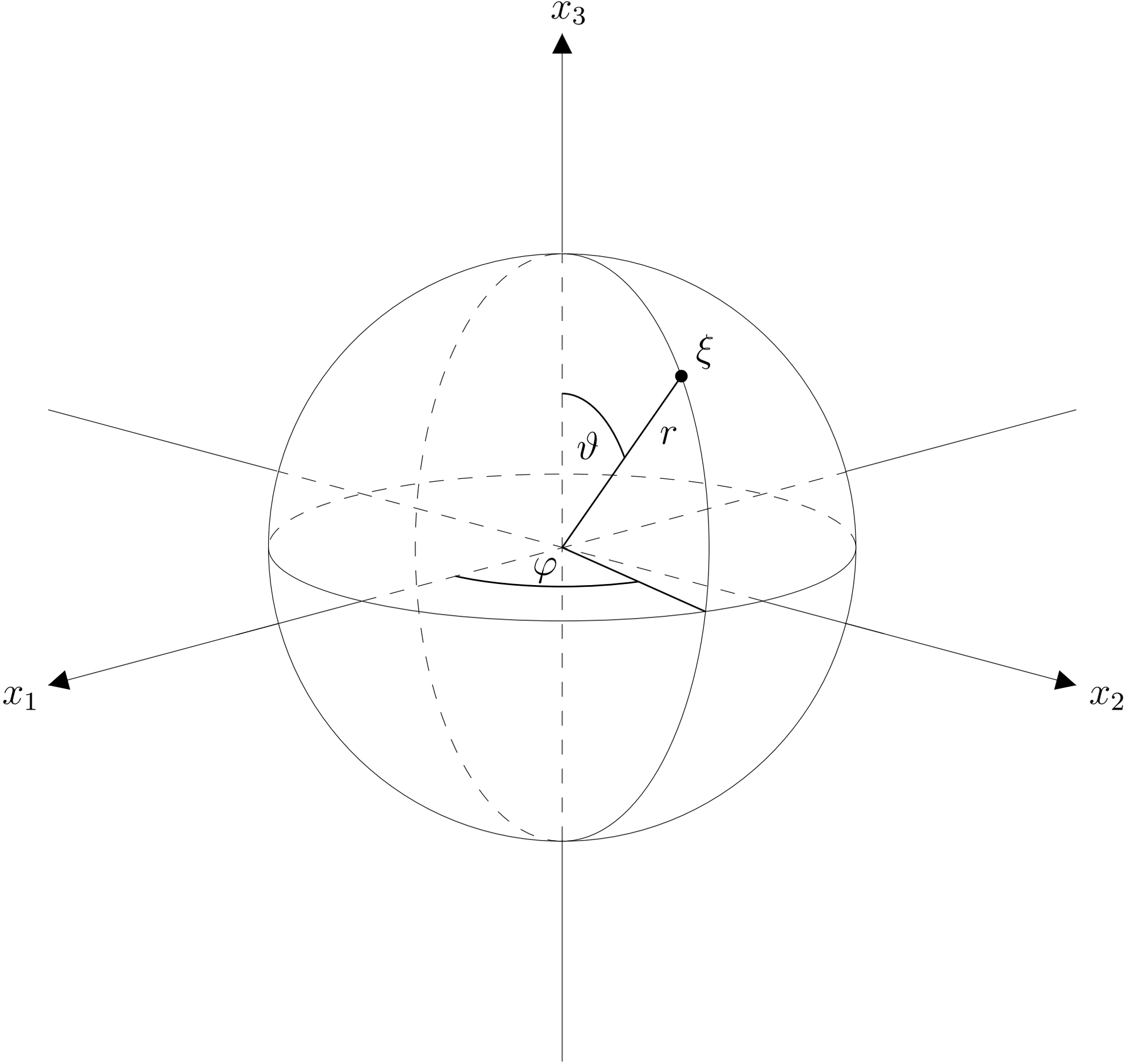
x_3
ξ
r
ϑ
φ
x_1
x_2