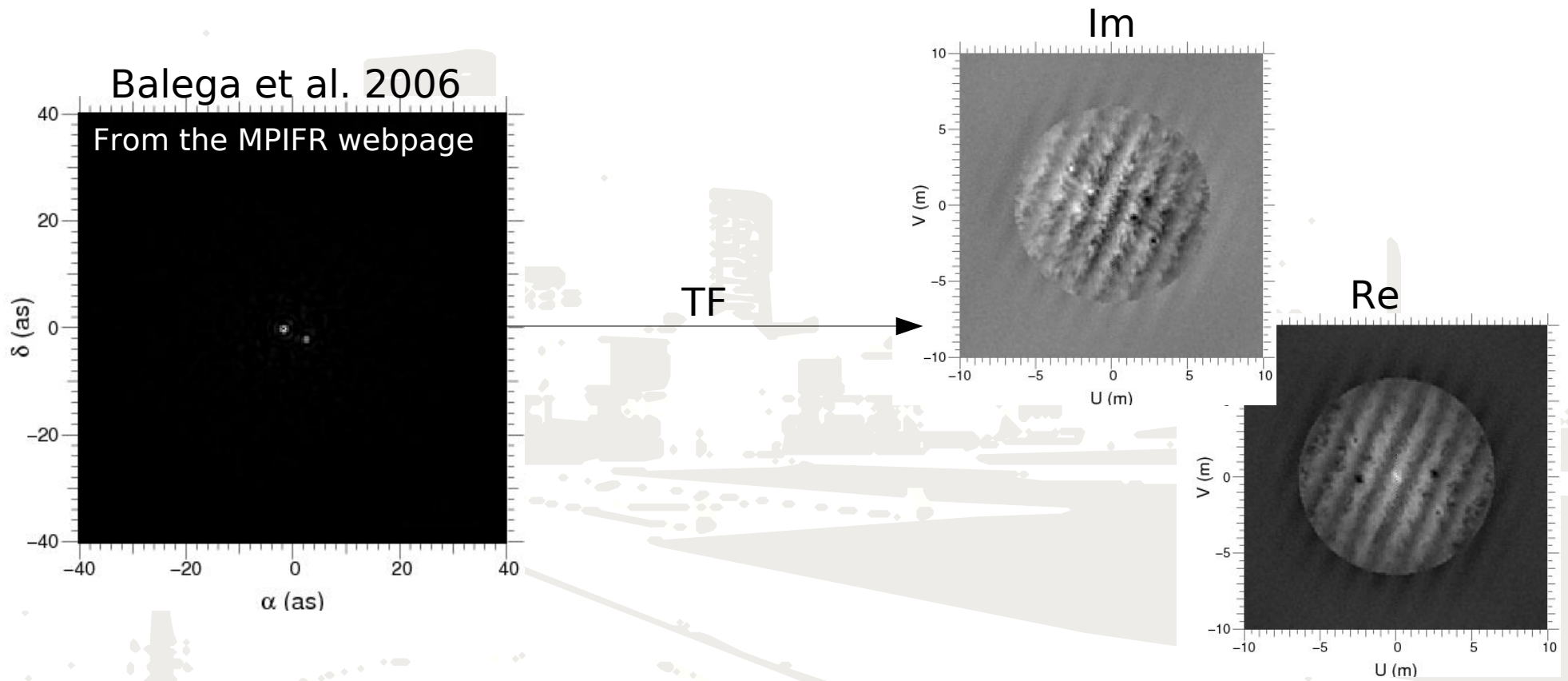


Image : $I(x,y) = O * \text{PSF} \rightarrow |V(u,v)|, \phi(u,v)$ & cut-off frequency at D/λ

Visibility and single dish telescope

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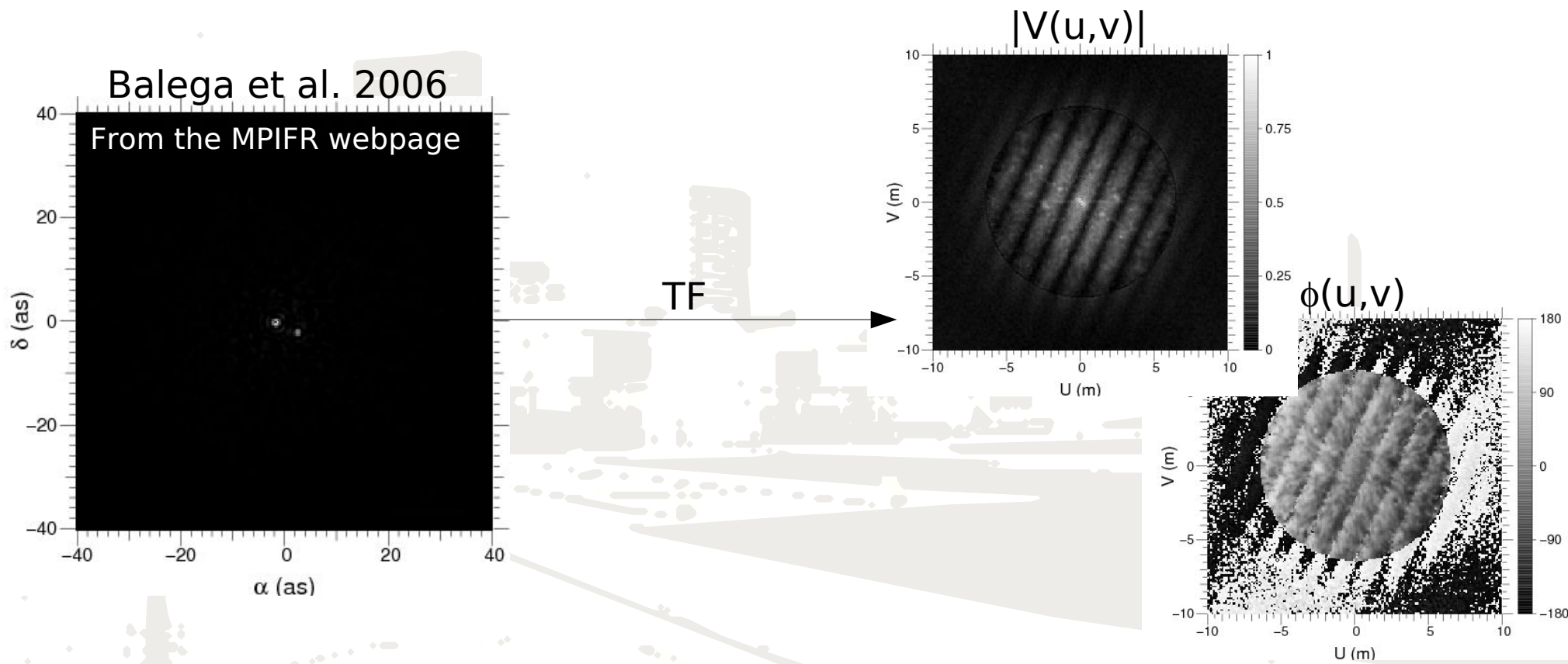


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Visibility and single dish telescope

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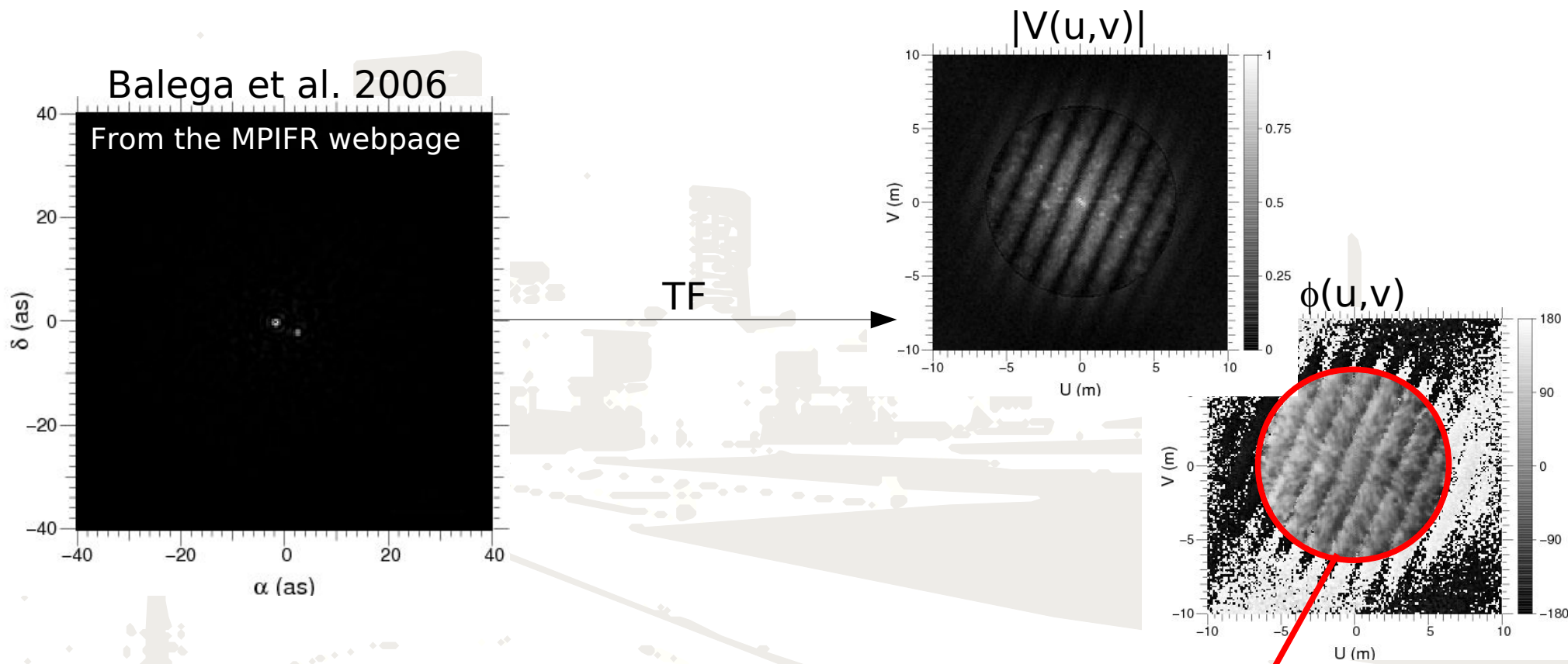


Image : $I(x,y) = O * \text{PSF} \rightarrow |V(u,v)|, \phi(u,v)$ & cut-off frequency at D/λ

Visibility and single dish telescope (speckle masking)

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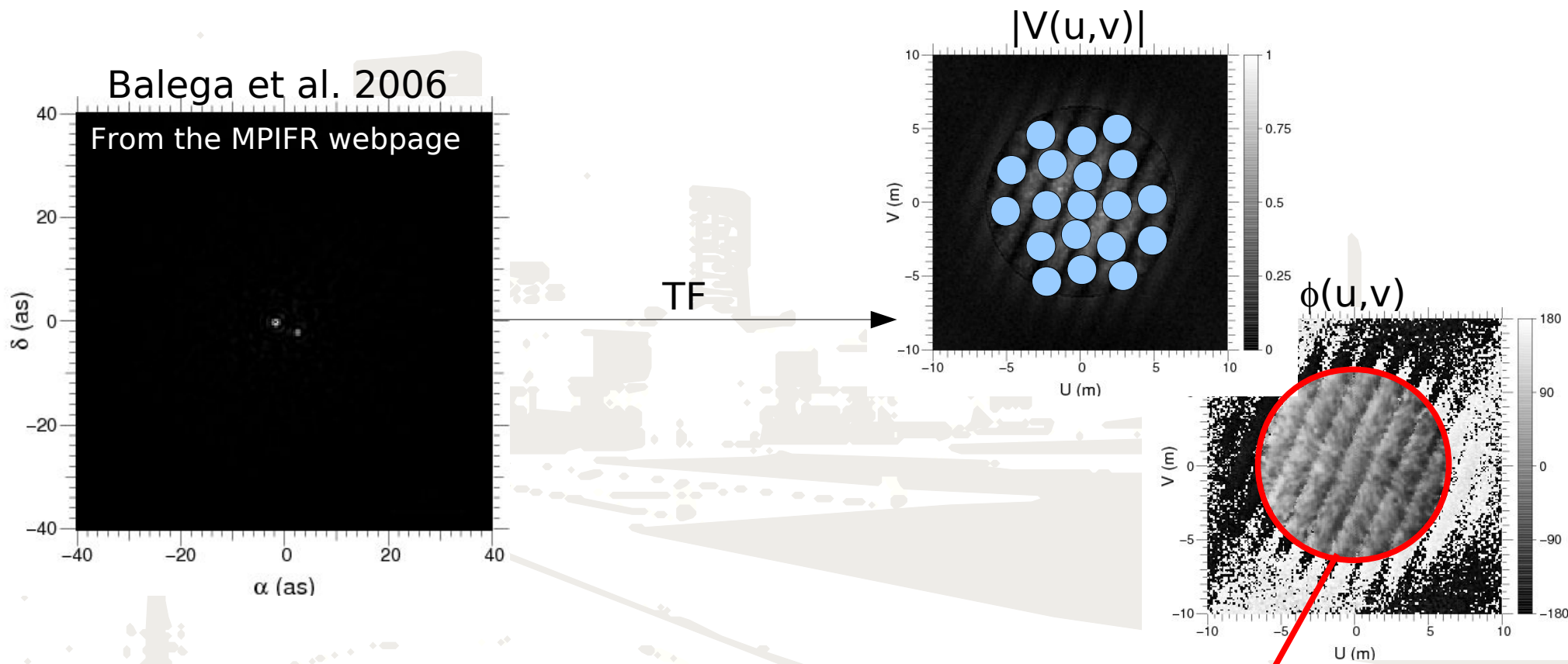
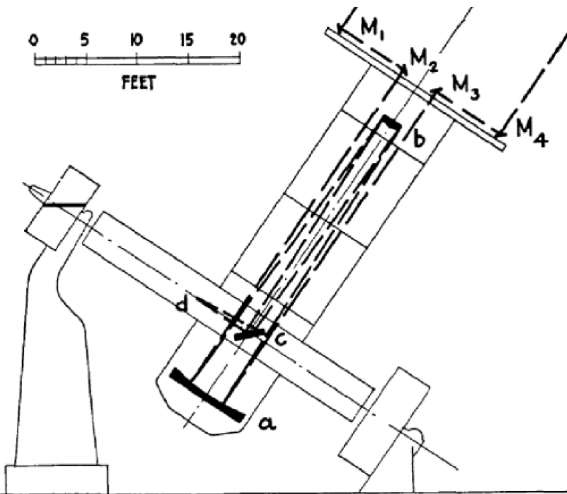


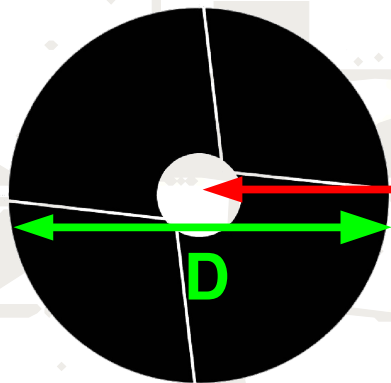
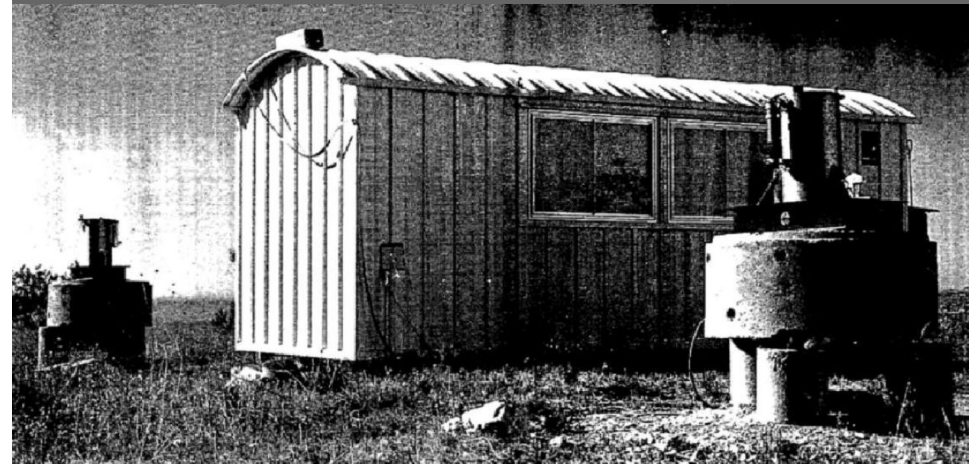
Image : $I(x,y) = O * \text{PSF} \rightarrow |V(u,v)|, \phi(u,v)$ & **cut-off frequency at D/λ**

Long-baseline optical/IR interferometry

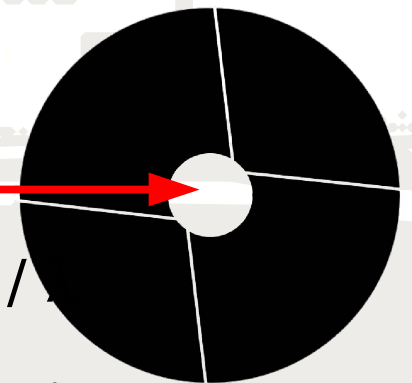
Michelson & Pease, 1921



Labeyrie, 1975



B



- Single-dish telescope : $0 < F_{ij} < \alpha D / \lambda$
 - 2T Interferometer : $F_{ij} = 0$ and B / λ
- \Rightarrow Only one (or very few) spatial frequency is scanned at once by an interferometer

VLT

UT1

ATs

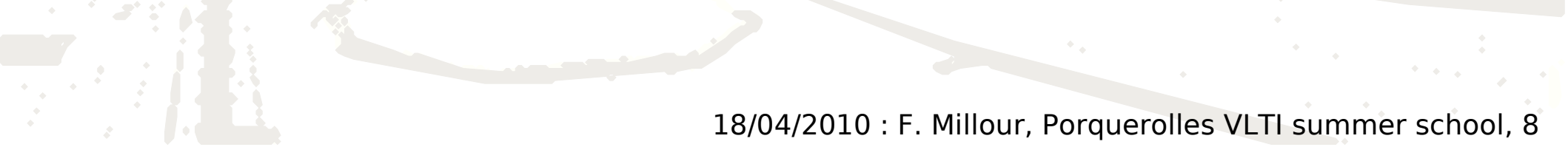
UT2

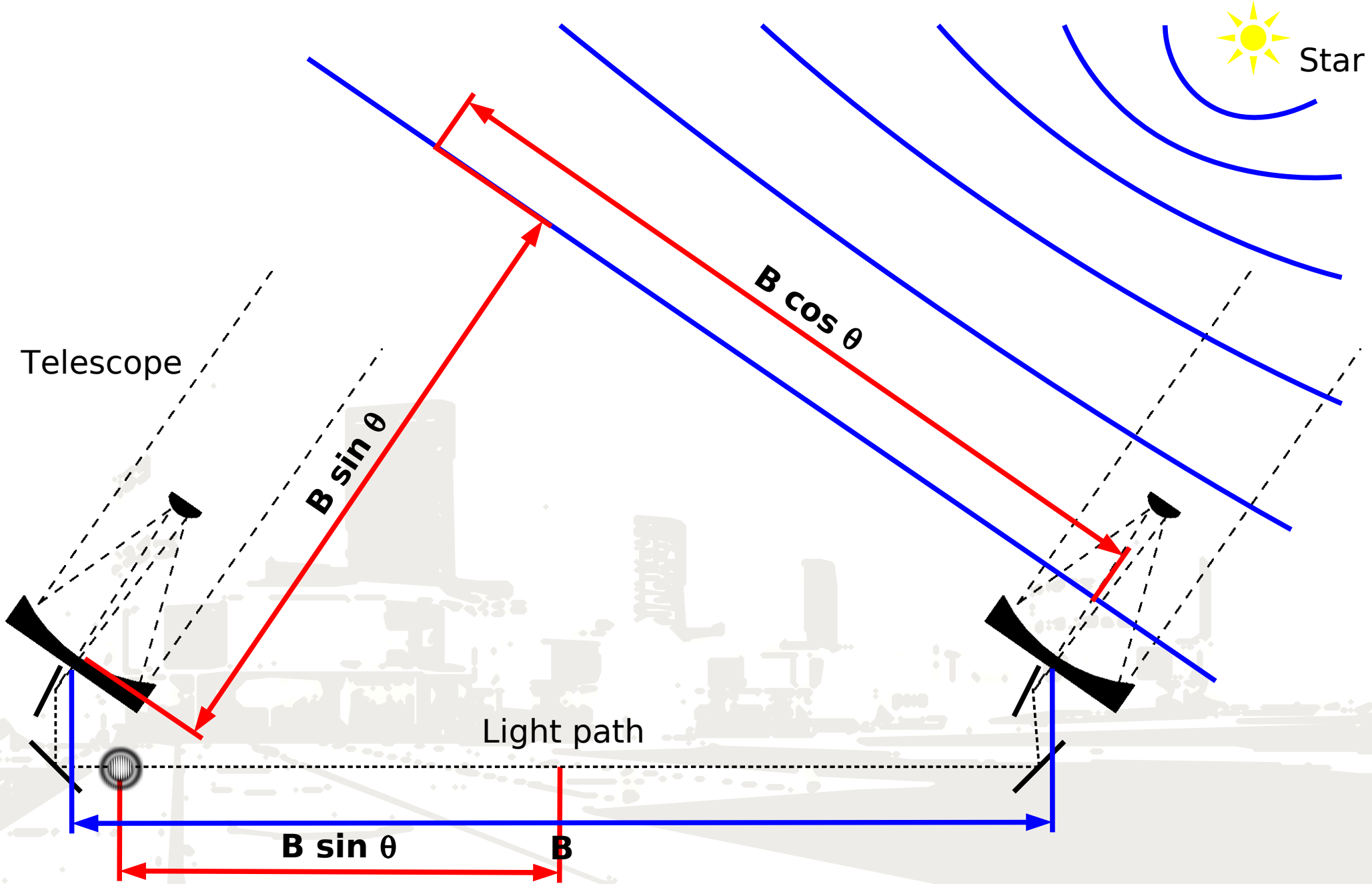
UT3

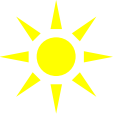
UT4

Focal lab.

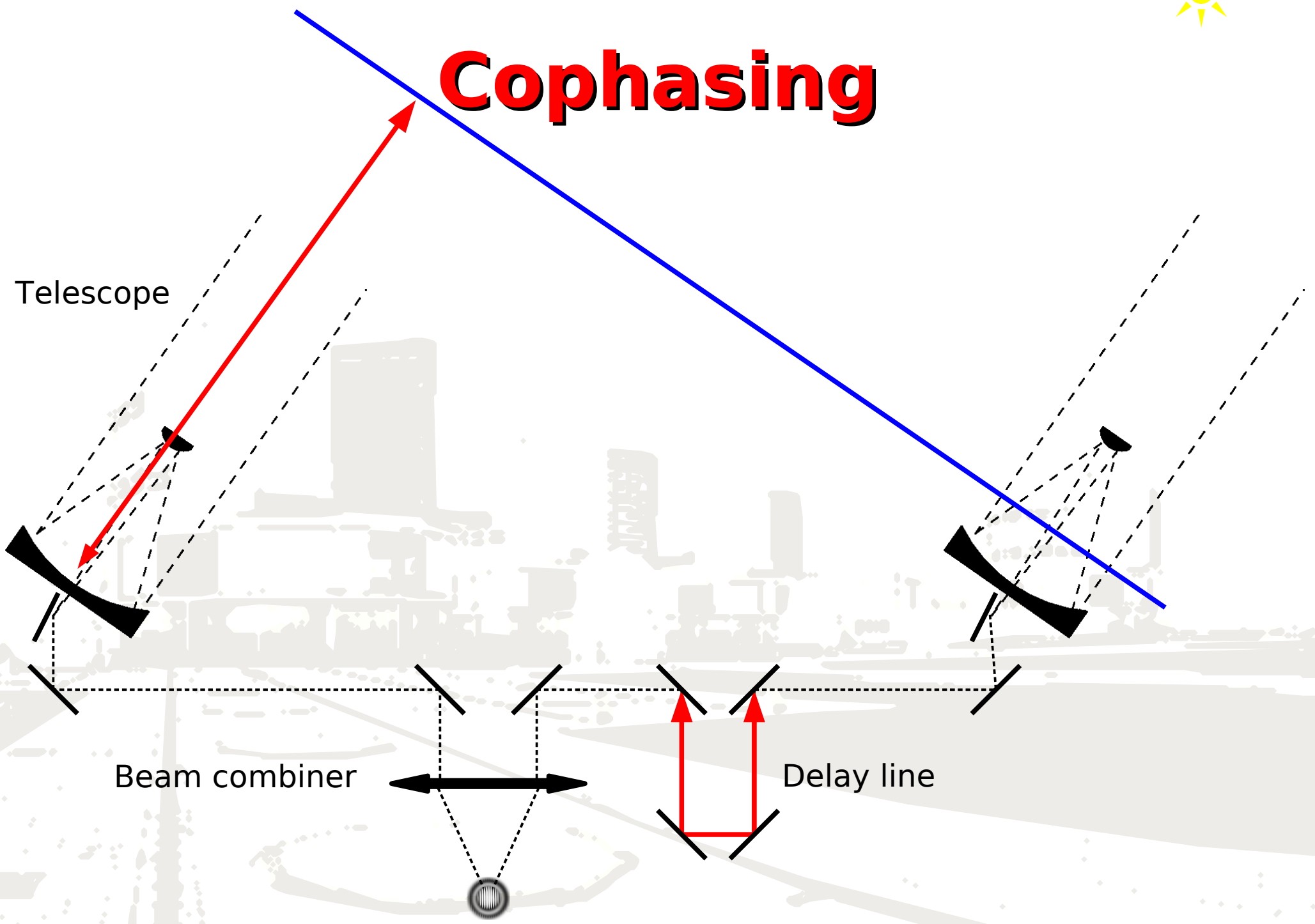
AT stations





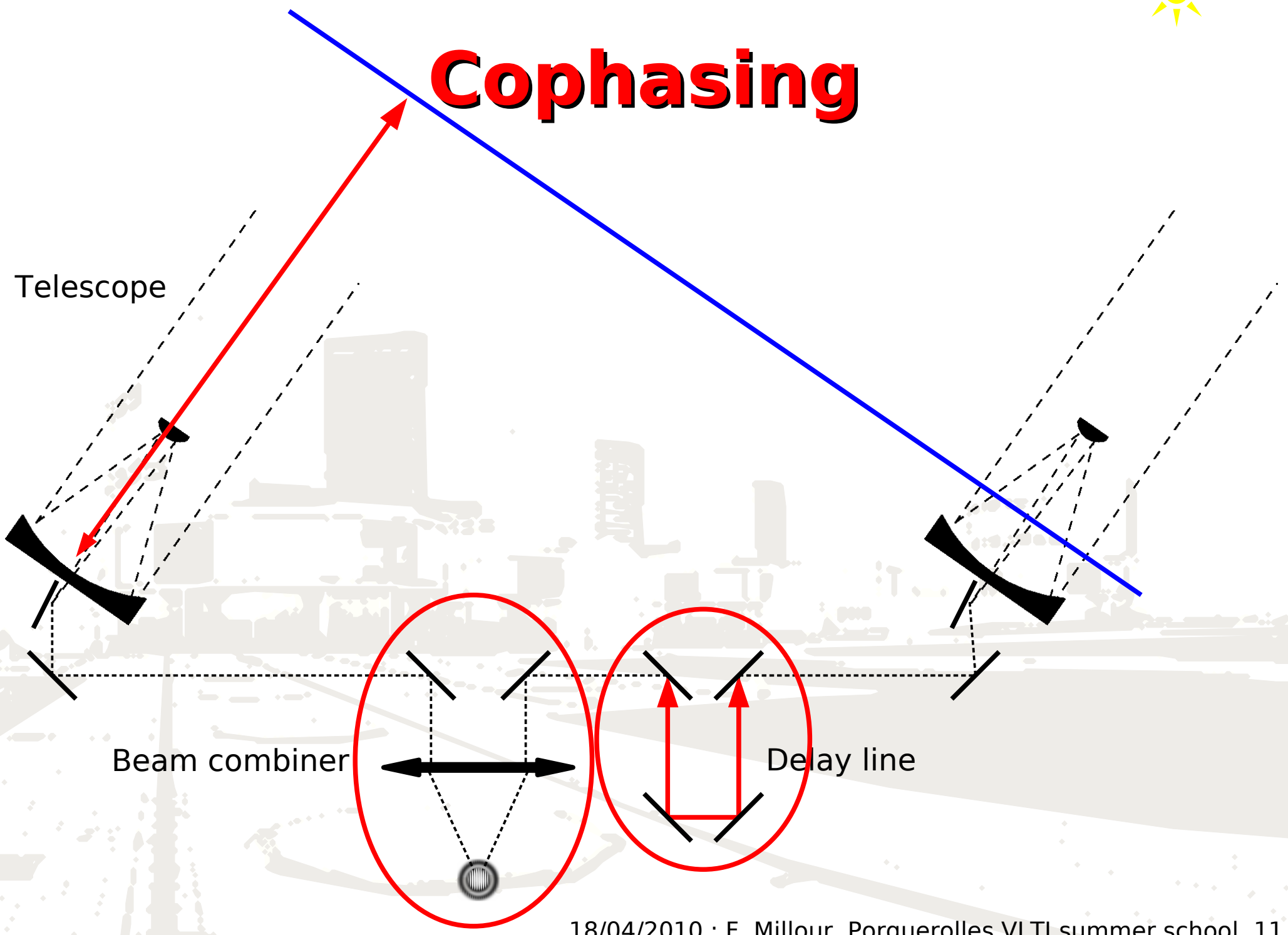


Cophasing

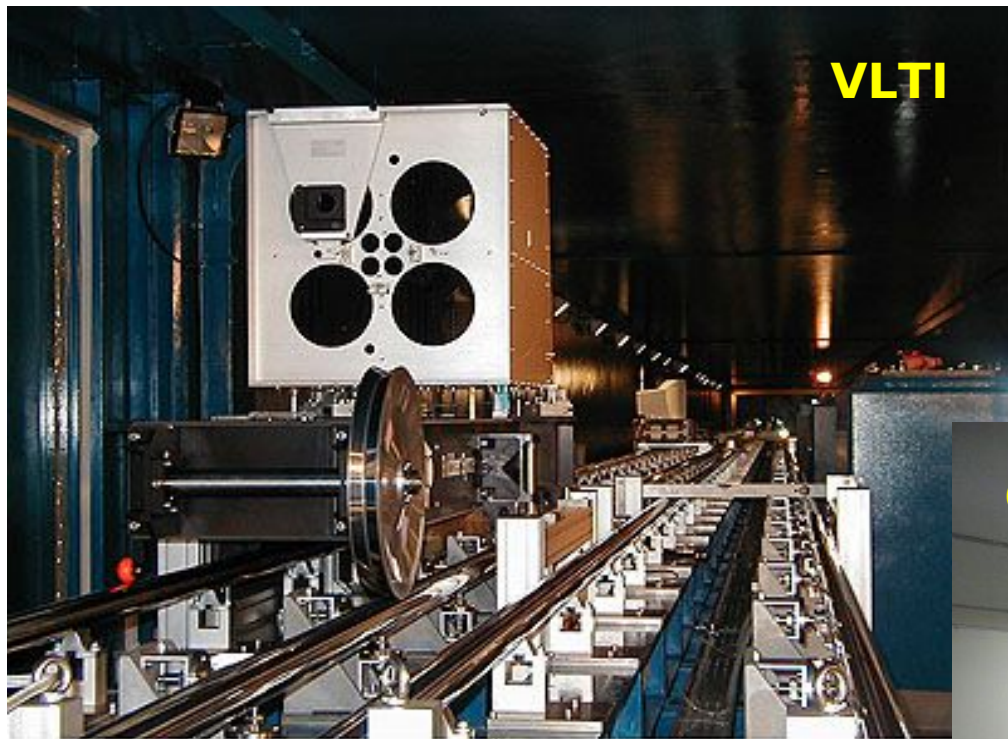




Cophasing



Delay Lines



VLTi

VLTi Delay Line Retroreflector Carriage

ESO PR Photo 26c/00 (11 October 2000)

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CHARA

Instruments

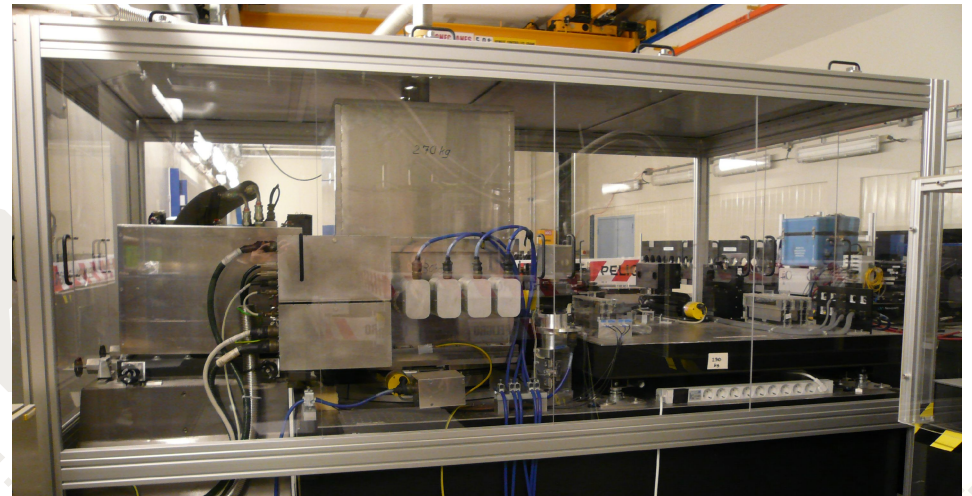
VINCI

- 2 telescopes
- K Band ($2\mu\text{m}$)
- Wideband



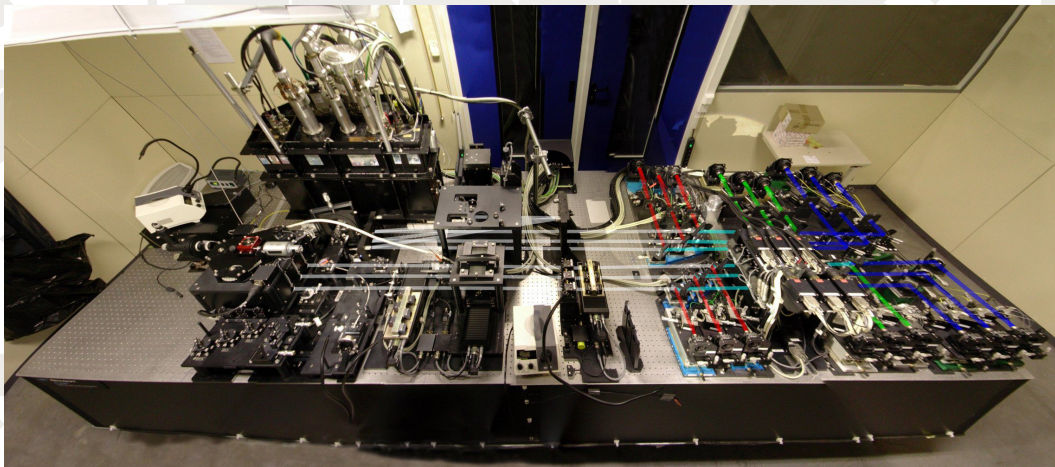
MIDI

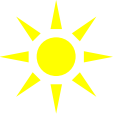
- 2 telescopes
- N Band ($8-13\mu\text{m}$)
- Spectral resolutions $R=30$ & 300



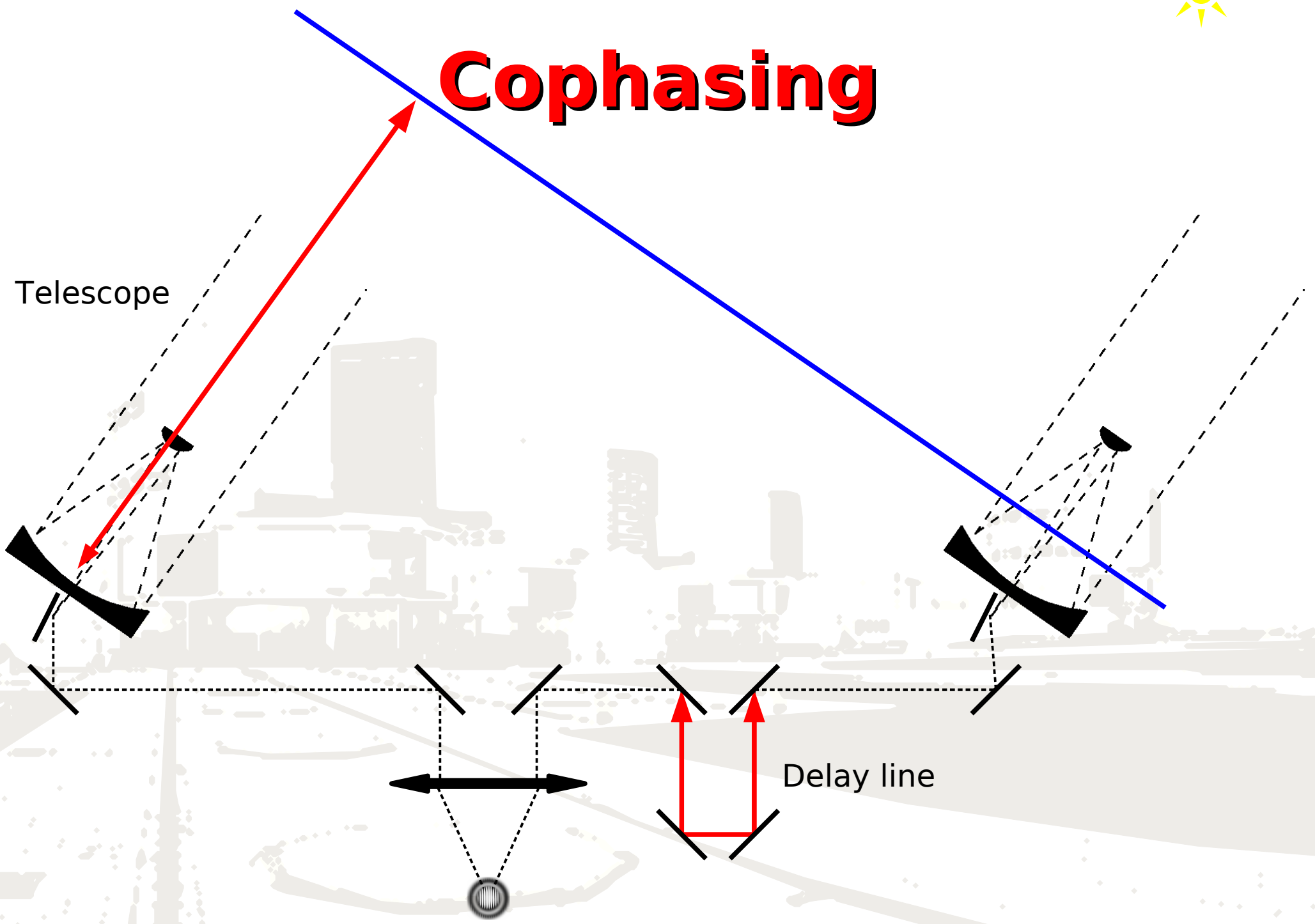
AMBER

- 3 telescopes (imaging capabilities)
- Simultaneous (J), H & K ($1-2.5\mu\text{m}$)
- Spectral resolutions
 $R=35, 1500$ & 12000





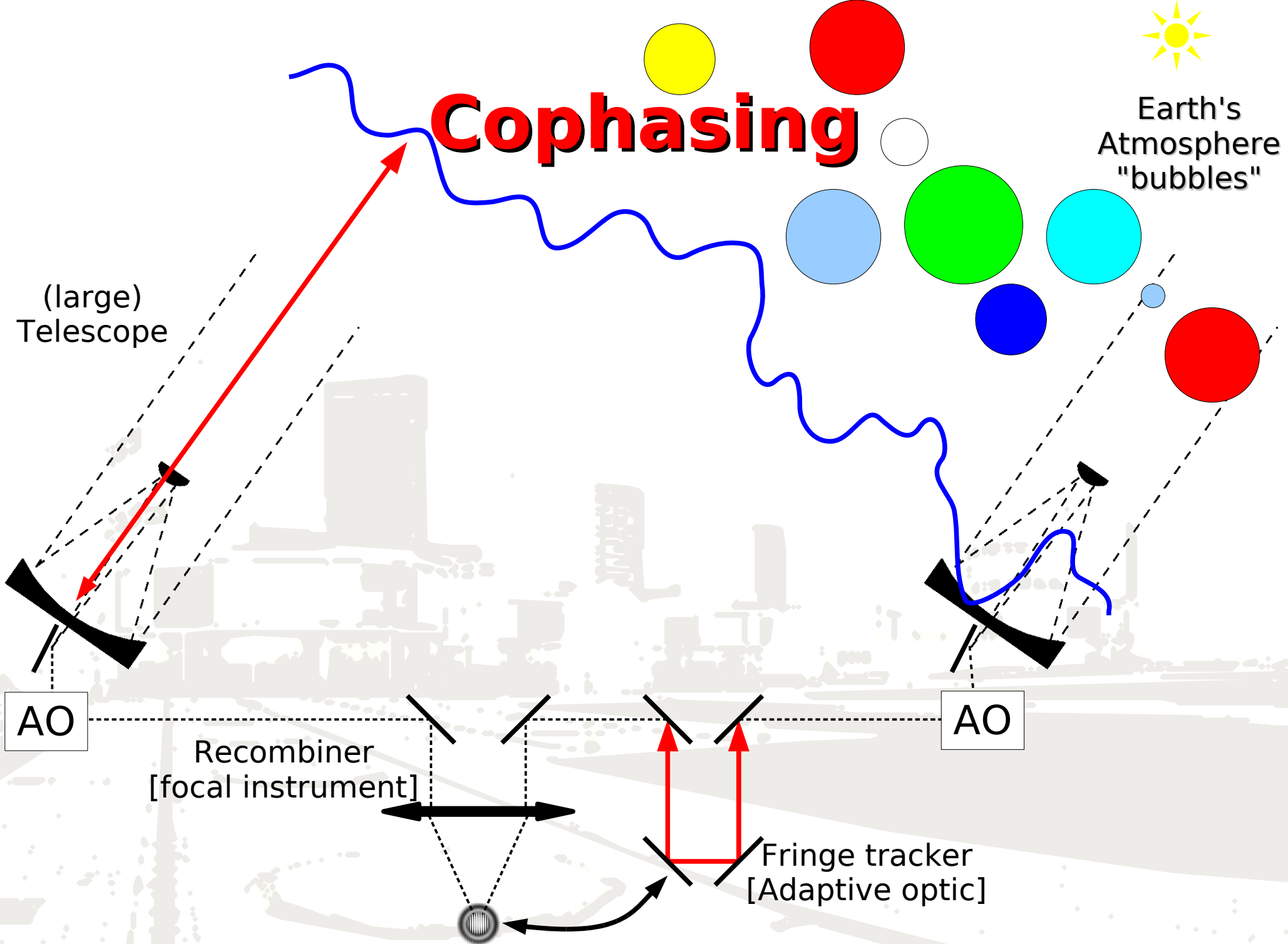
Cophasing



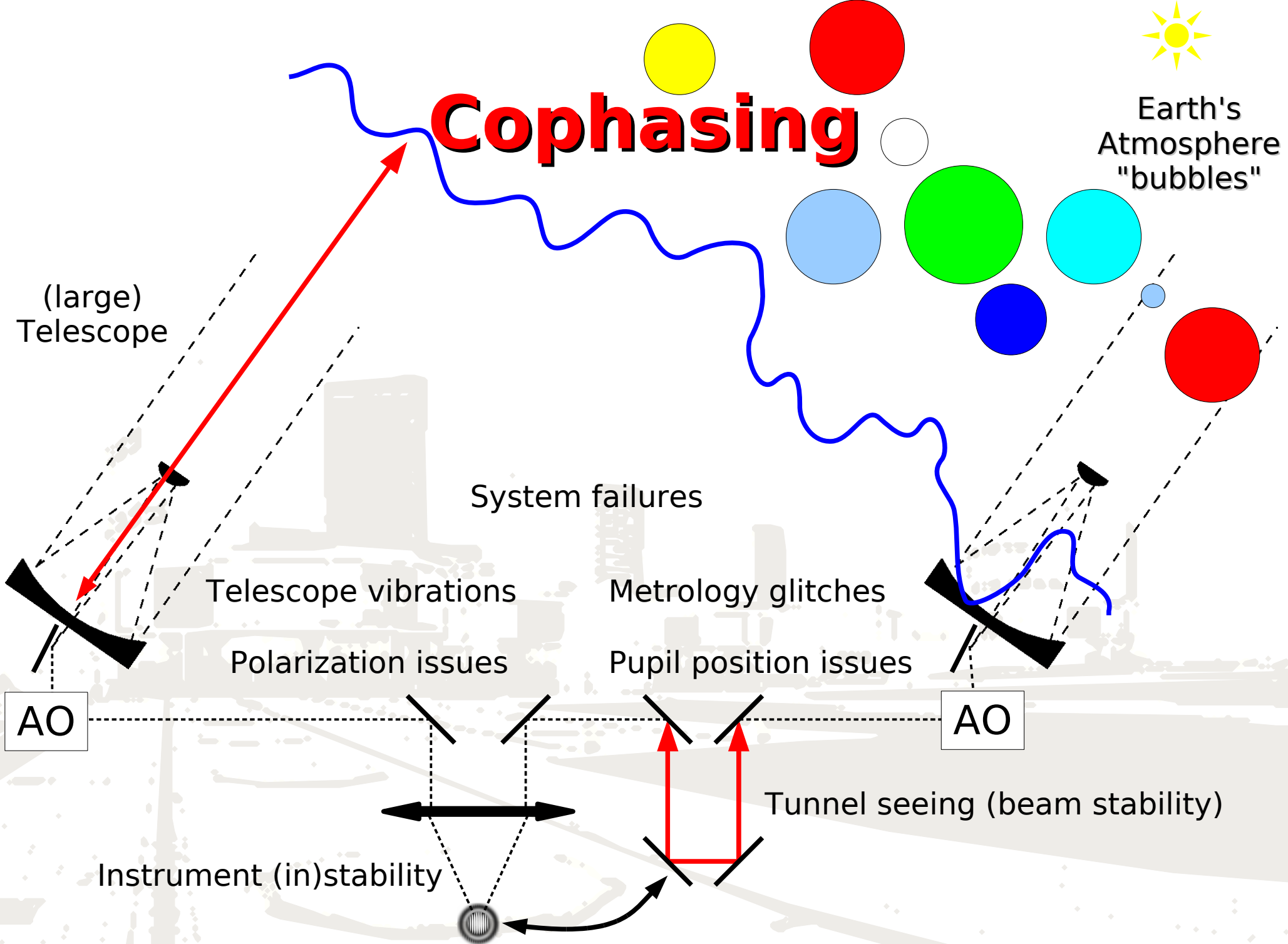
Telescope

Delay line

Cophasing



Cophasing



Earth's Atmosphere "bubbles"

(large) Telescope

System failures

Telescope vibrations

Metrology glitches

Polarization issues

Pupil position issues

AO

AO

Tunnel seeing (beam stability)

Instrument (in)stability

What visibility with interferometry ?

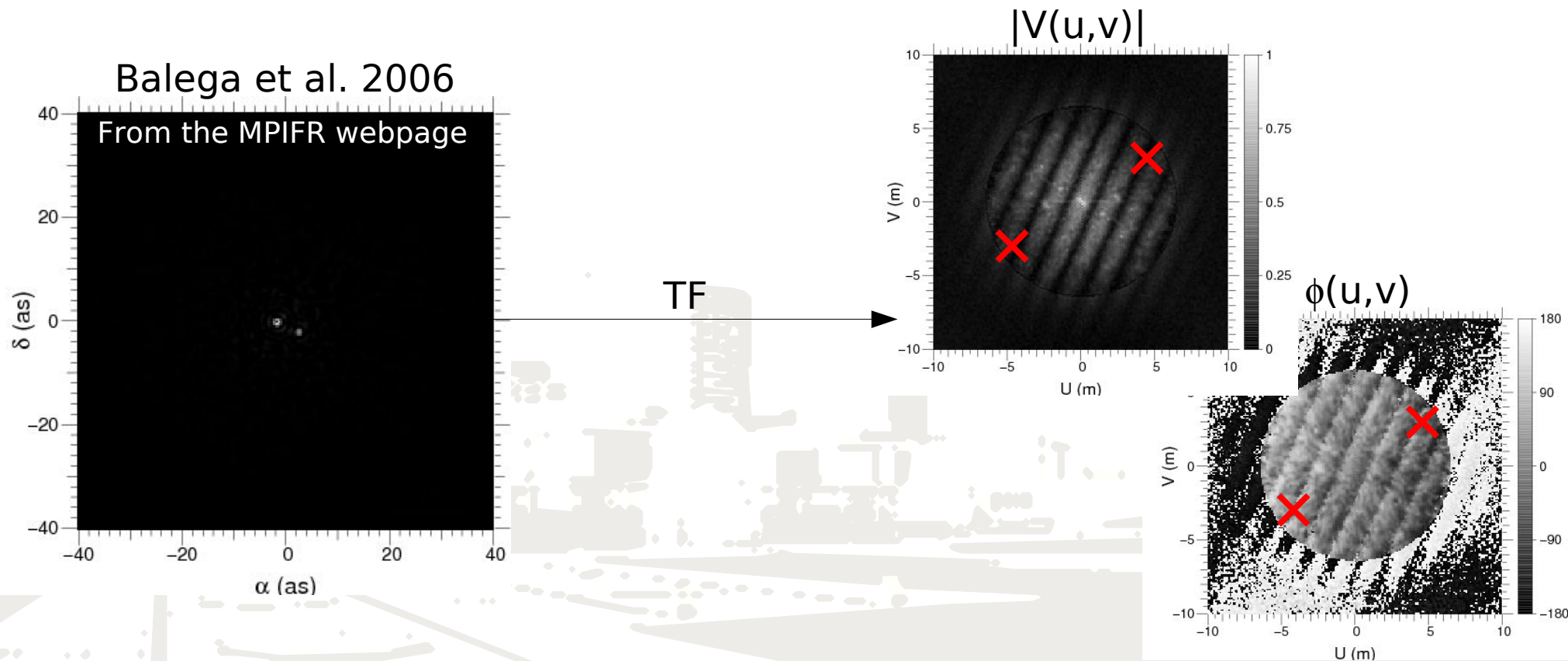


Image : $I(x,y) = O * \text{PSF} \rightarrow |V(u,v)|, \phi(u,v)$ & cut-off frequency at D/λ

What visibility with interferometry ?

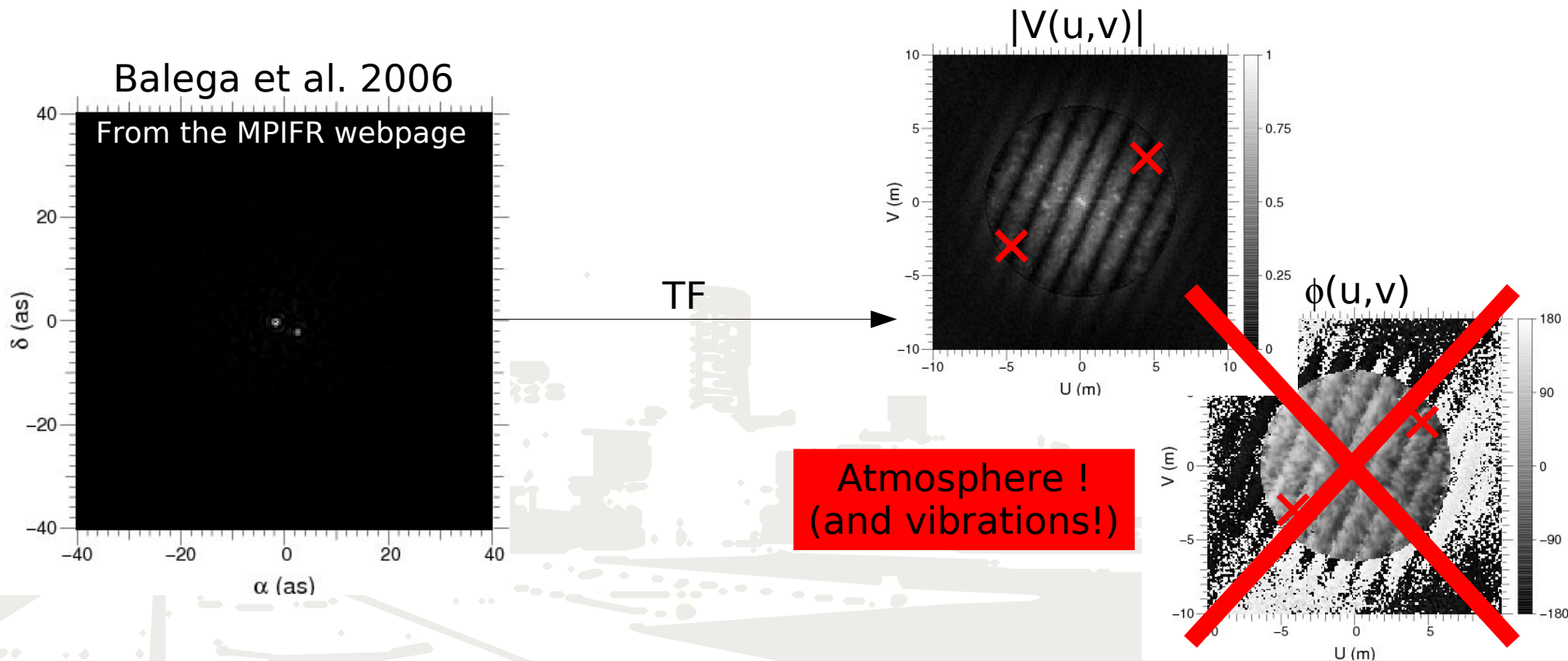


Image : $I(x,y) = O * \text{PSF} \rightarrow |V(u,v)|, \phi(u,v)$ & cut-off frequency at D/λ

What visibility with interferometry ?

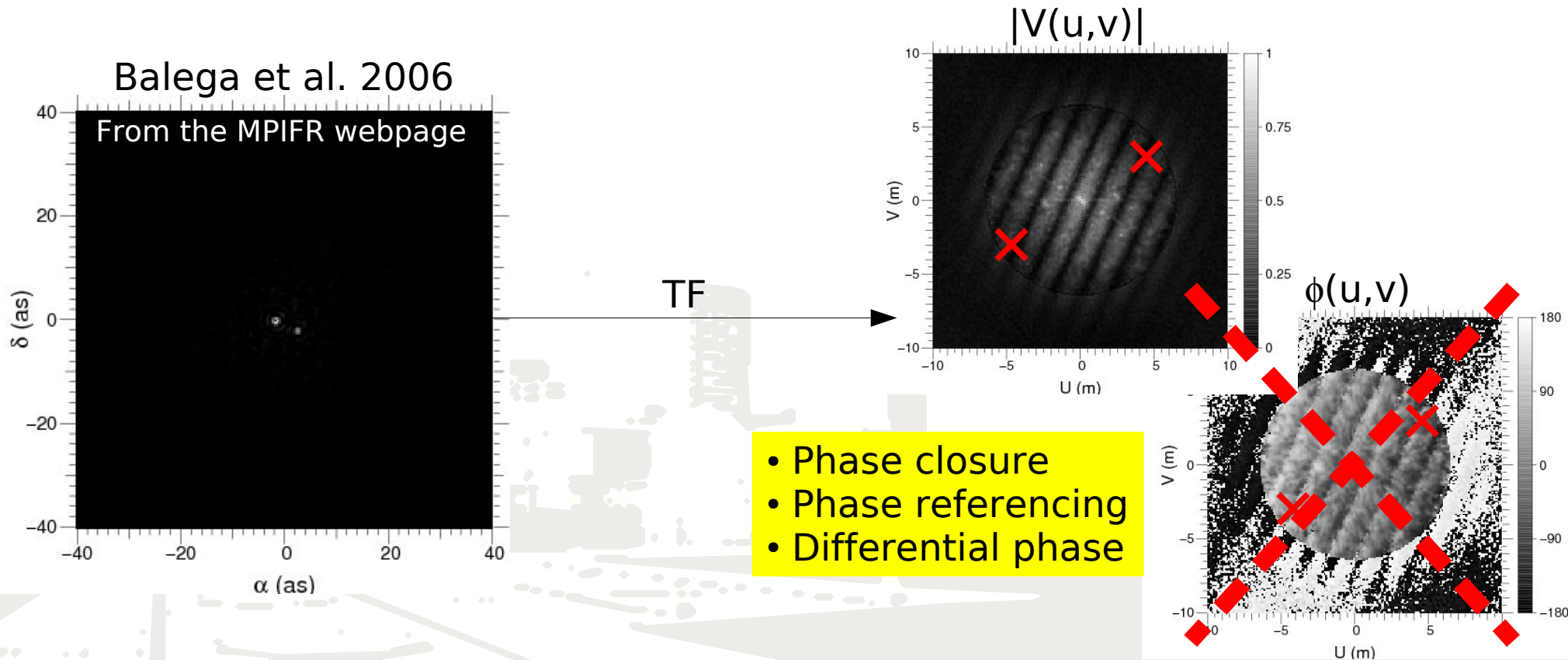
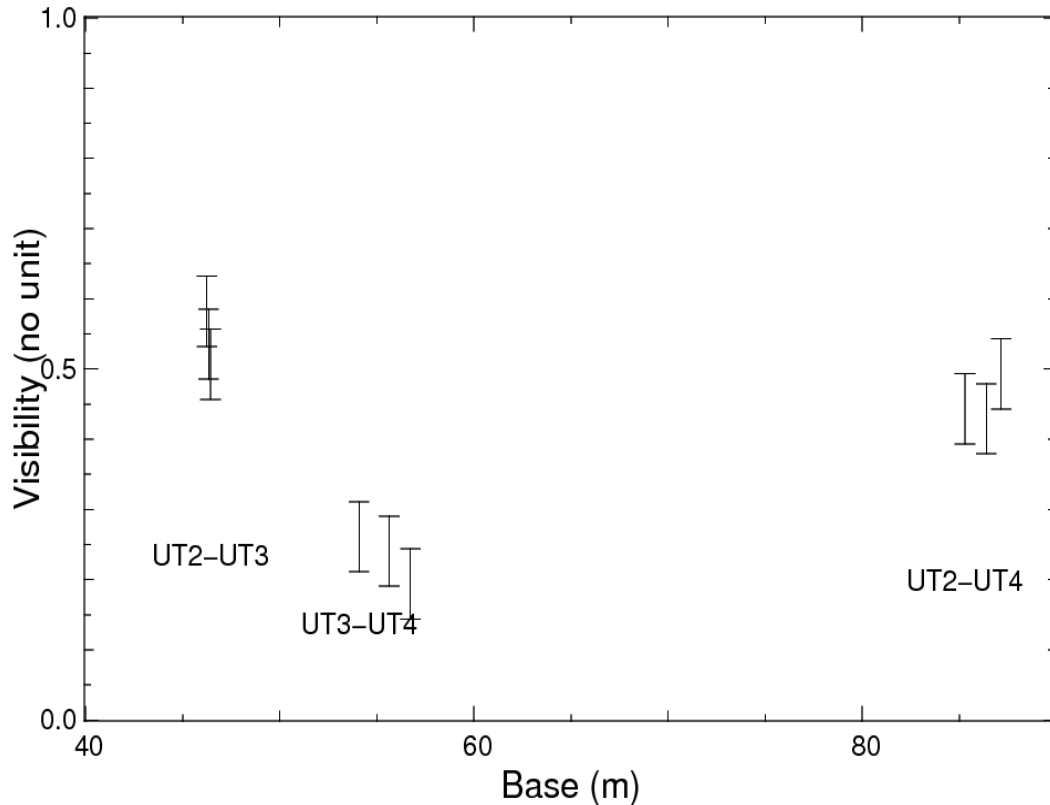


Image : $I(x,y) = O * \text{PSF} \rightarrow |V(u,v)|, \phi(u,v)$ & cut-off frequency at D/λ

This session

is about what you can do with that ...



Model fitting in the Fourier plane domain is “attractive”:

Domain where interferometric measurements are made
=> errors easier to take into account (ex: Gaussian noise)

When (U,V) plane sampling is poor (almost always the case)

Better than nothing when no imaging is possible (ex: variable source)

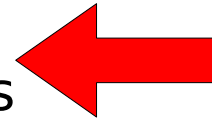
Realistic in the VLTI AMBER and MIDI contexts

Simple first step : parametric analysis using basic visibility functions.

Ad-hoc modeling

Allows you to get a first idea of what you have observed!

- Use Fourier transform properties
- Use basic intensity distribution functions



Important first step
towards modelling with
real physical models

Fourier transform properties:

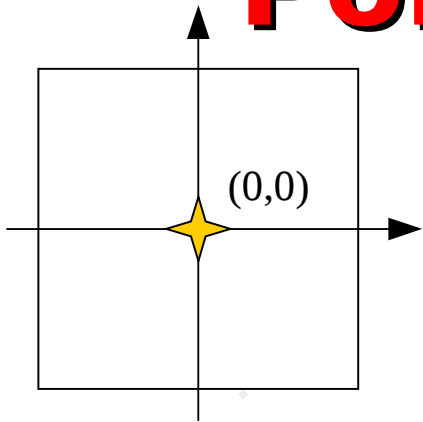
- **Addition** $\text{FT}\{f(x, y) + g(x, y)\} = F(u, v) + G(u, v)$
- **Convolution** $\text{FT}\{f(x, y) \times g(x, y)\} = F(u, v) \cdot G(u, v)$
- **Shift** $\text{FT}\{f(x - x_0, y - y_0)\} = F(u, v) \exp[2\pi i(ux_0 + vy_0)]$
- **Similarity** $\text{FT}\{f(ax, by)\} = \frac{1}{|ab|} F(u/a, v/a)$

Point source function

Use: Multiple stars

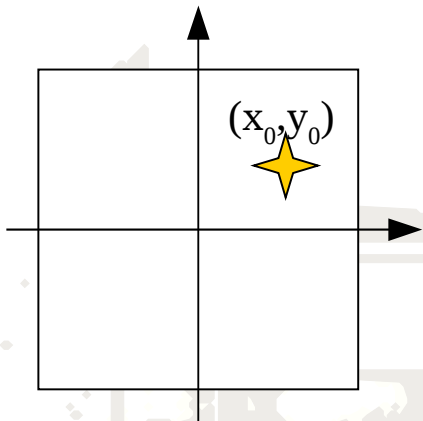
Centered source

$$I(x, y) = \delta(x, y) \longrightarrow V(u, v) = 1$$



Off-axis source

$$I(x, y) = \delta(x - x_0)\delta(y - y_0) \longrightarrow V(u, v) = \exp[-2i\pi(x_0u + y_0v)]$$

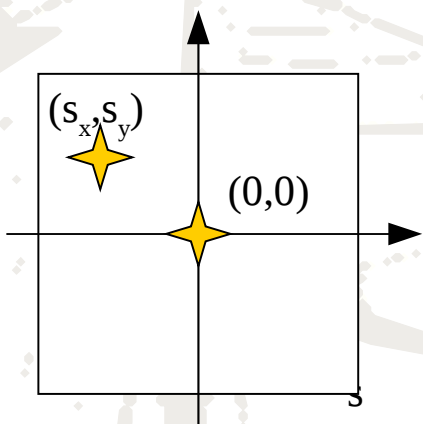


Binary system

$$A\delta(x, y) + B\delta(x - sx, y - sy) \text{ with } s = \sqrt{sx^2 + sy^2}$$

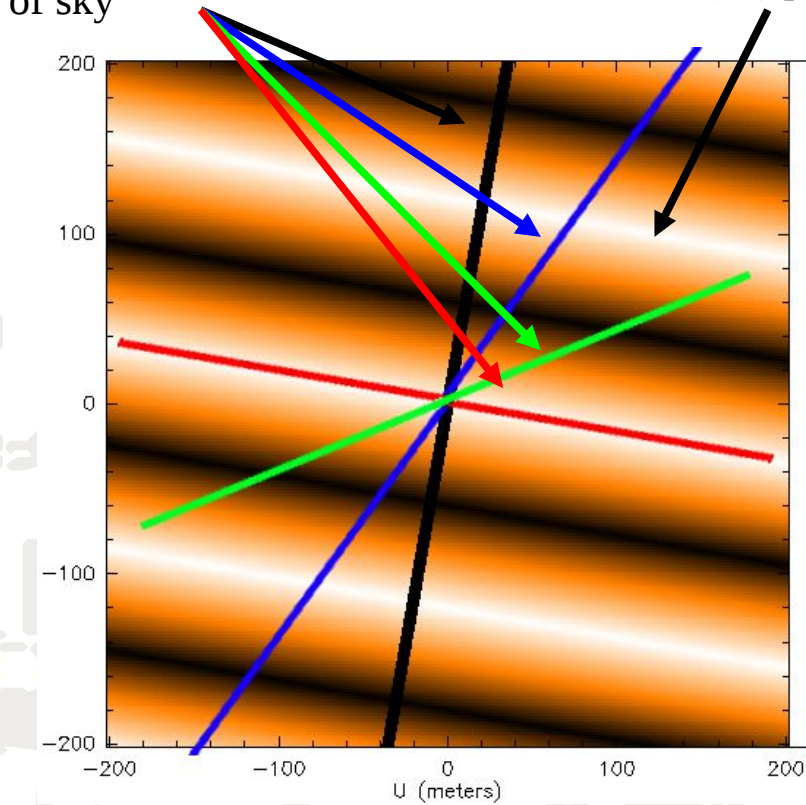
$$\longrightarrow V(u, v) = \sqrt{\frac{1+r_{ab}^2+2r_{ab} \cos 2\pi \vec{L}_b \vec{s} / \lambda}{1+r_{ab}^2}}$$

with $r_{ab} = A/B$
with $\vec{L}_b =$ Baseline vector



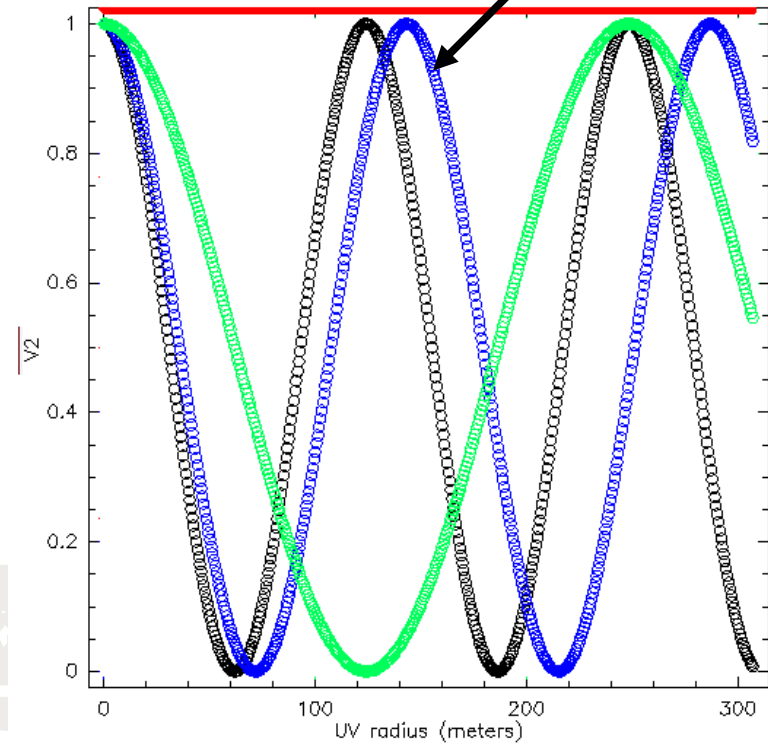
Binary star

Projection of baseline in the plane of sky

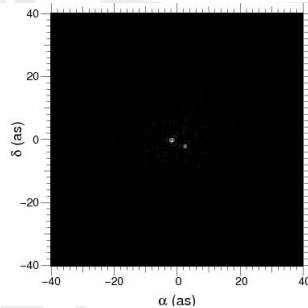


The visibility amplitude squared in (uv) plane

Squared visibility curves for three baselines as a function of baseline length



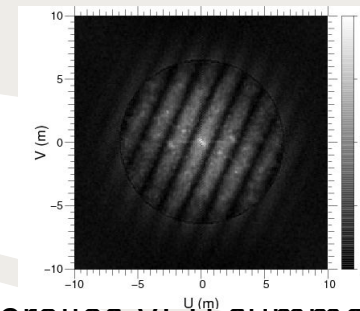
image



Remember:

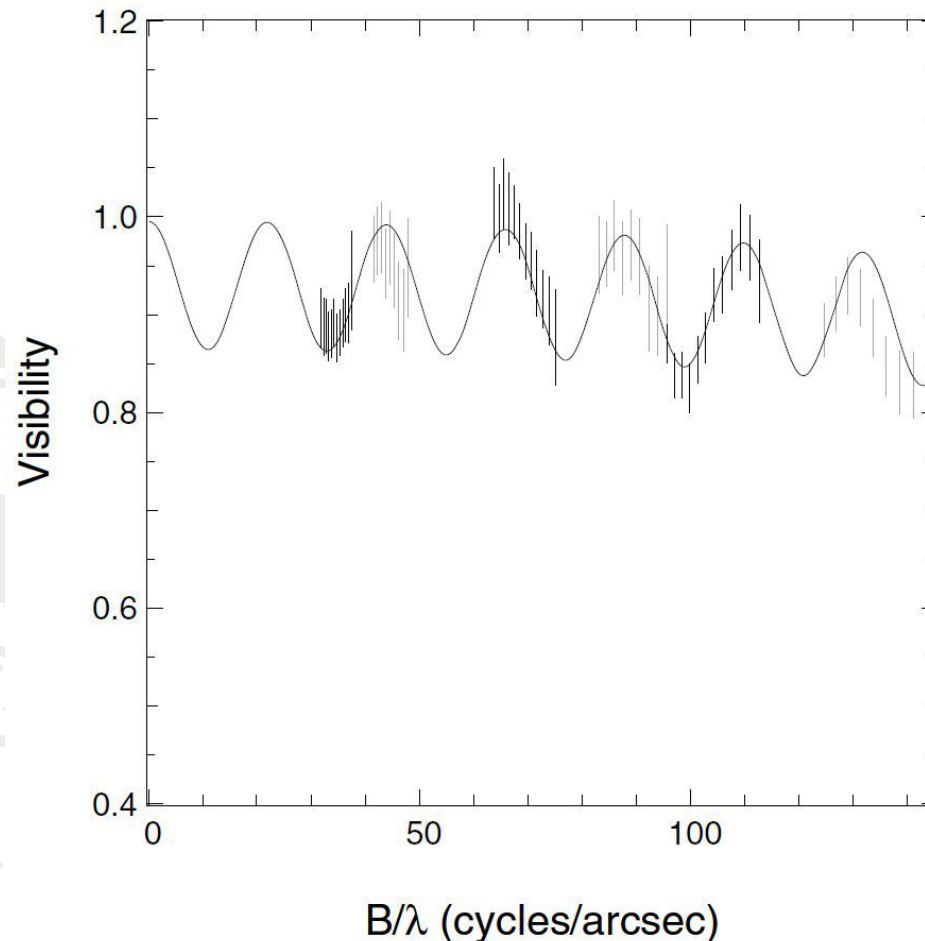
TF

Visibility



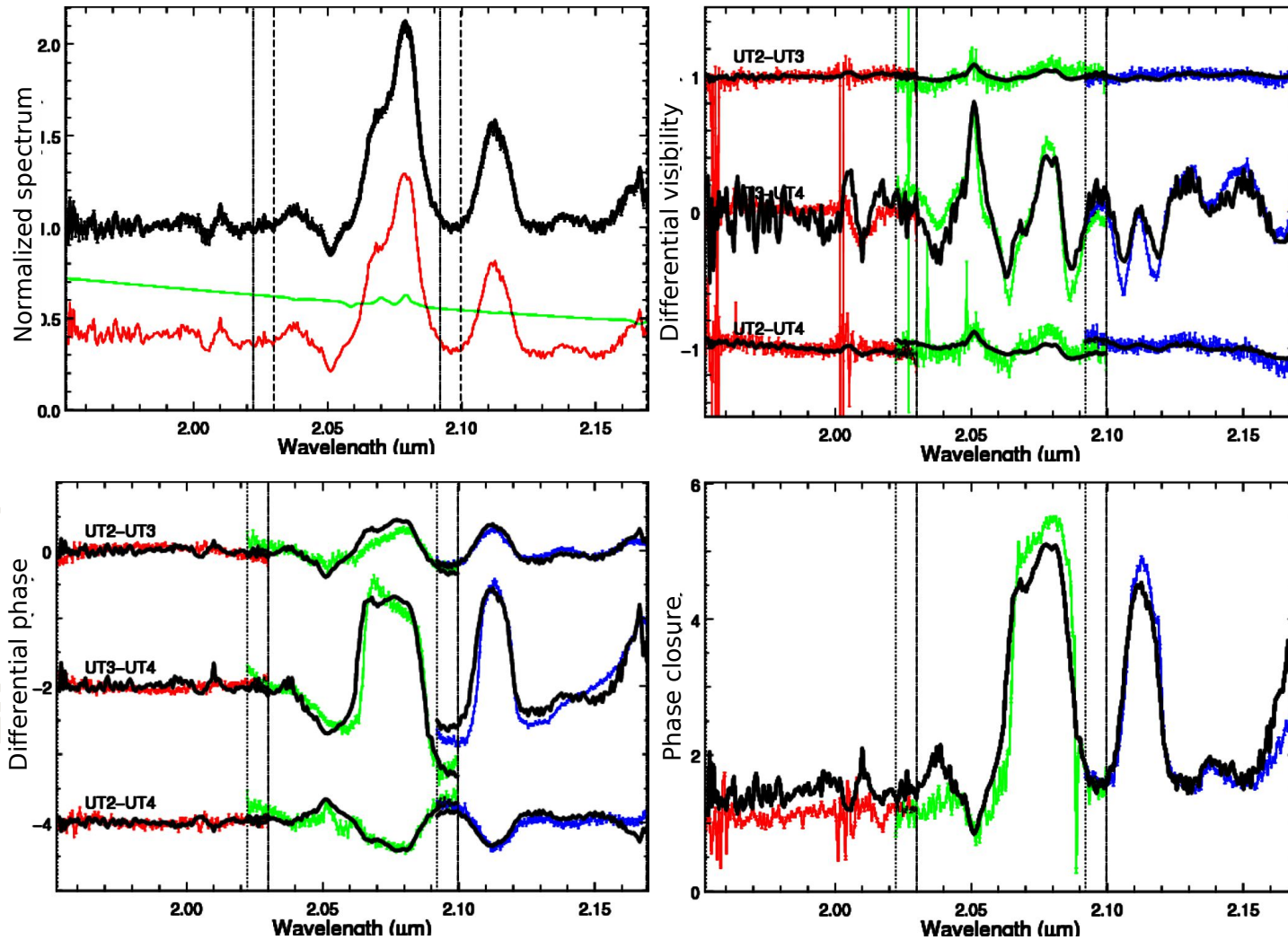
Binary star (example 1)

Binary star visibility curve as a function of spatial frequency



δ Cen, Meilland et al. 2008

Binary star (exemple 2)

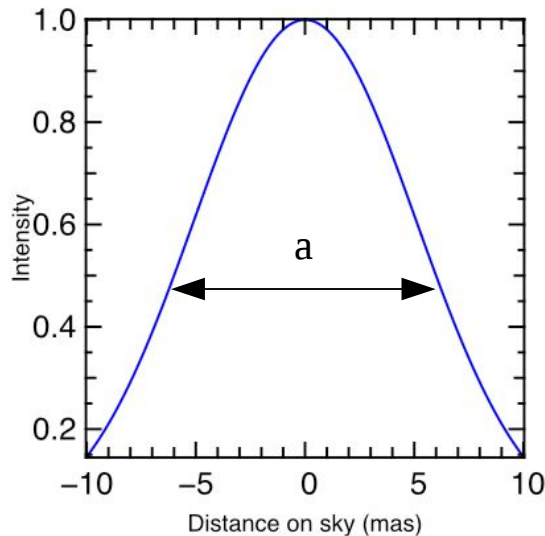


**Spectrally
varying
flux ratio
makes it
working !**

γ^2 Vel, Millour et al. 2007

Gaussian brightness distribution.

Use: Estimate for angular sizes of envelopes, disks, etc.



$$I(r) = \frac{I_0}{\sqrt{\pi/4 \ln 2} a} \exp(-4 \ln 2 r^2 / a^2)$$

Where a = FWHM intensity, I_0 = Peak intensity
and

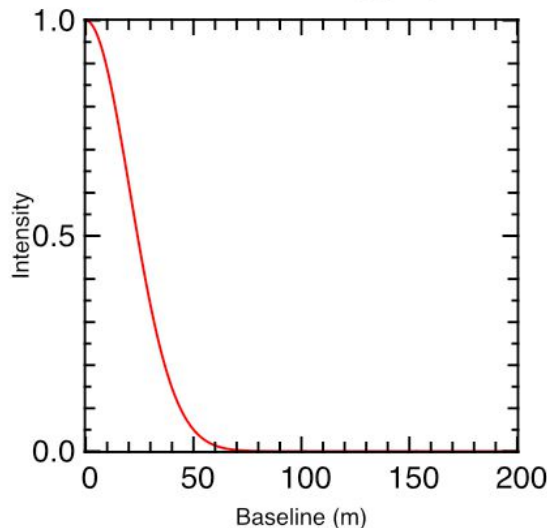
$$r = \sqrt{x^2 + y^2}$$



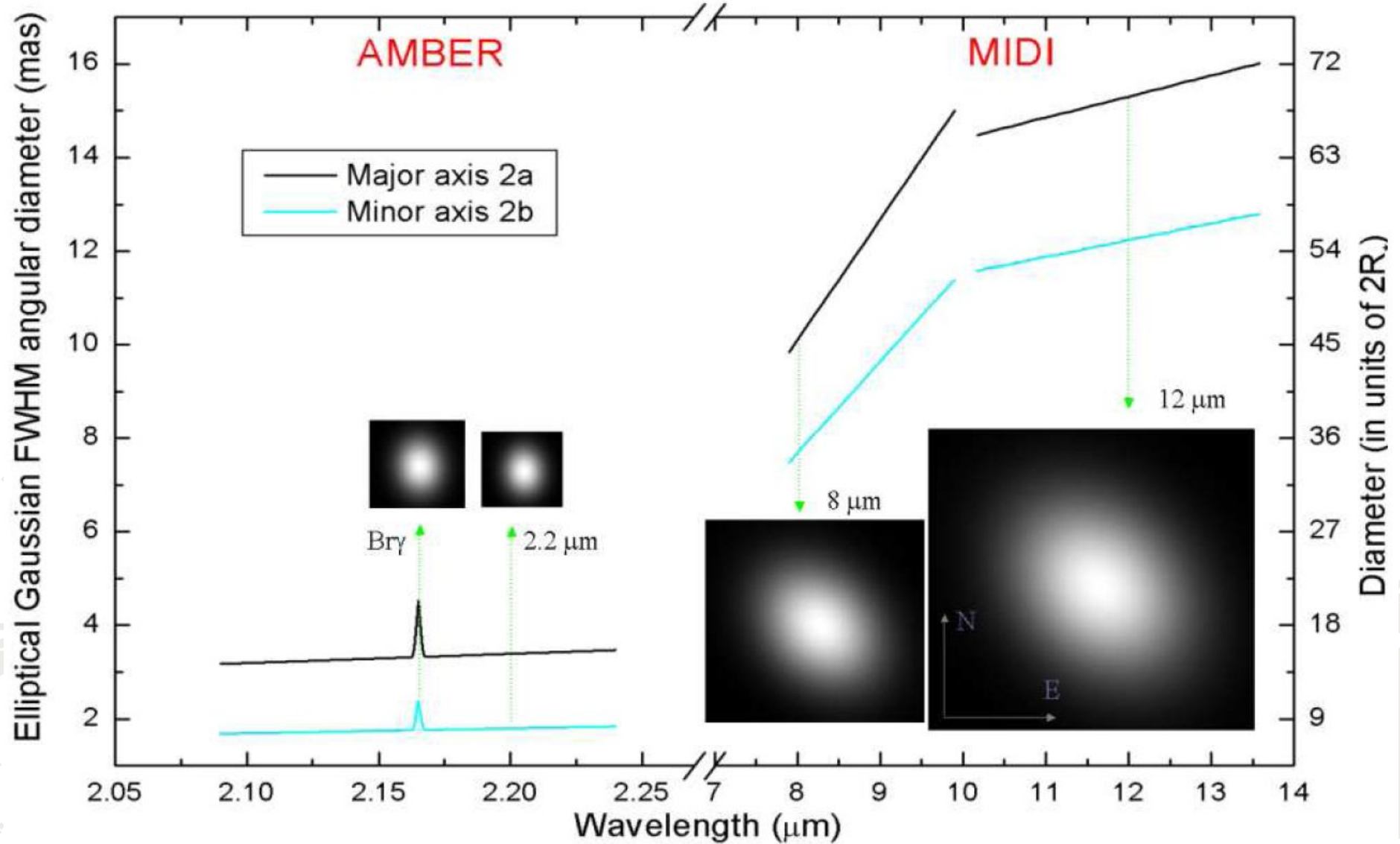
$$V(\rho) = \exp[-(\pi a \rho)^2 / (4 \ln 2)]$$

Where

$$\rho = \sqrt{u^2 + v^2}$$



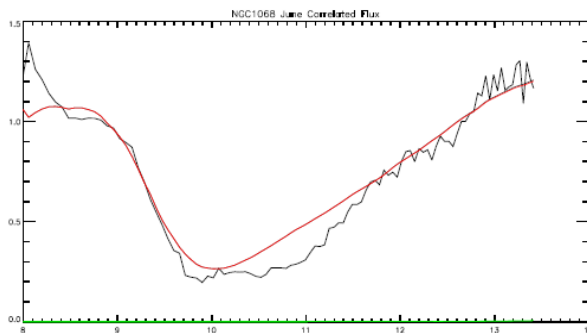
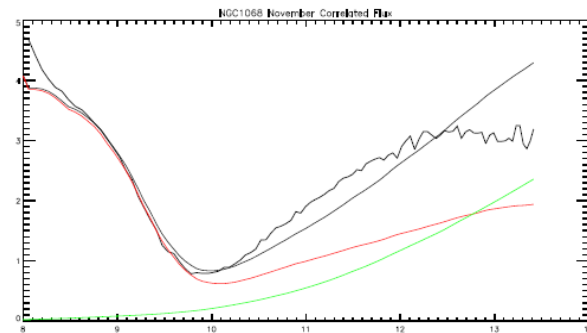
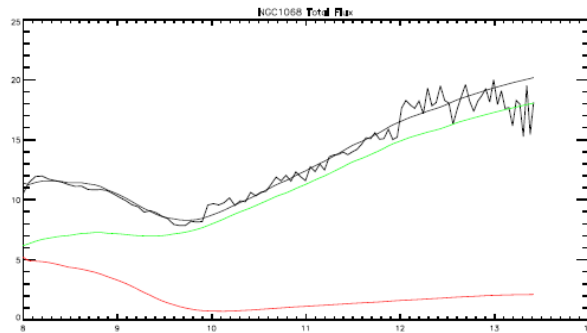
Gaussian (example 1)



Dominiciano da Souza et al A&A 2007

Gaussian (example 2)

- MIDI observations of NGC 1068
- 1st-order interpretation with a series of Gaussian disks

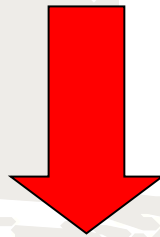


Rottgering et al 2004

Uniform disk

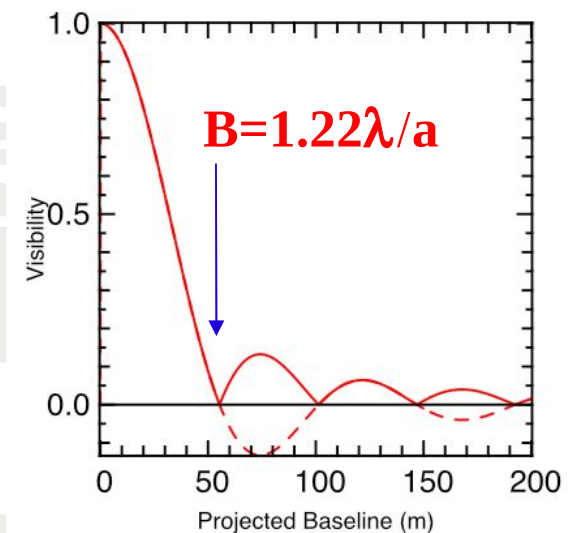
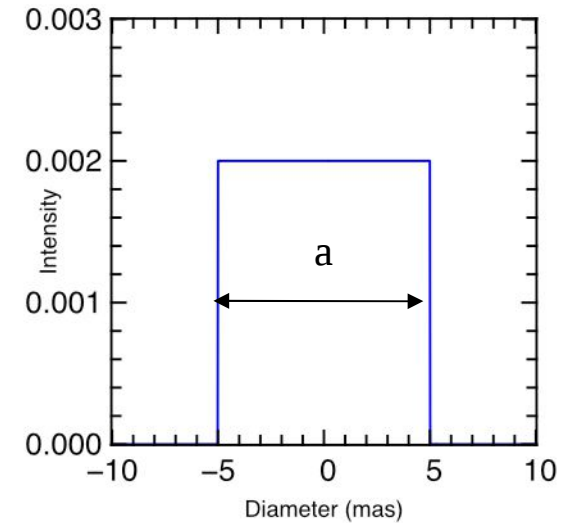
Use: approximation for brightness distribution of photospheric disk.

$$I(r) = 4/(\pi a^2), \text{ if } r = \sqrt{x^2 + y^2} \leq a/2$$
$$I(r) = 0 \text{ otherwise}$$

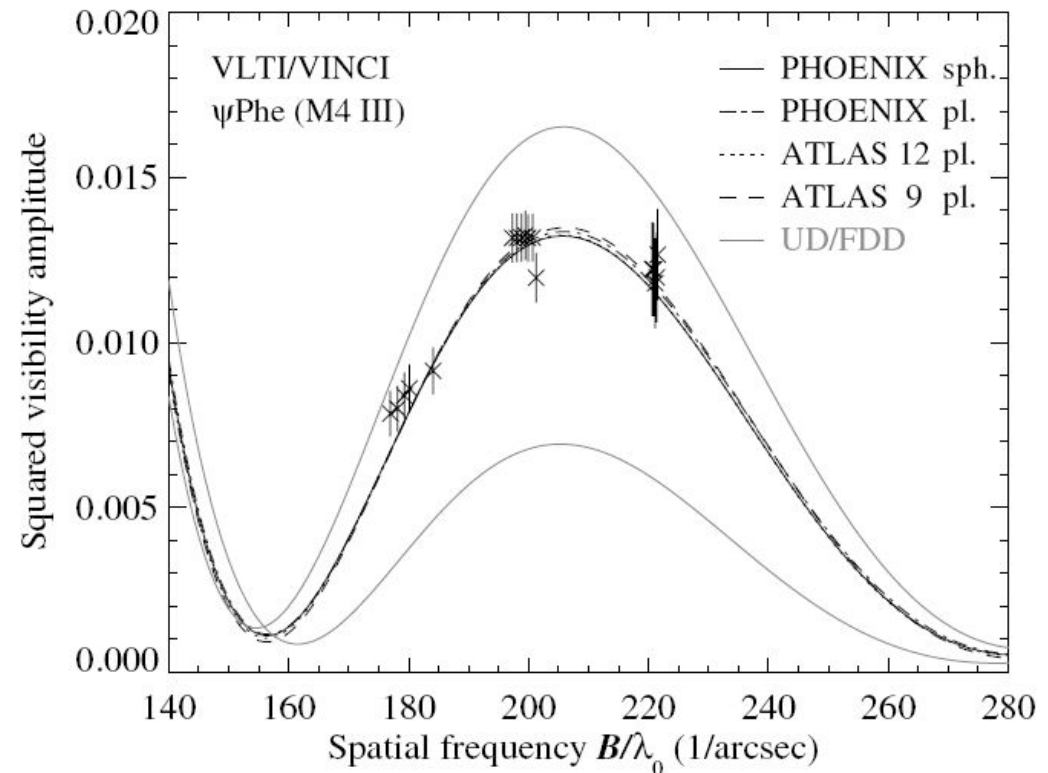
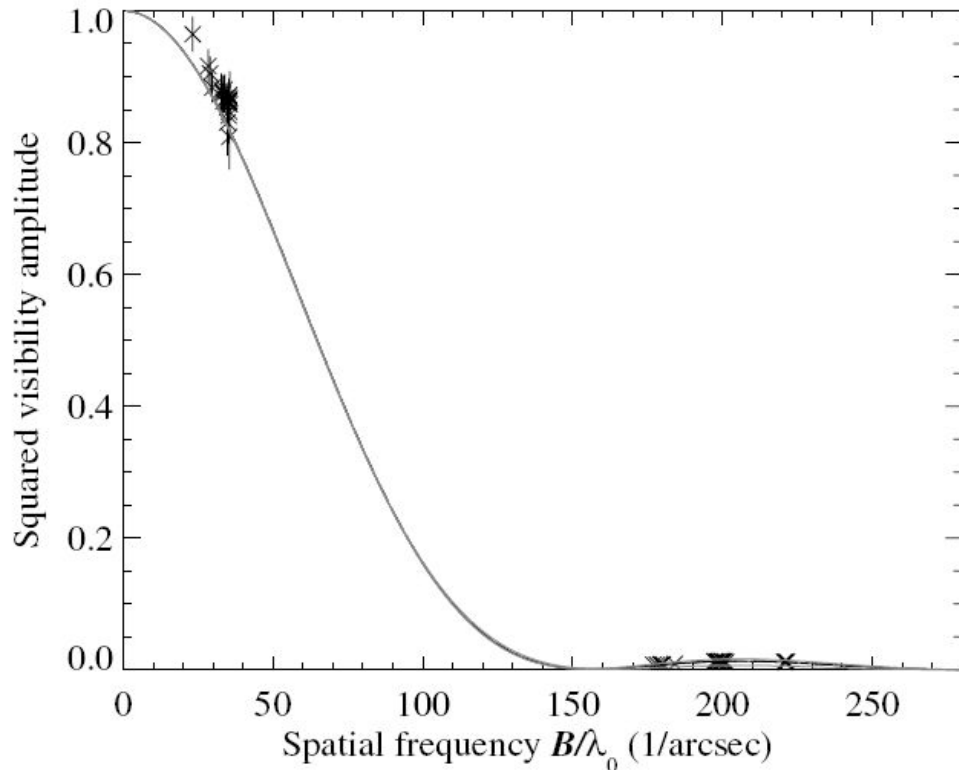


$$F(\rho) = \frac{J_1(\pi a \rho)}{\pi a \rho} \text{ with } \rho = \sqrt{u^2 + v^2}$$

a = diameter
Sophistication of the model
 $I = f(r)$, limb darkening
Cf Hankel transformation
(afterwards)



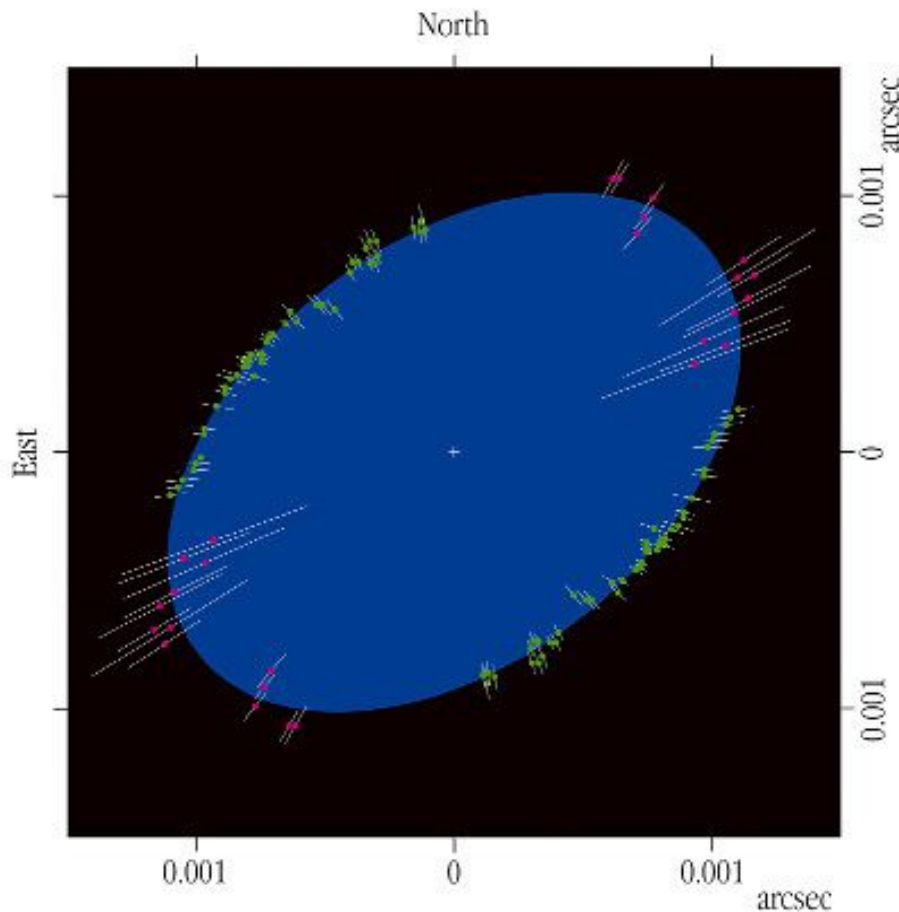
Uniform disk (example 1)



Wittkowski et al. 2003

- Comparison of ψ Phe VLT/VINCI observations with uniform disk model (gray line)
- Second lobe points are the most constraining

Uniform disk (example 2)



- Determination of uniform diameter of Archenar (VLTI/VINCI)
- Different positions angles shows evidence for flattening due to fast rotation

The Shape of Achernar
(VLTI + VINCI)

ESO PR Photo 15b/03 (11 June 2003)

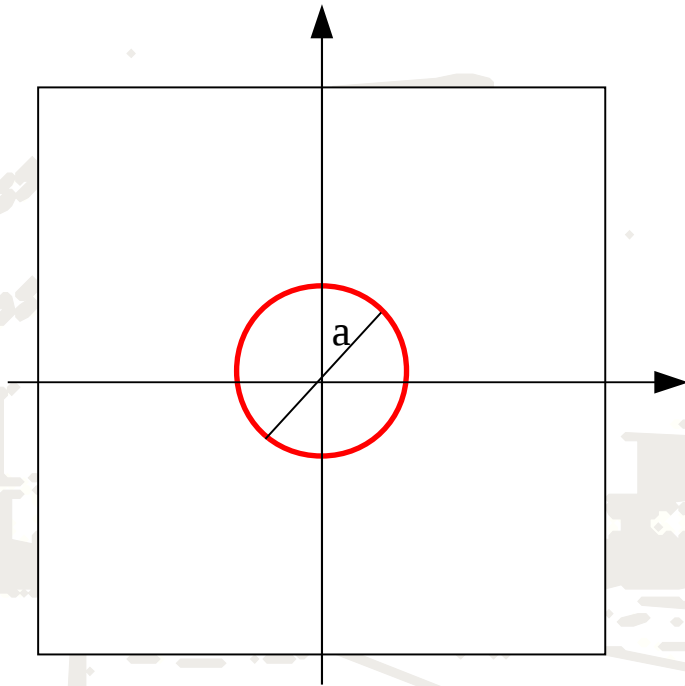
©European Southern Observatory



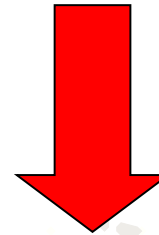
Dominiciano da Souza et al A&A 2003

Ring

Use: complex centro-symmetric structure



$$I(r) = 1/(\pi a)\delta(r - a/2)$$

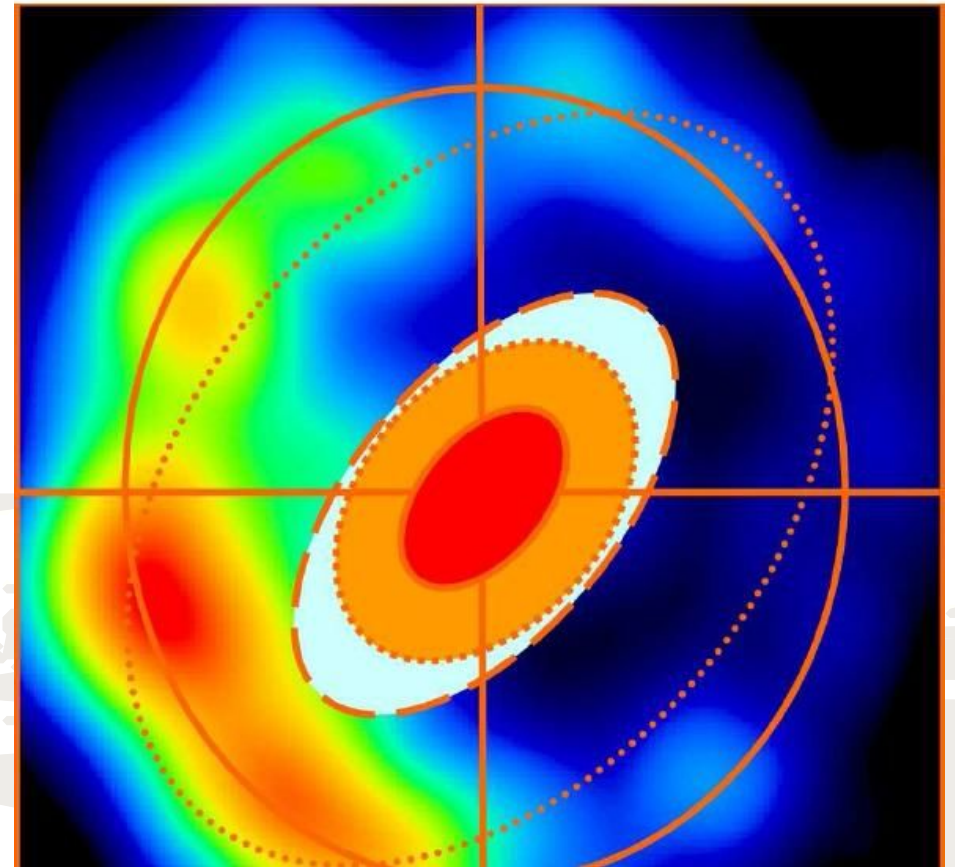


$$V(\rho) = J_0(\pi a \rho)$$

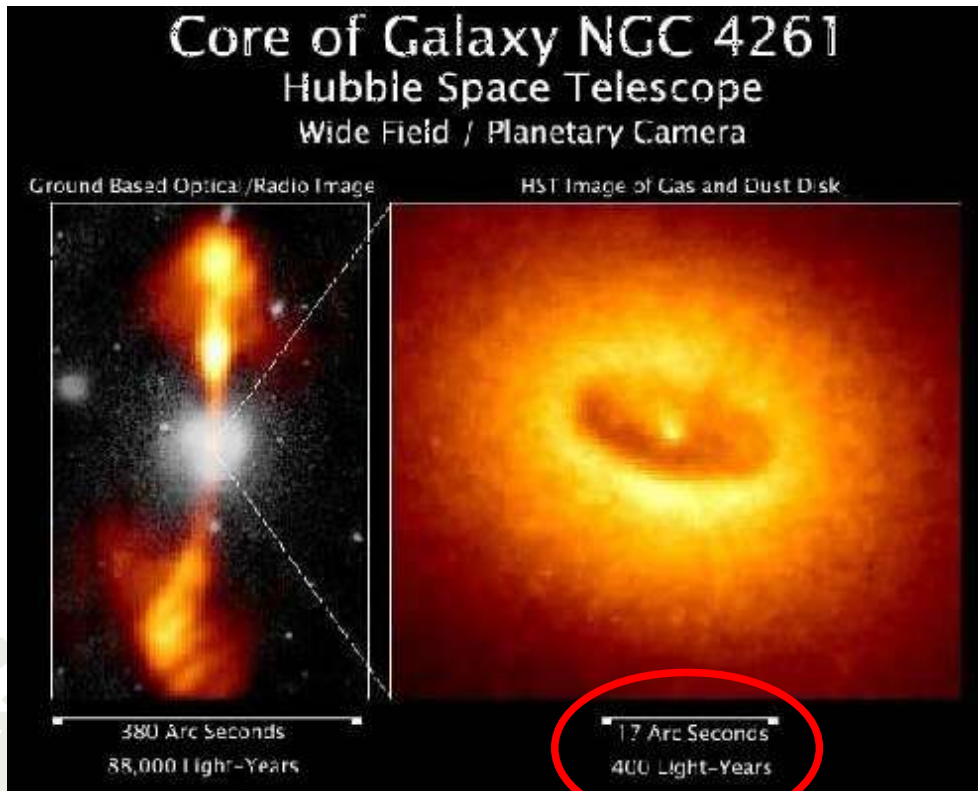
Ring (example 1)

- RS Oph aspherical Nova explosion

Chesneau et al., A&A 2007

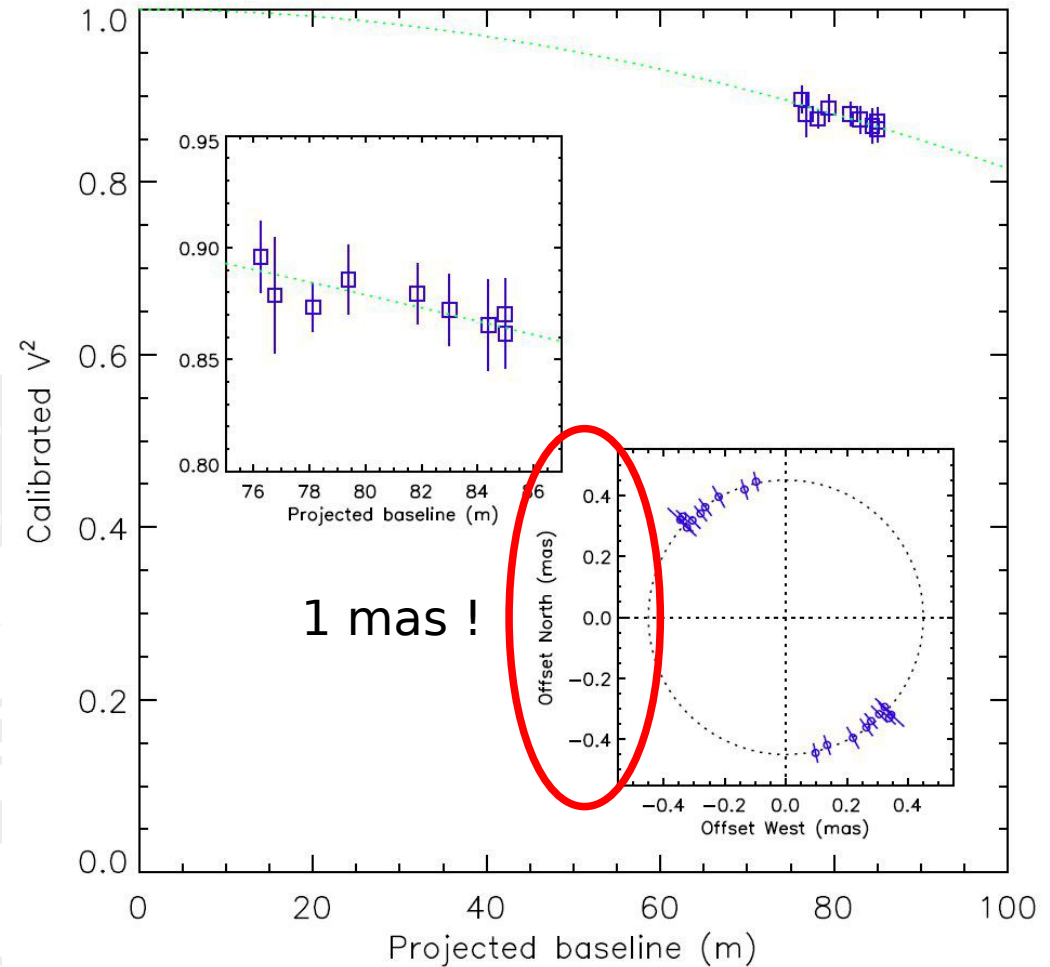


Ring (example 2)



17 arc-seconds

Core of galaxy NGC 4151
Keck-interferometer

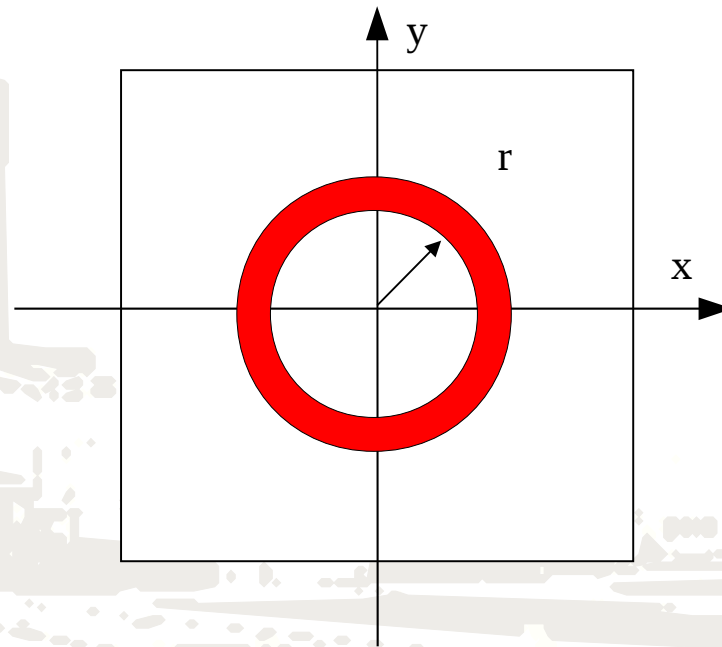


Kishimoto et al. 2009

Circularly symmetric object

e.g: an accretion disk made of a finite sum of annuli with different effective temperatures

Circularly symmetric component $I(r)$
centered at the origin of the (x,y) coordinate system.



The relationship between brightness distribution and visibility is a **Hankel function**

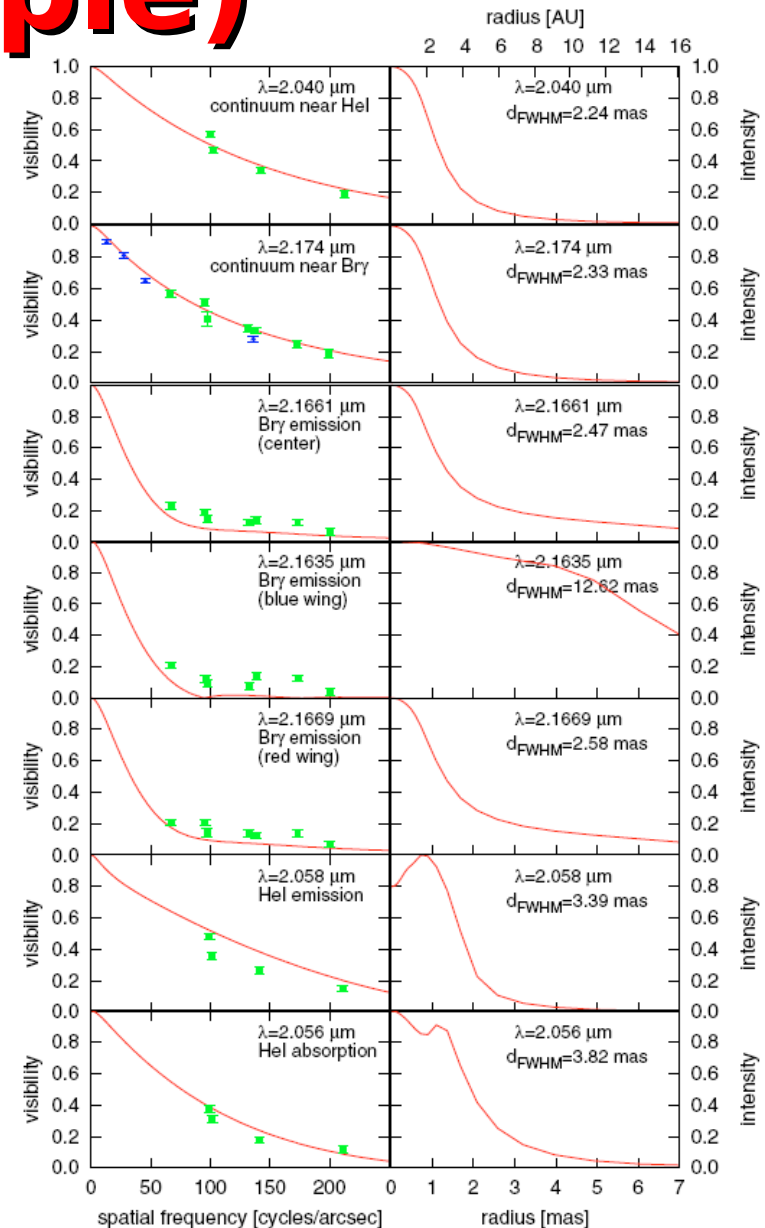
$$V(\rho) = 2\pi \int_0^{\infty} I(r) J_0(2\pi r \rho) r dr$$

$$\text{with } r = \sqrt{x^2 + y^2} \quad \text{and} \quad \rho = \sqrt{u^2 + v^2}$$

Circularly symmetric object (example)

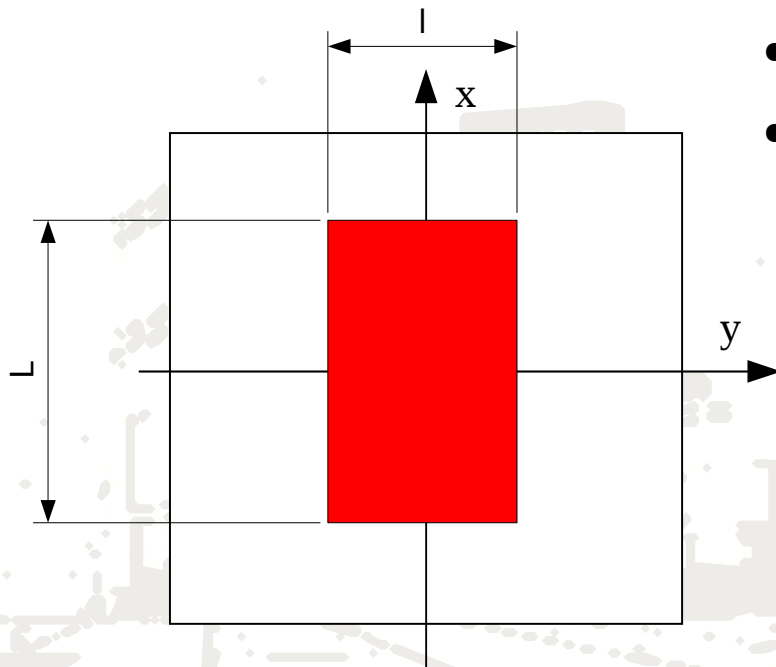
- Optically thick wind around η Car (Hillier models gives intensity profiles)

Weigelt et al., A&A 2007

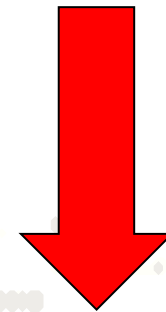


Pixel

Basic brick of an image !



- $I(x,y) = 1/lL$ if $|x| < l$ and $|y| < L$
- $I(x,y) = 0$ otherwise



$$V = \frac{\sin(\pi x l) \sin(\pi y L)}{\pi^2 xy / L}$$

The modelling process

- Model

- Instrument / atmosphere

- Data

- Comparison

Parameters: $\alpha, \beta, \gamma, \dots$ \longrightarrow $I(x, y, \alpha, \beta, \dots)$

$$V(u, v) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} I(x, y) \exp(-2\pi i(xu + yv)) dx dy$$

Sparse sampling $\{ \dots, V(u_i, v_i), \dots \} i = 1..n$	Observing model $\rho(t, \lambda), \phi_\delta(t, \lambda)$
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Observation $\{ \dots, V'(u_k, v_k), \dots \} k = 1..n$	Error $\epsilon(u, v)$
--	---------------------------

$$\chi^2 = f(V(u_i, v_i), V'(u_k, v_k), \epsilon'(u, v))$$

— find $\min(\chi^2)$

Conclusion(s)

- ✓ Visibility study without imaging can be efficient.
- ✓ The (u,v) coverage strategy is different from imaging. Limited allocated time means (very) limited (u,v) points.
- ✓ Use basic models in order to prepare your observation and determine what is the more constraining configuration.
- ✓ Visibility space is the natural place to understand the errors of the final result.
- ✓ Always start by describing your observations in terms of basic functions. It brings qualitative and quantitative information useful for further more detailed computations.

How to launch ASPRO (local installation)



"FULL ASPRO INTERFACE"

Here you are !

