

Observability (and (u,v) coverage)

Euro Summer School
**Active Galactic Nuclei at the highest angular resolution:
theory and observations**
August 27 - September 7

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based on the presentation of D. Segransan
at the Goutelas Summer school (2006)

Observability

- ***Single dish telescopes:***

Constraints are HA and Fz

=> one needs LST, RA and DEC

Observing **efficiency is high** (large (u,v) coverage, low overheads)

- ***Interferometers:***

Constraints are HA, Fz **and** (u,v)

=> one needs LST, RA, DEC **and Bvect**

+ Hardware constraints : DL range, Dome vignetting

Observing **efficiency is low** (poor (u,v) coverage, high overheads)

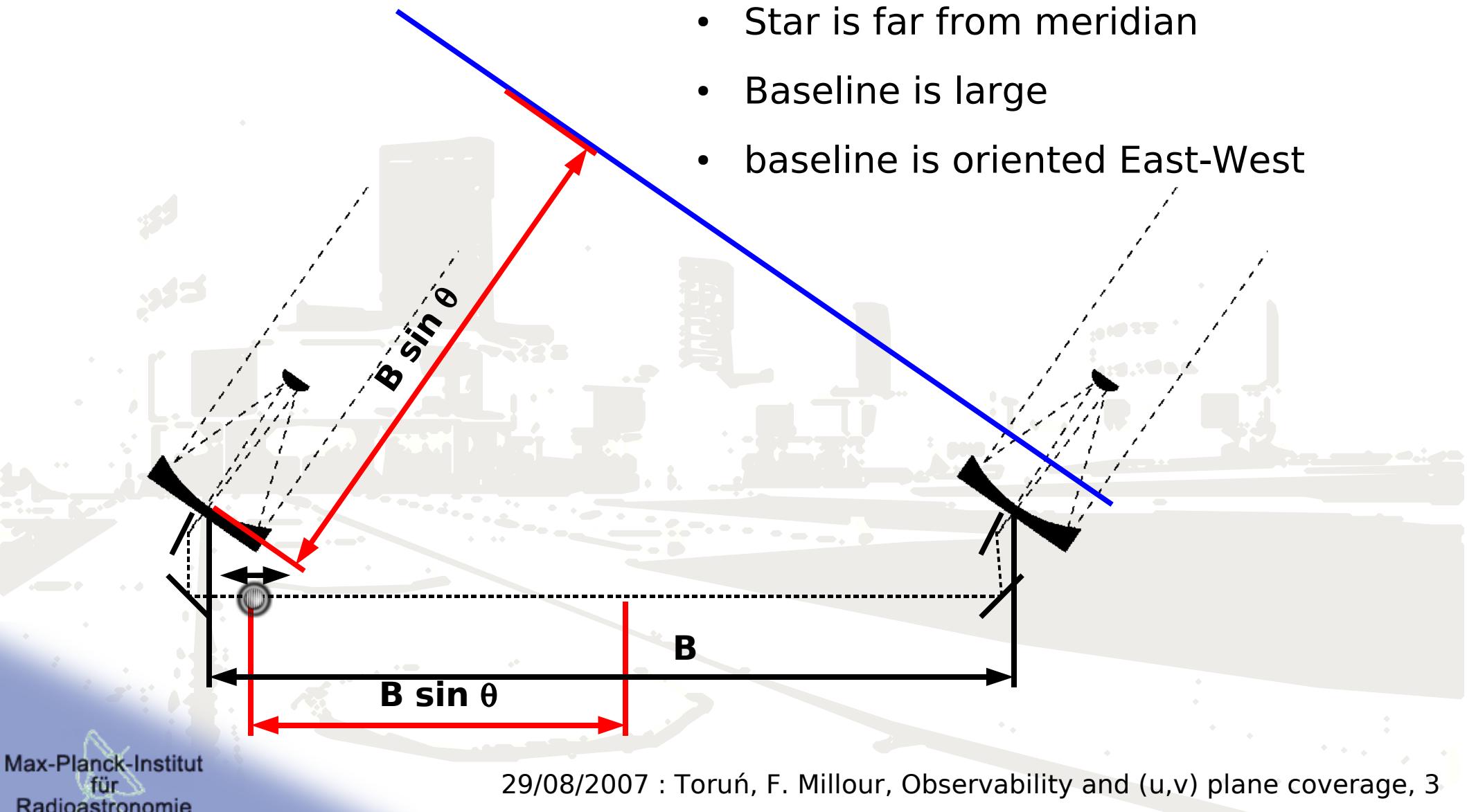
=> A good Observation Preparation Software is required



OPD

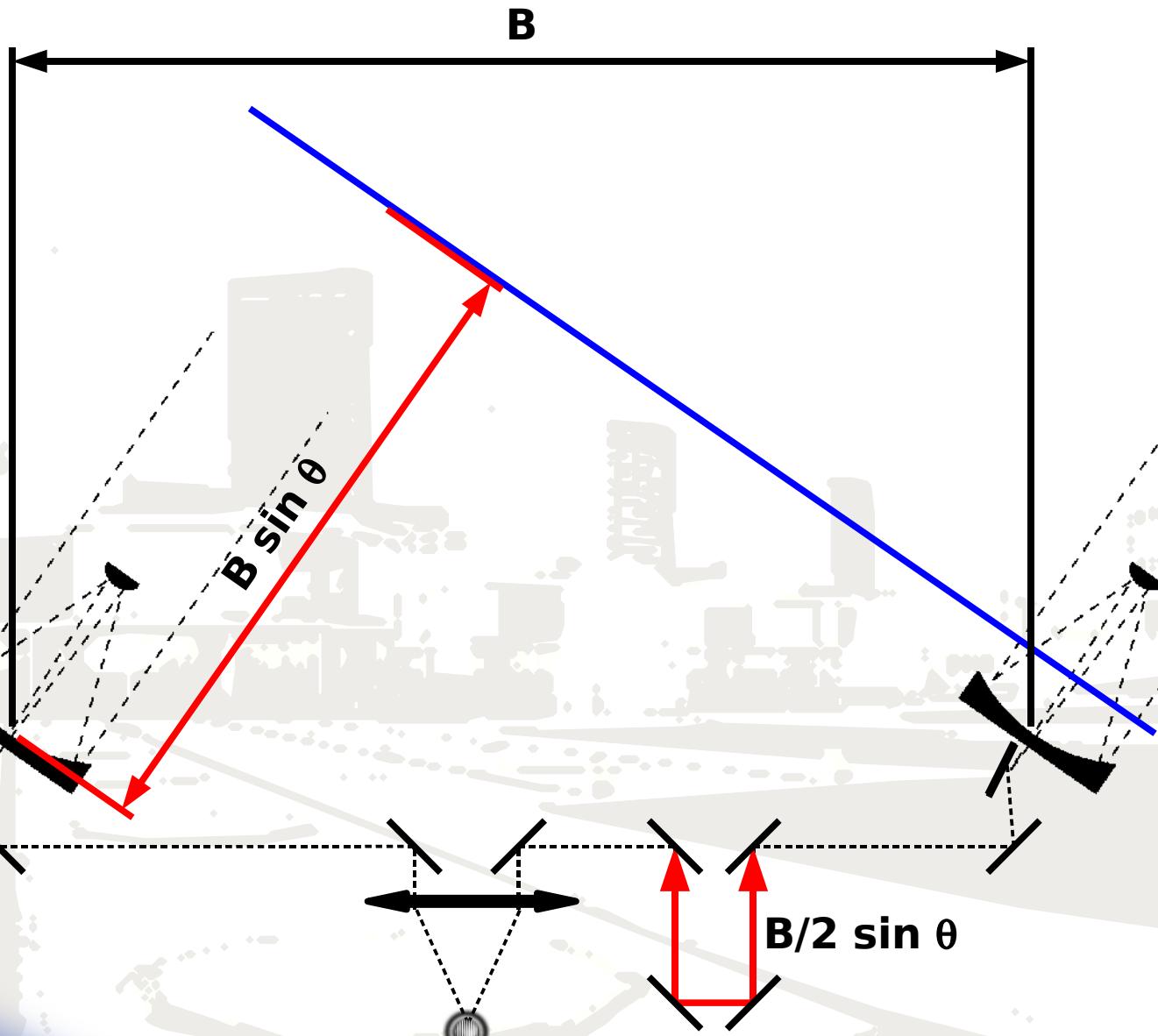
$B \sin \theta$ can be very large if:

- Star is far from meridian
- Baseline is large
- baseline is oriented East-West





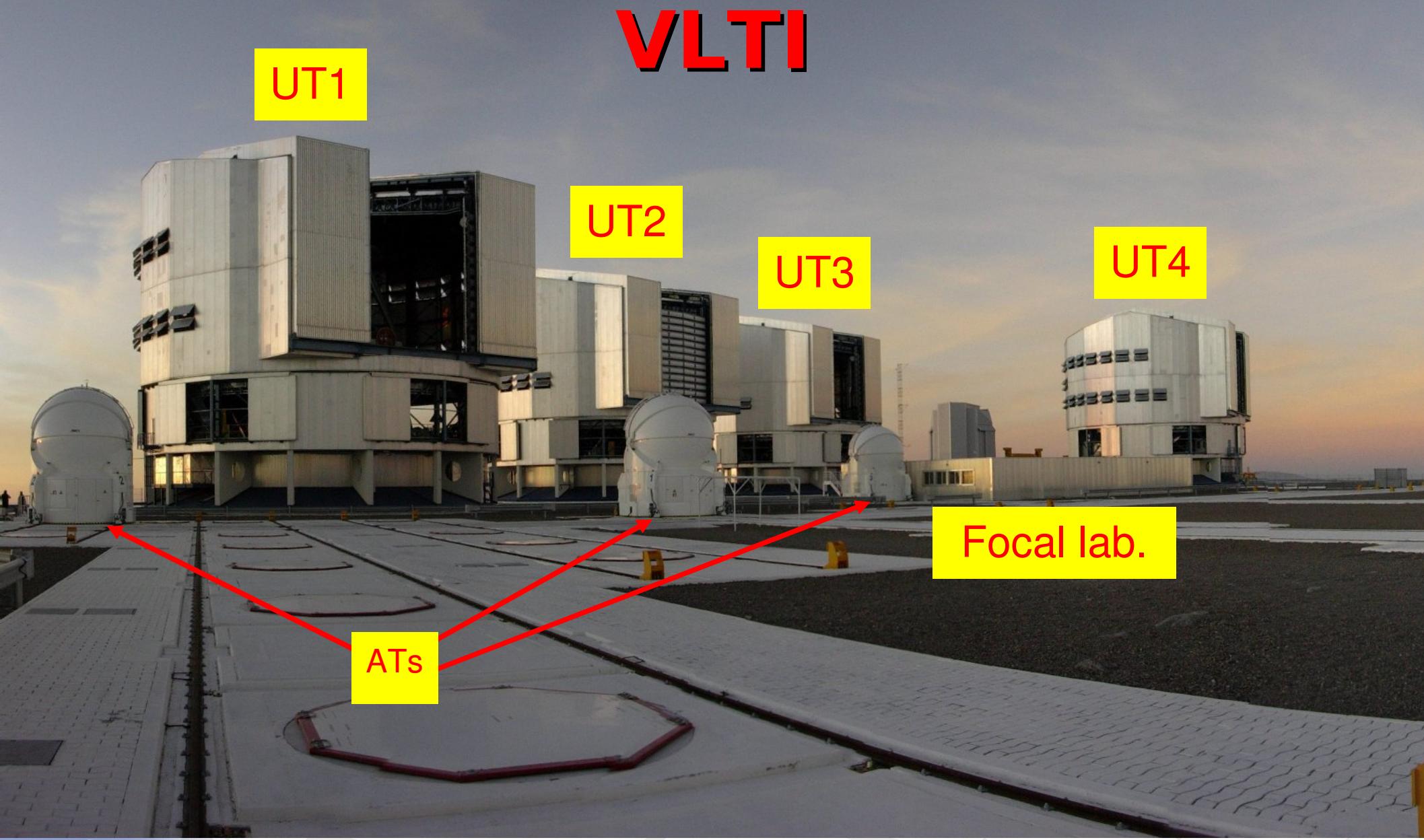
OPD



VLTI (?)



Photo: Florentin Millour





Google

Image © 2006 DigitalGlobe

VLTI

200m

130m

What is (u,v) plane ?

$$V(u, v) = \frac{\hat{I}(u, v)}{\hat{I}(0, 0)}$$

Fourier transform

$$\hat{I}(u, v) \Leftrightarrow I(x, y)$$

$\vec{B} = (\Delta X, \Delta Y, \Delta Z)$ is the projected baseline vector

$(u, v) = \frac{1}{\lambda}(\Delta X, \Delta Y)$ are the spatial frequencies

Spatial frequencies:

- unitless (radians⁻¹)
- represent distances in the wavefront in wavelength units
- (u,v) are conjugated to (x,y)

(u,v) plane and single dish telescope

Object observed at the
Special Astronomical Observatory (Zelentchouk)

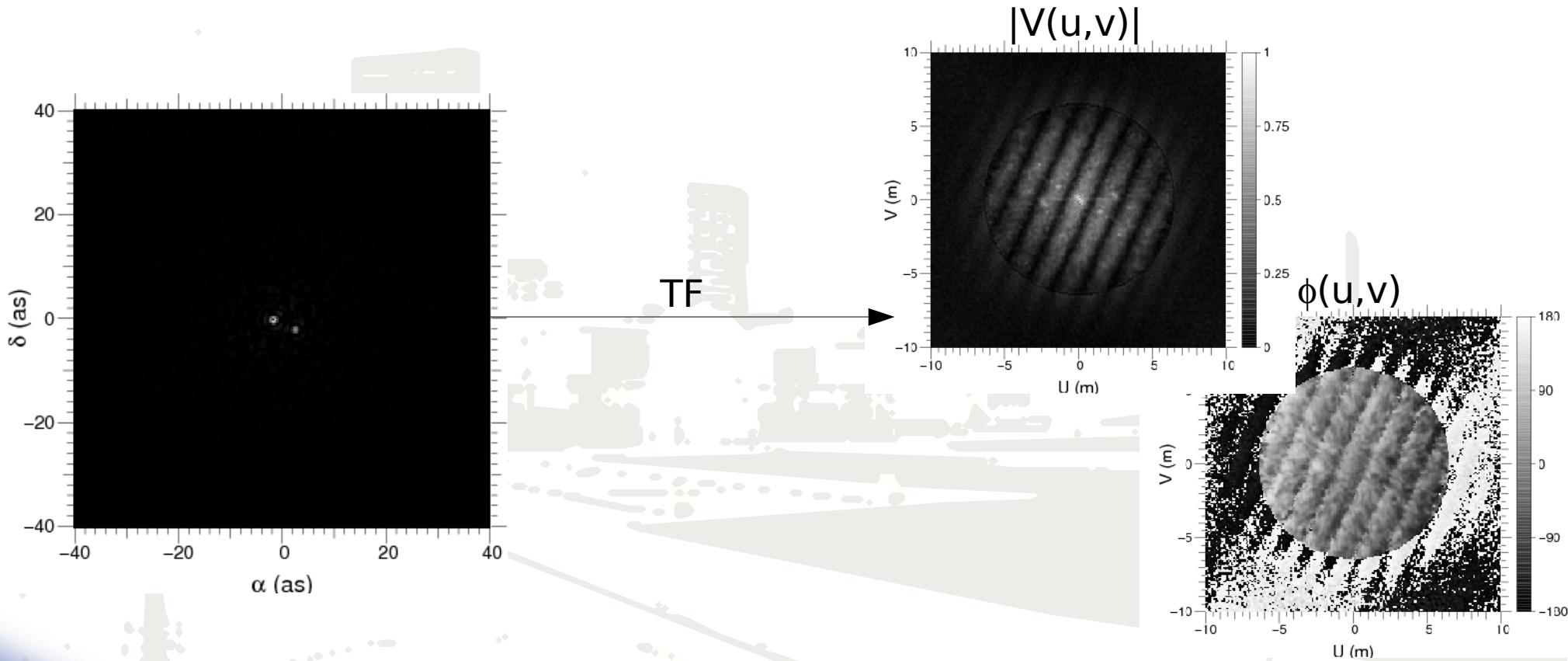


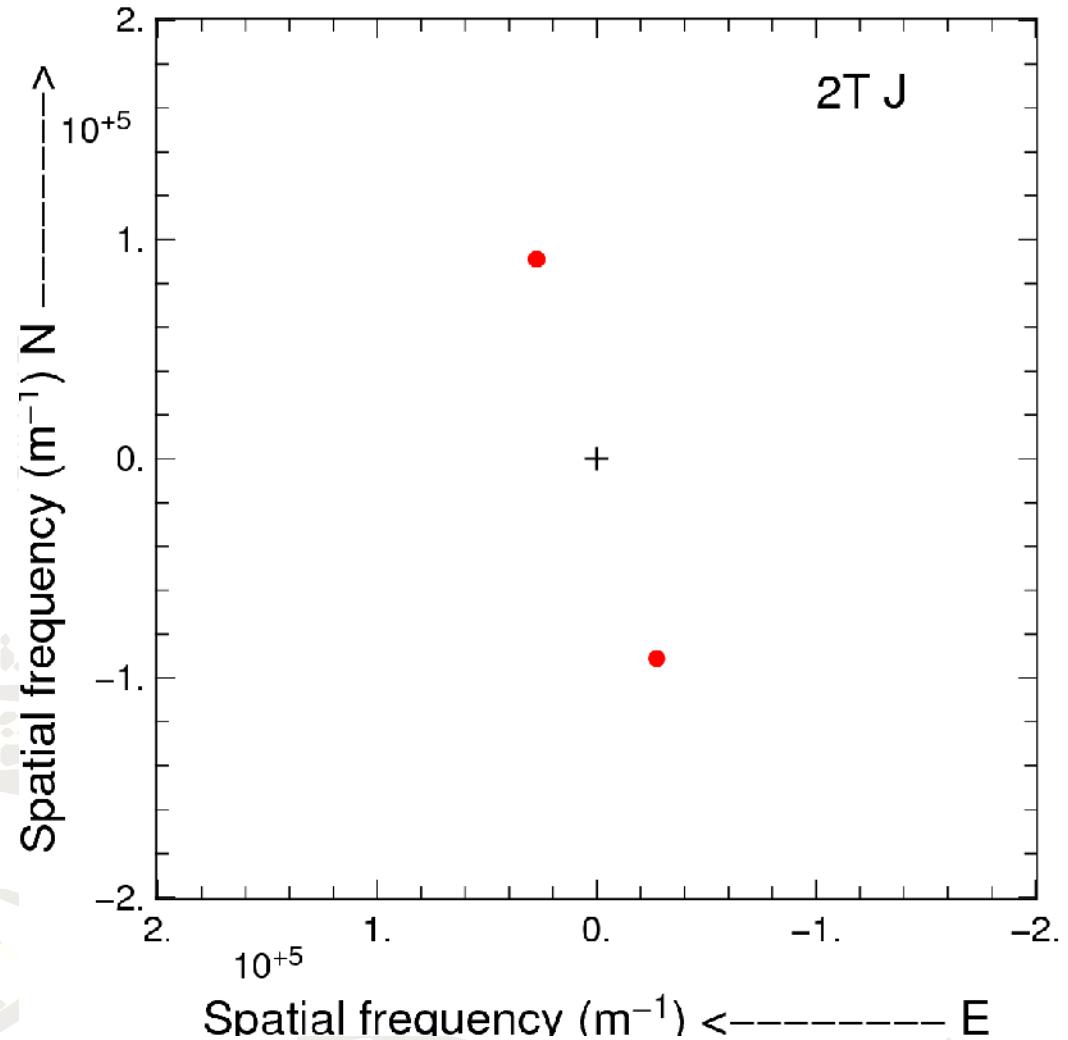
Image : $I(x,y)=O^*PSF$

$|V(u,v)|$, $\phi(u,v)$ & cut-off frequency at D/λ

(u,v) plane with an interferometer: 2T snapshot

(u,v) plane is poorly sampled.

A lot of the object's information is missing due to the (u,v) gaps.



How to fill the gaps ?

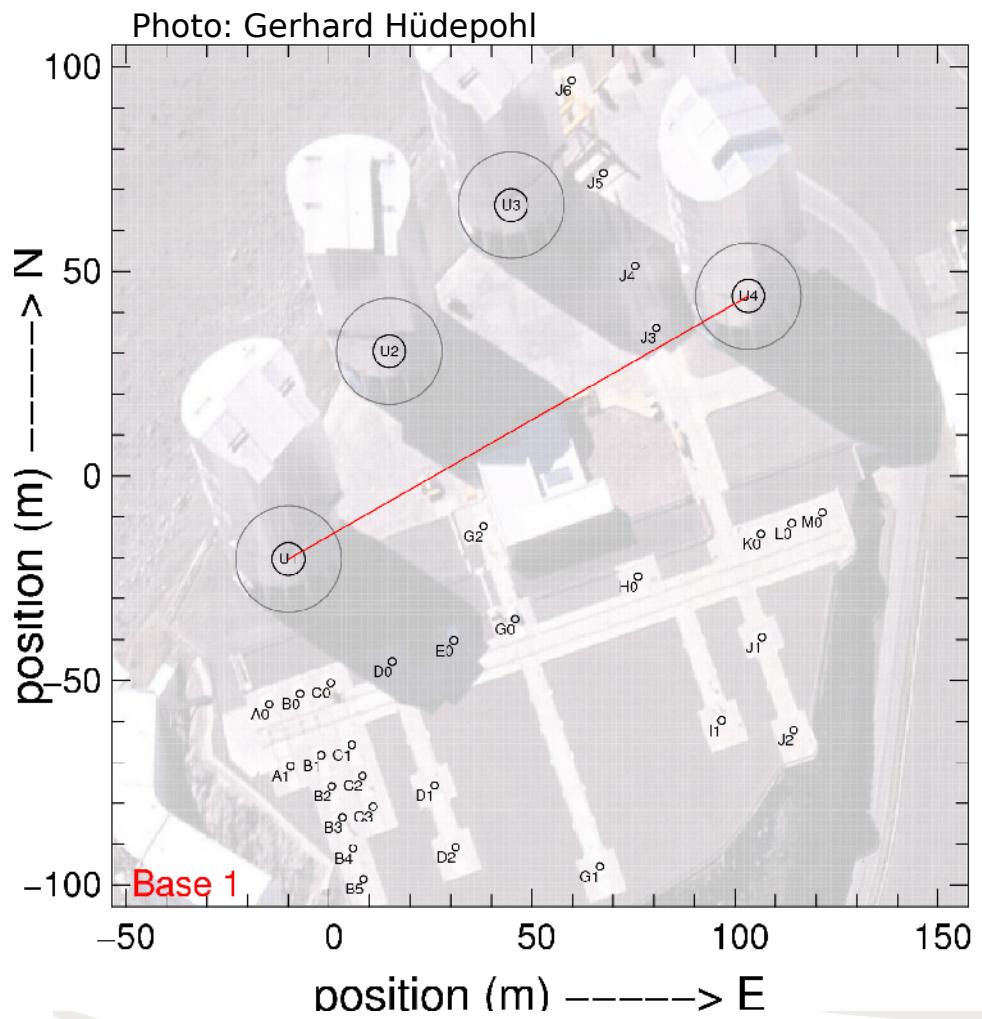
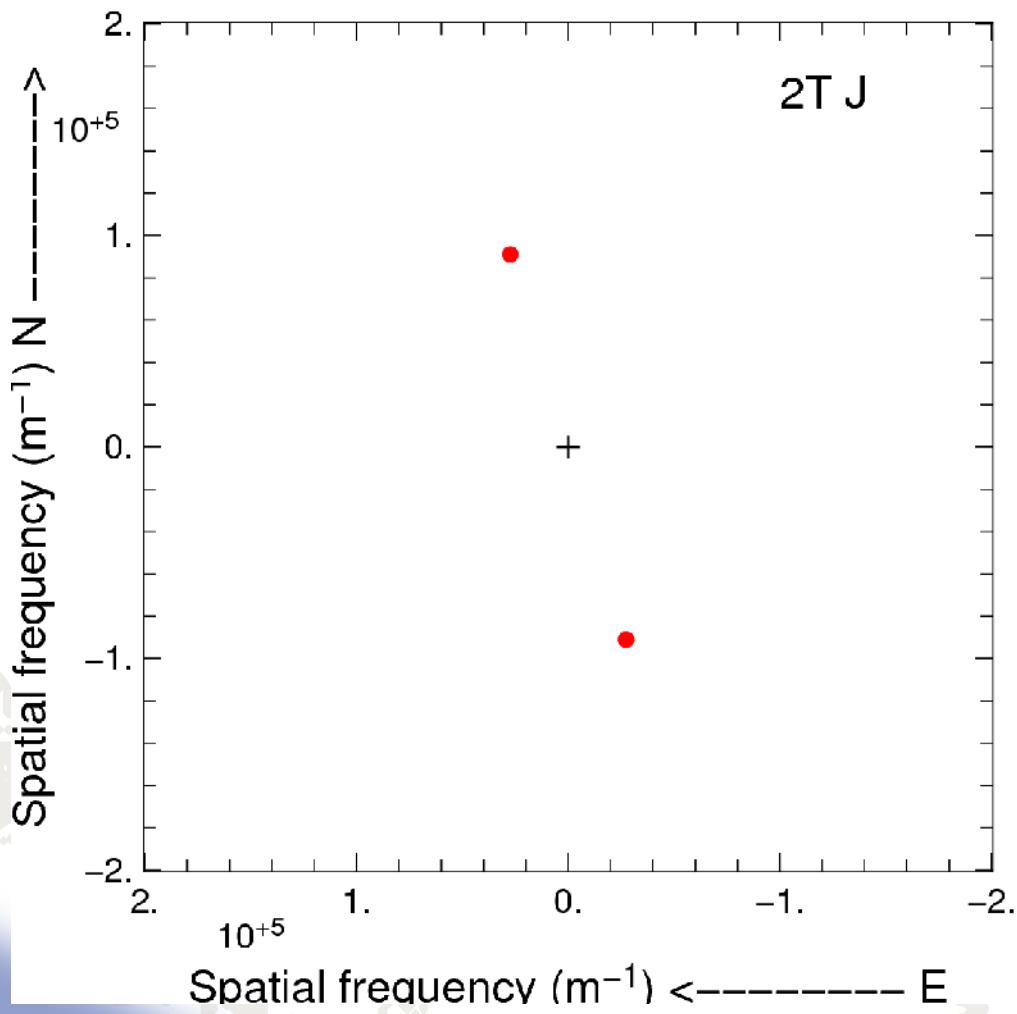
- "**cheap**" way:
 - Earth rotation (supersynthesis) → - **Time consuming**
 - Wavelength range → - **Lower sensitivity**
- "**expensive**" way:
 - Increase Nr of telescopes → - **Expensive**
 - Baseline reconfiguration → - **Time consuming & expensive**

(u,v) plane filling with more telescopes

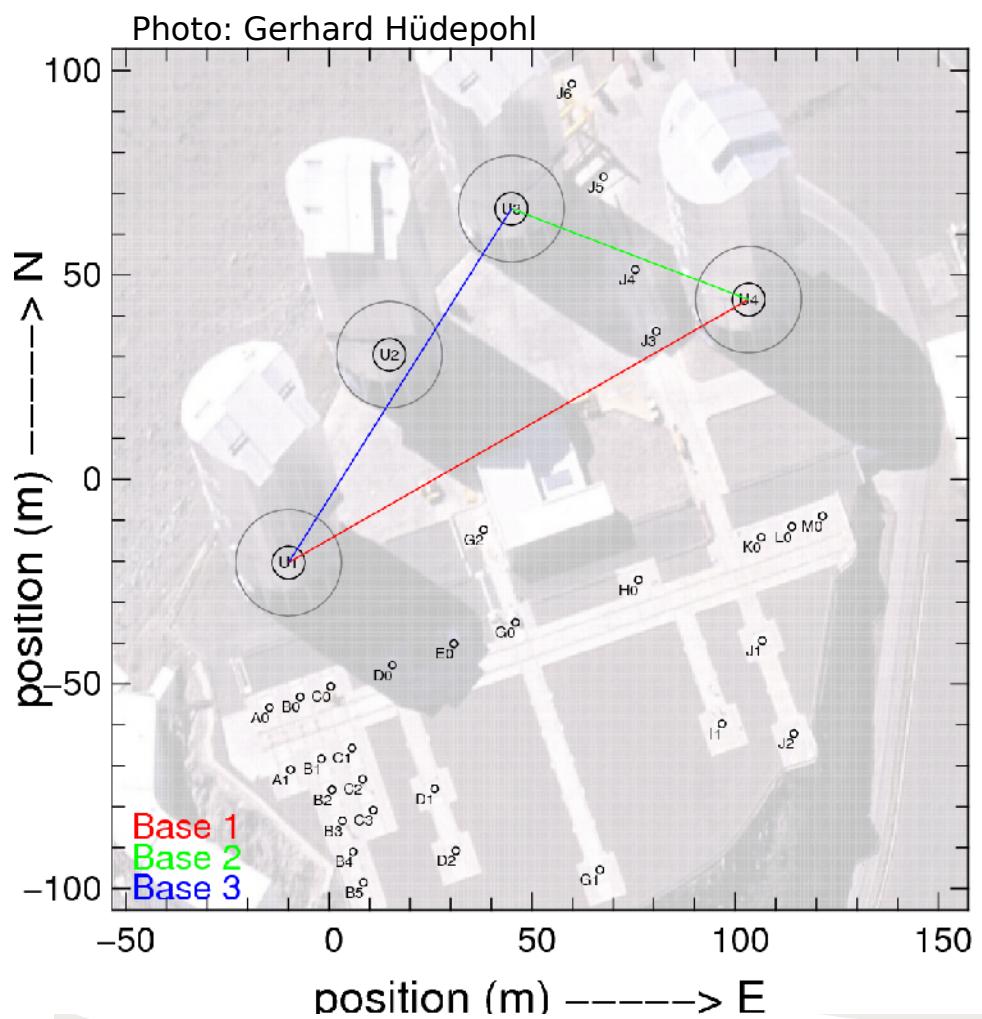
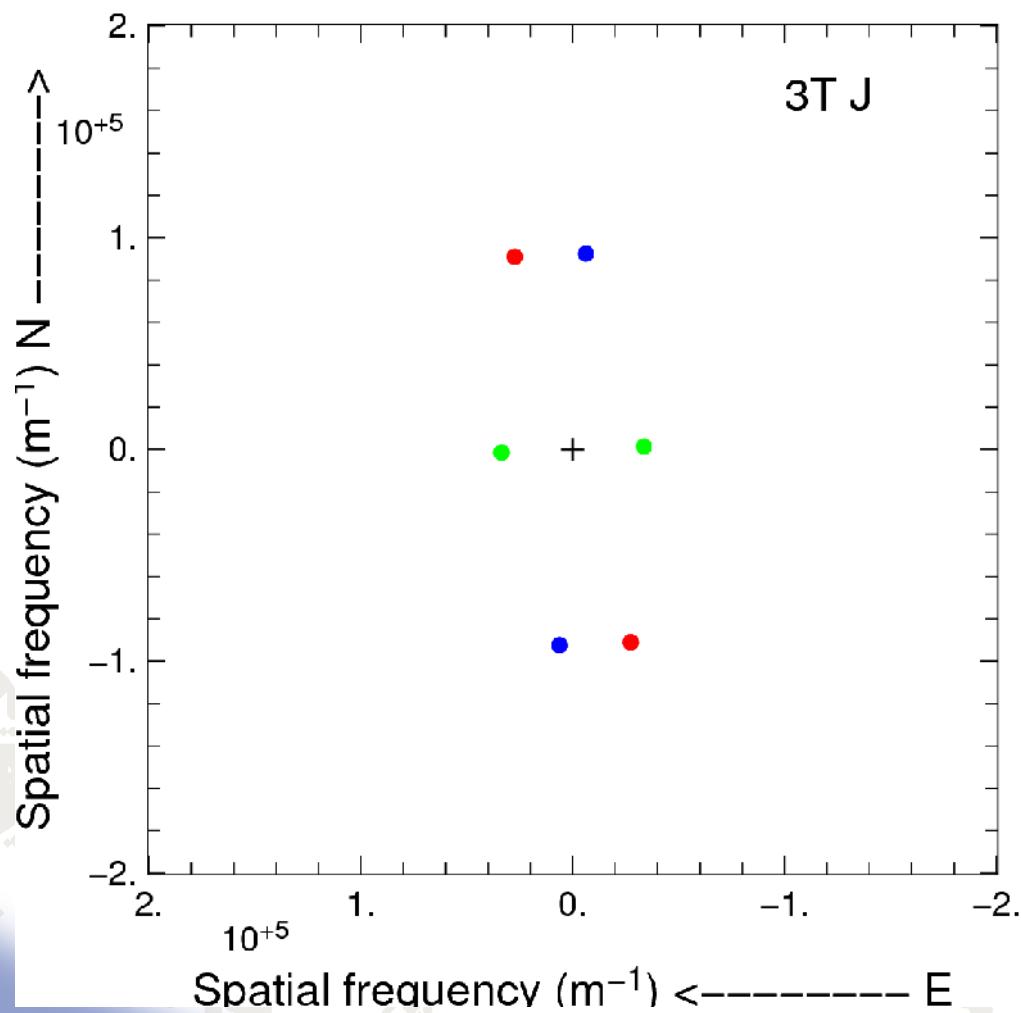
- A 2 telescopes interferometer gives access to **1** (u,v) point per measurement.
 - A 3 telescopes interferometer gives access to **3** (u,v) point per measurement.
 - A N telescopes interferometer gives access to $N(N-1)/2$ points per measurements
- => We have access to high spatial frequencies but ...

A lot of gaps remain in the (u,v) plane

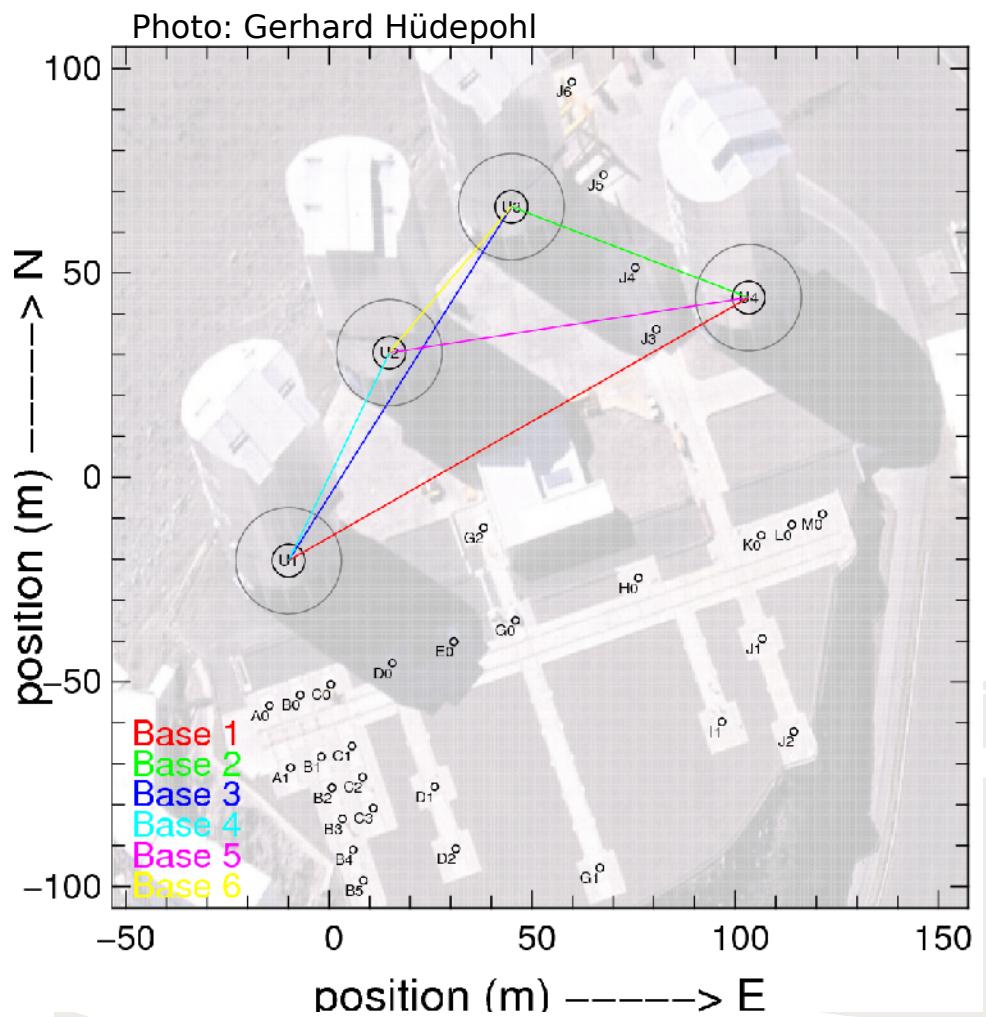
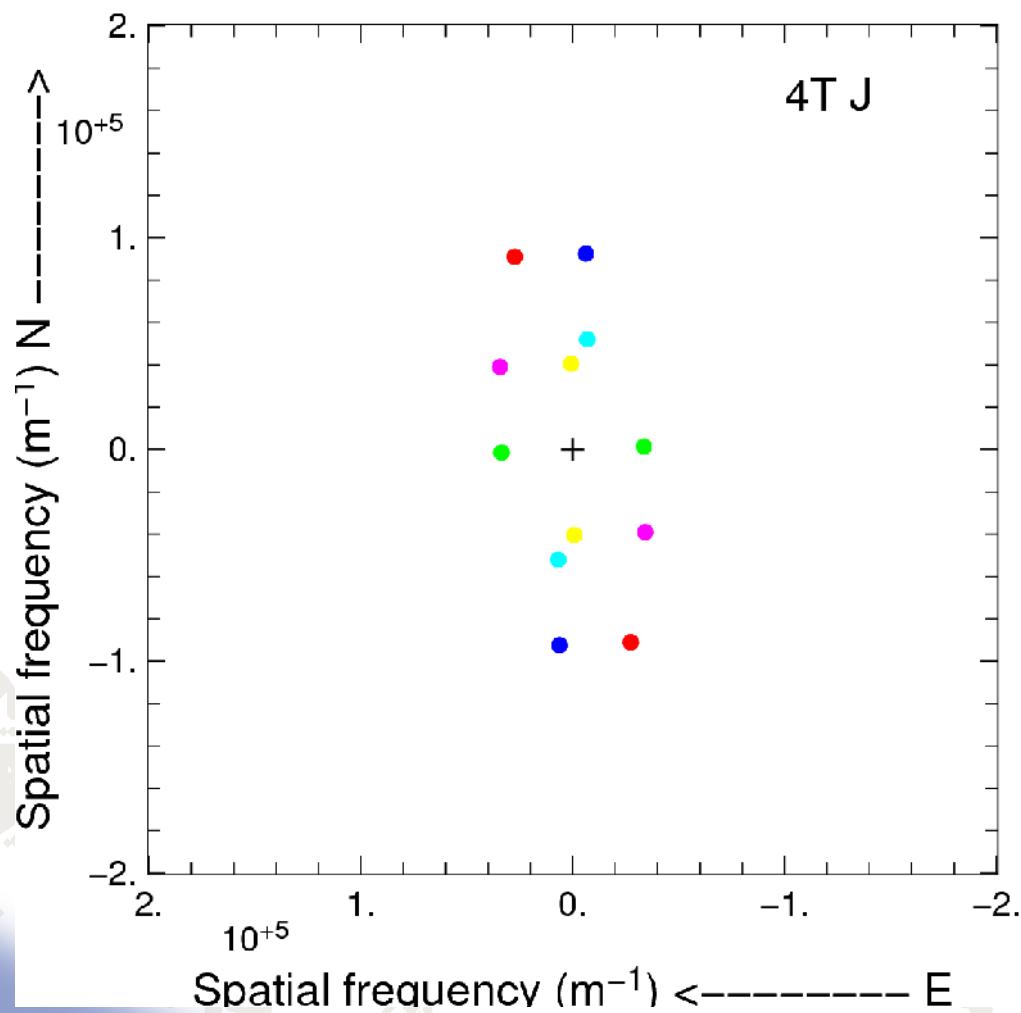
(u,v) plane filling with more telescopes: 2T



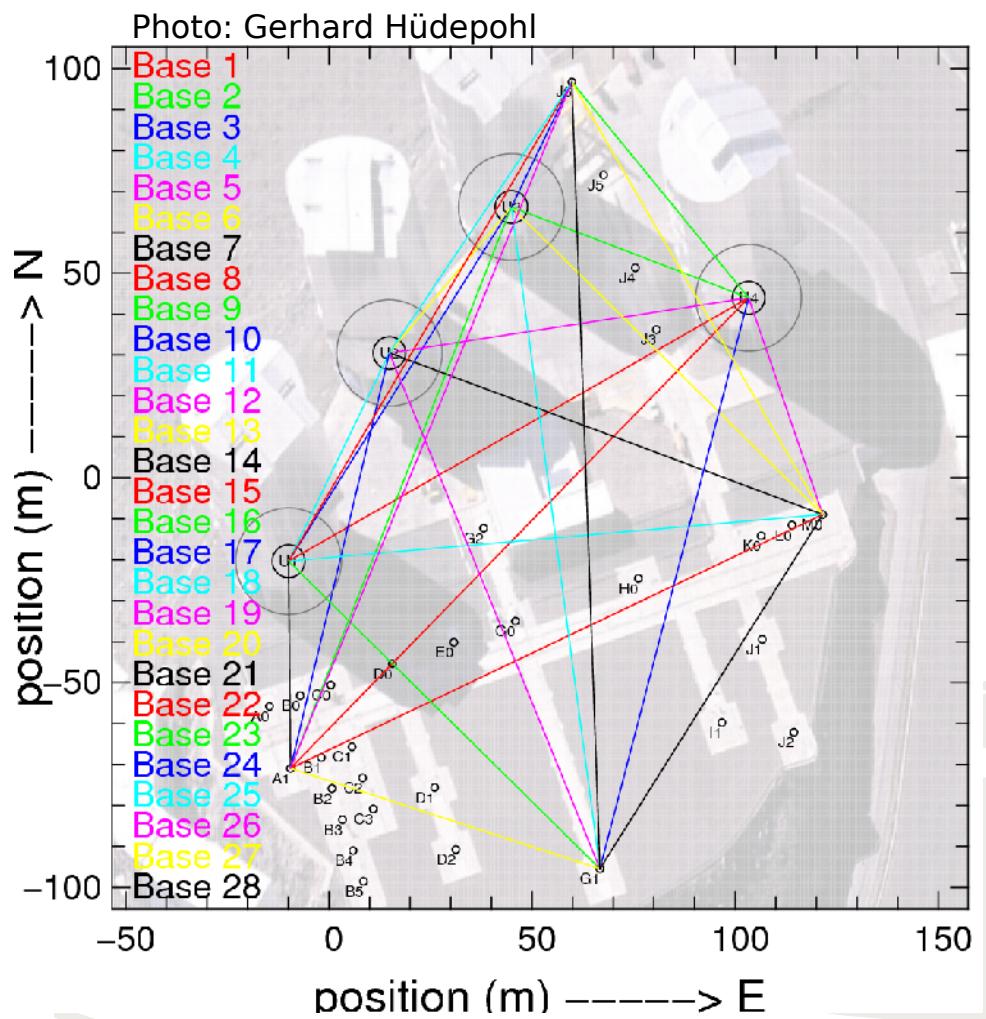
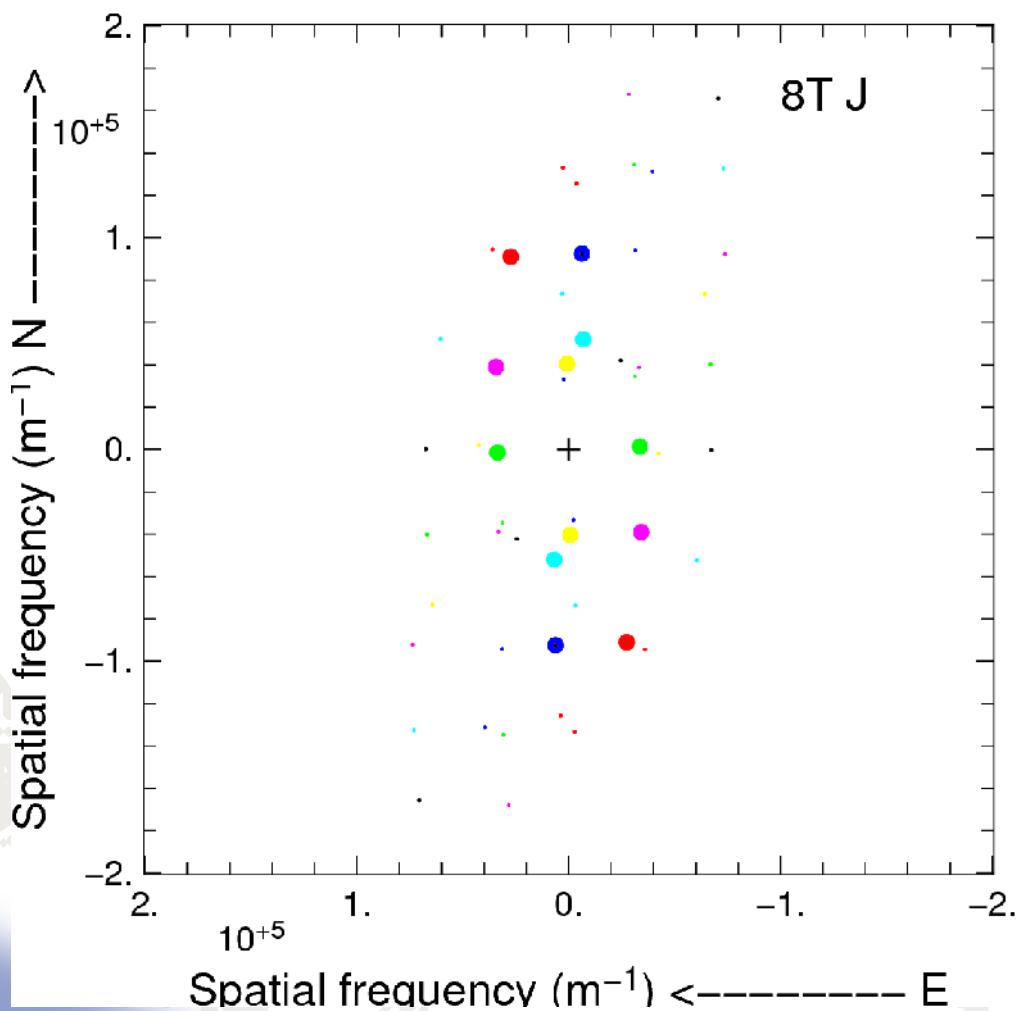
(u,v) plane filling with more telescopes: 3T



(u,v) plane filling with more telescopes: 4T



(u,v) plane filling with more telescopes: 8T (4AT & 4UT)



(u,v) plane filling with the earth rotation (supersynthesis)

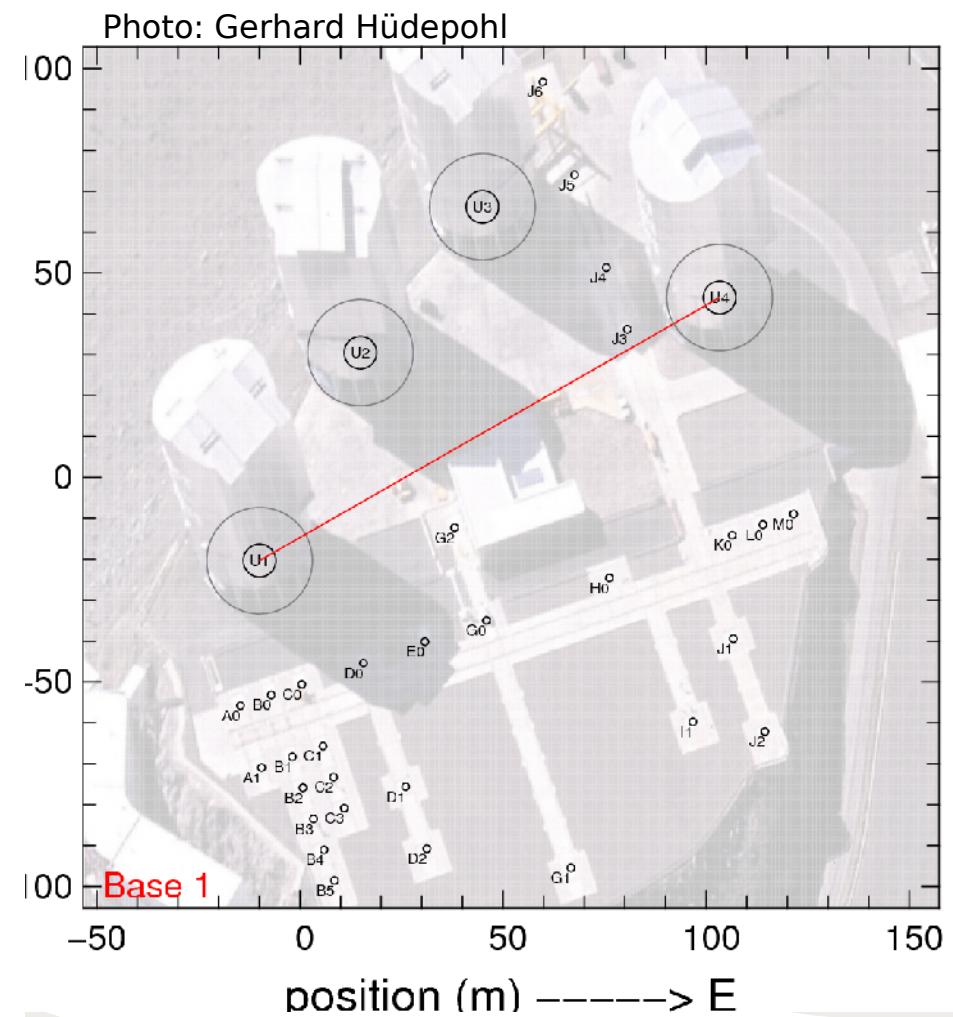
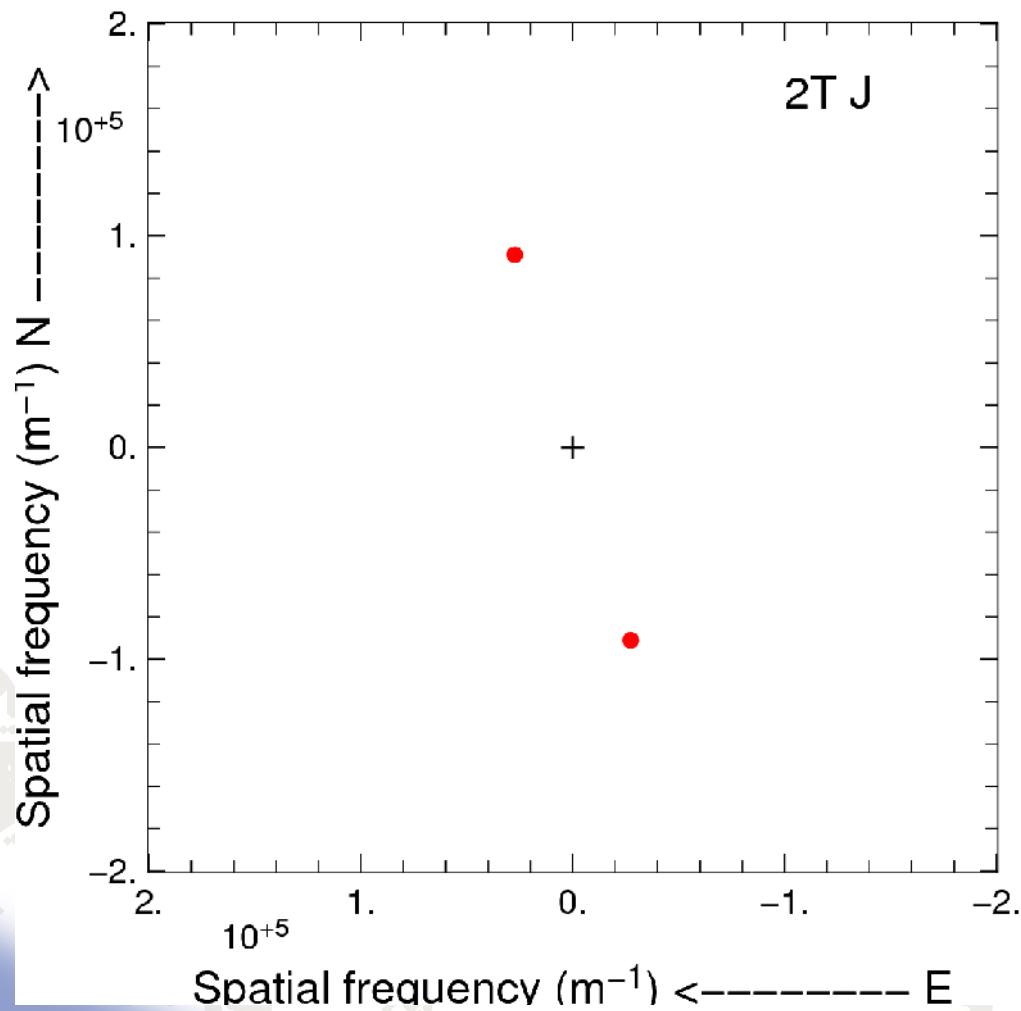
- (u,v) plane sampling depends on:
 - hour angle h
 - source declination δ
 - baseline vector (X,Y,Z)

$$\begin{pmatrix} u \\ v \\ w \end{pmatrix} = \frac{1}{\lambda} \begin{pmatrix} \sin(h) & \cos(h) & 0 \\ -\sin(\delta)\cos(h) & \sin(\delta)\cos(h) & \cos(\delta) \\ \cos(\delta)\cos(h) & -\cos(\delta)\sin(h) & \sin(\delta) \end{pmatrix} \begin{pmatrix} X \\ Y \\ Z \end{pmatrix}$$

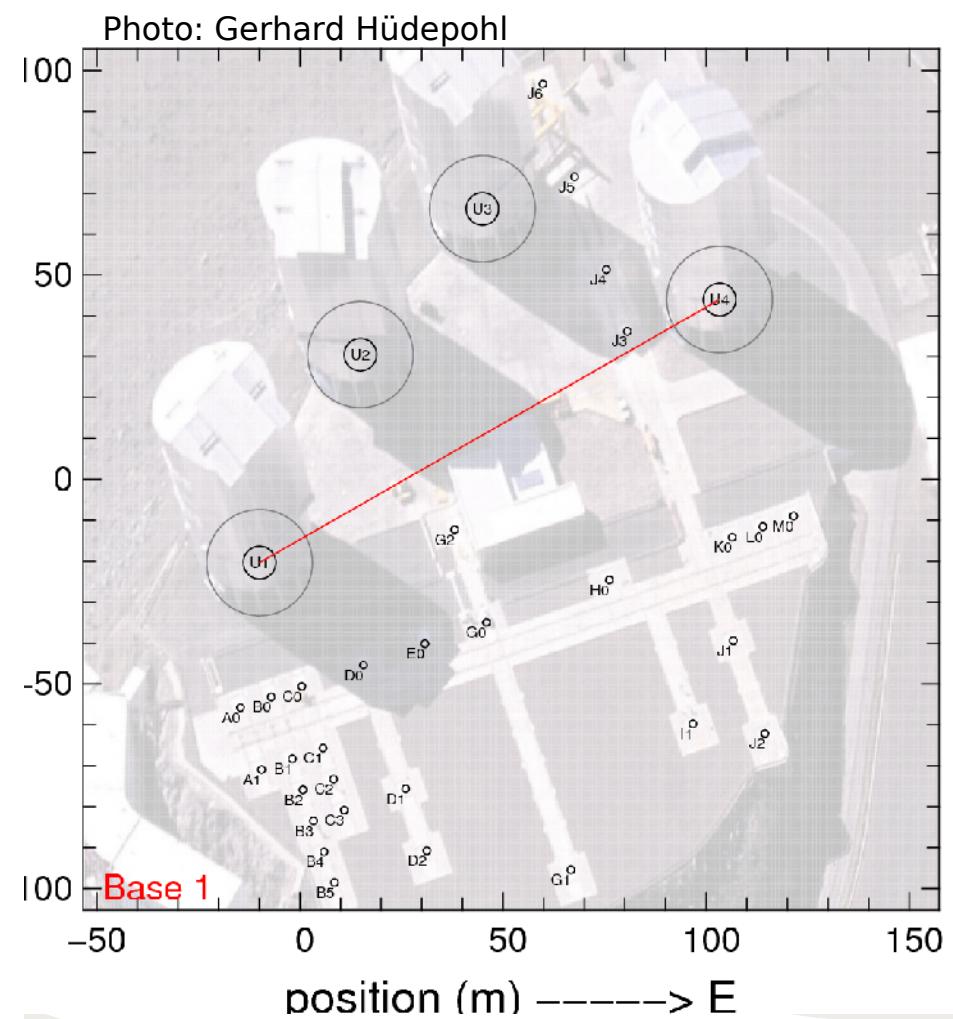
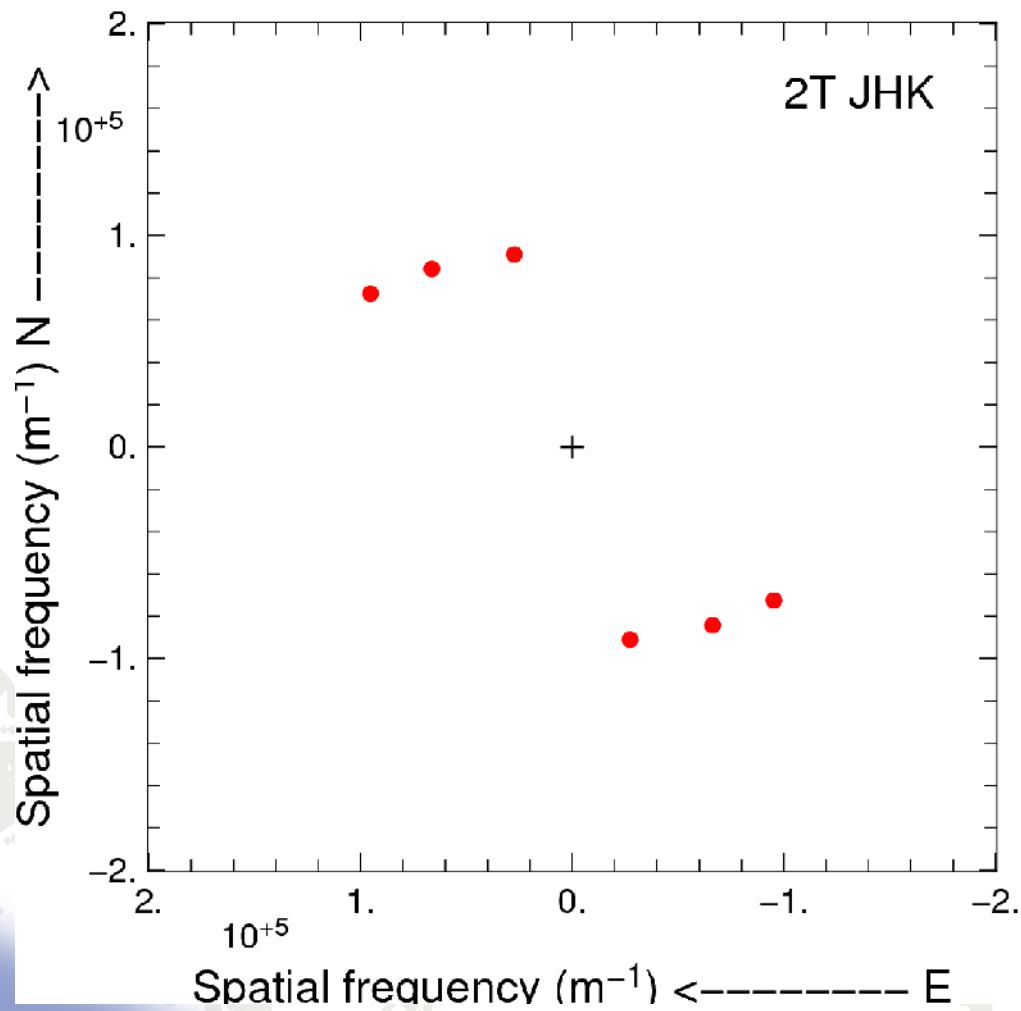
- Eliminating h from the equation above gives an ellipse equation:

$$u^2 + \left(\frac{v - \frac{Z}{\lambda} \cos(\delta)}{\sin(\delta)} \right)^2 = \frac{X^2 + Y^2}{\lambda^2}$$

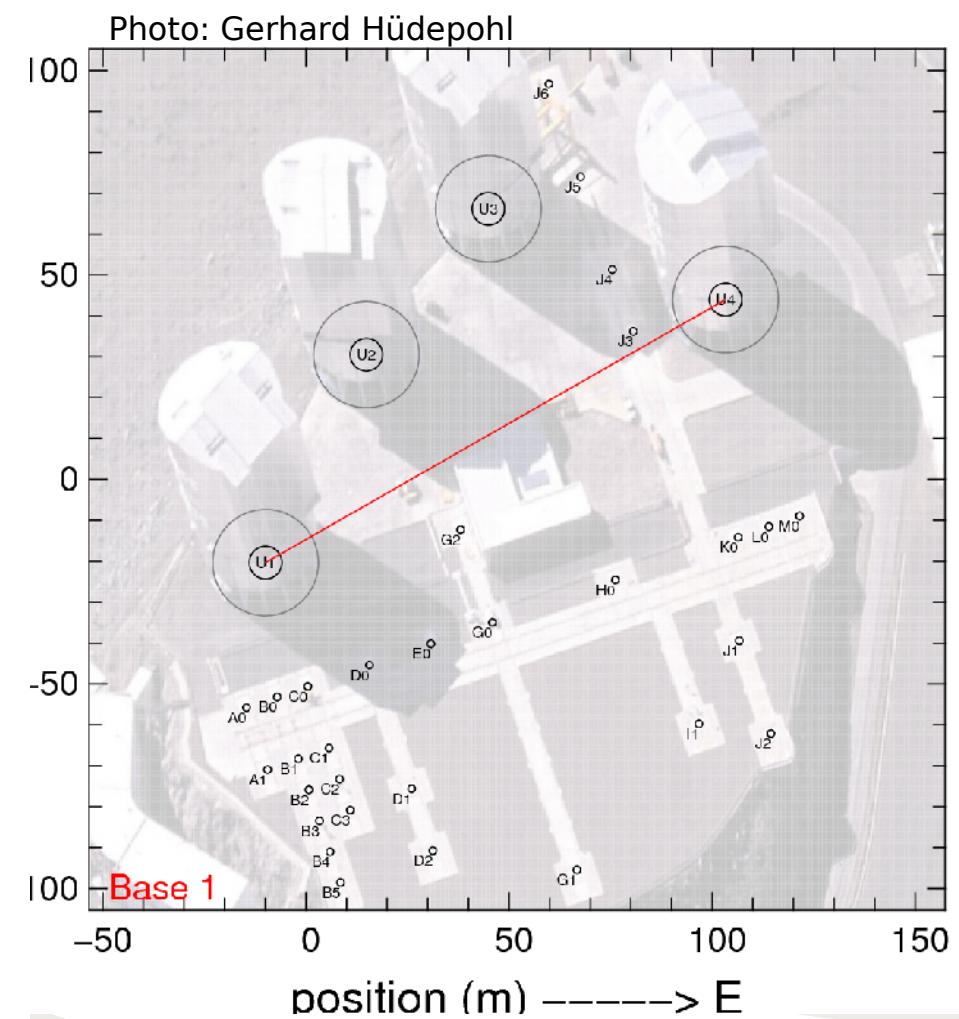
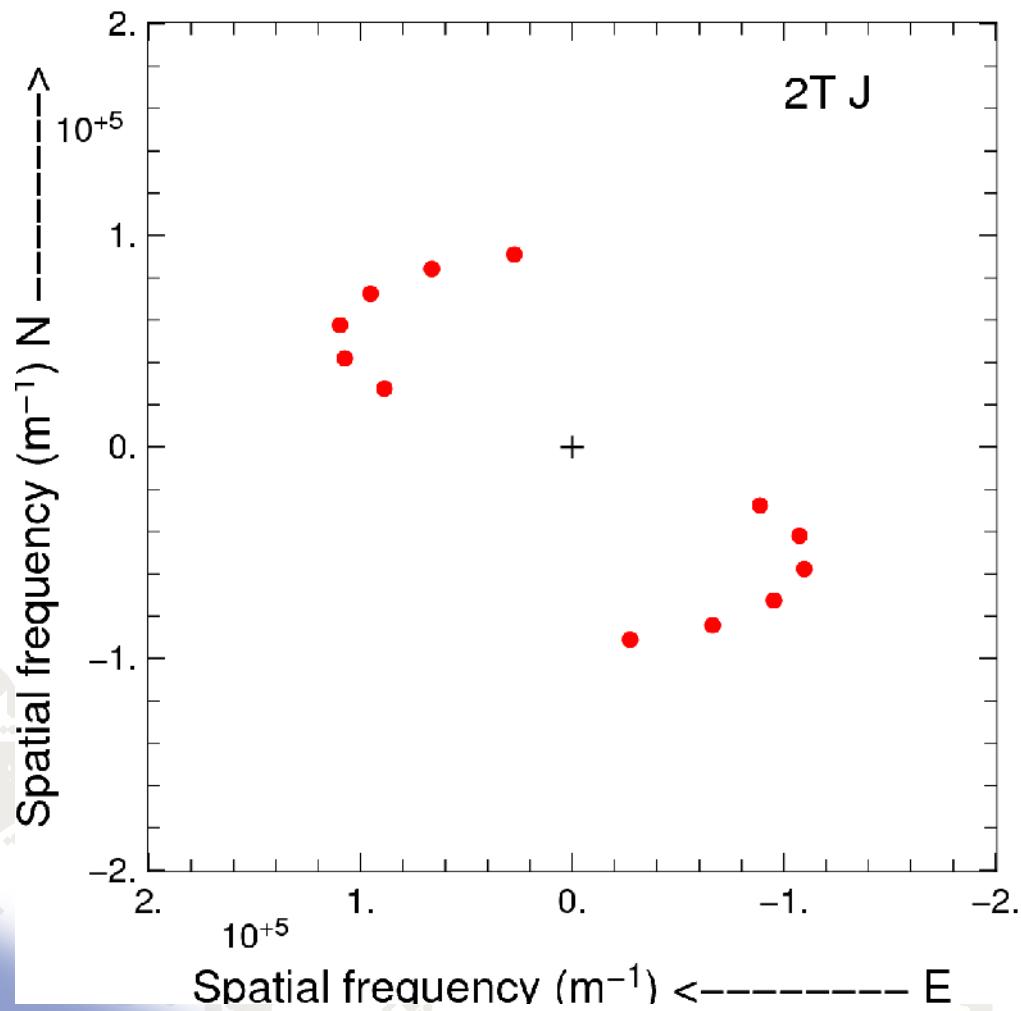
Supersynthesis (2T)



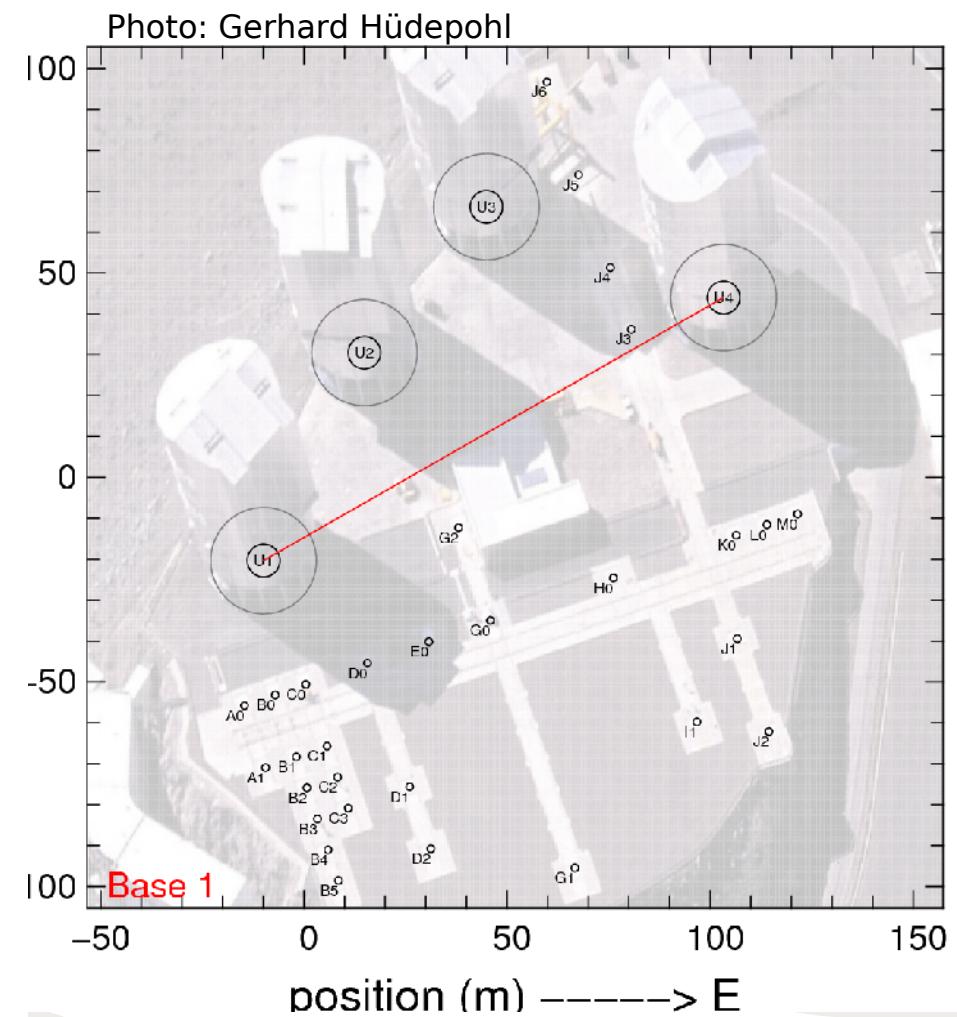
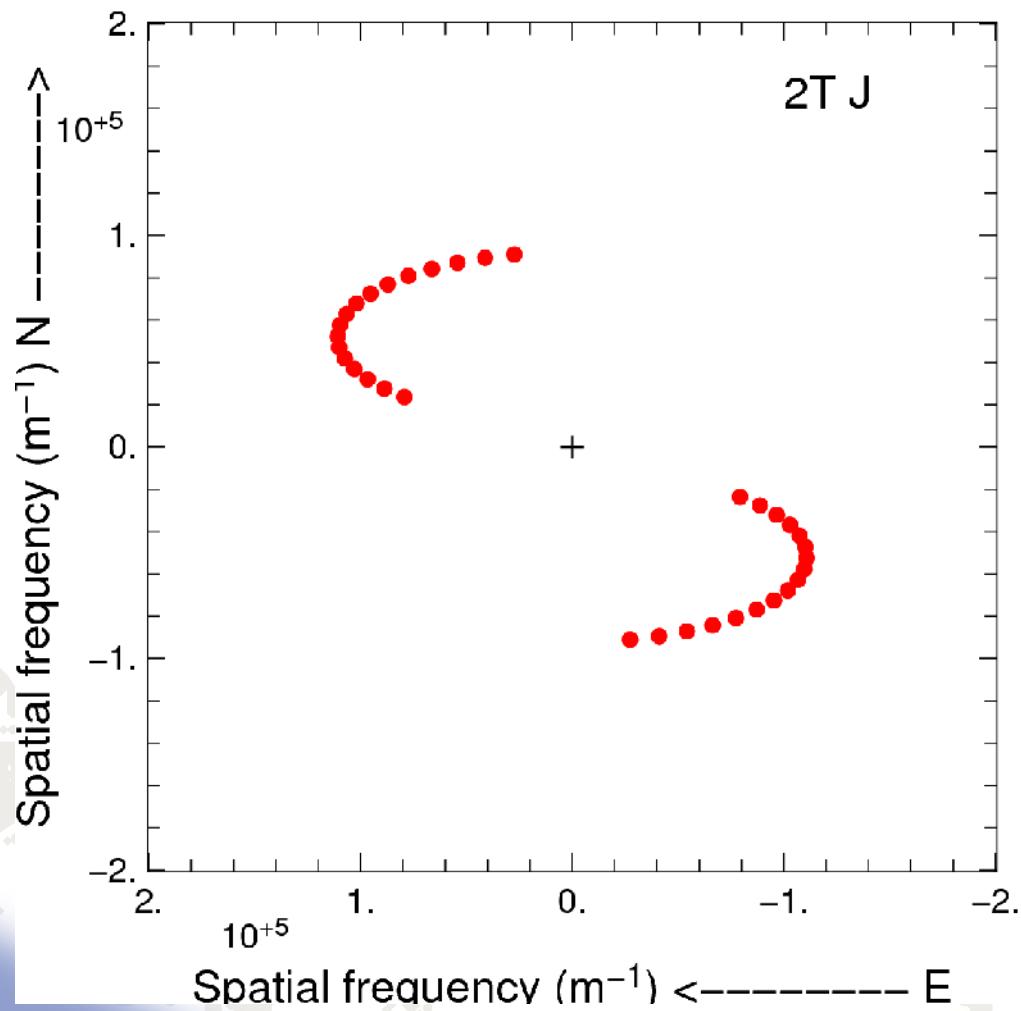
Supersynthesis (2T)



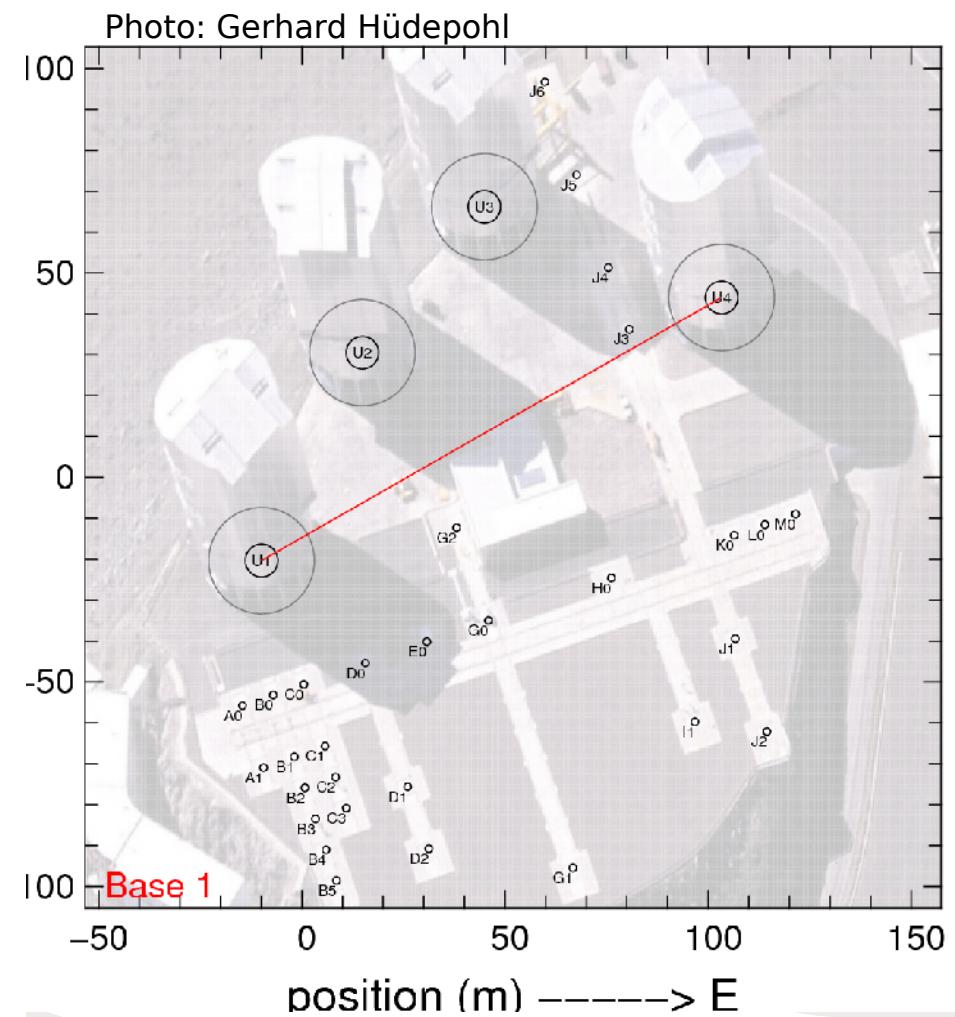
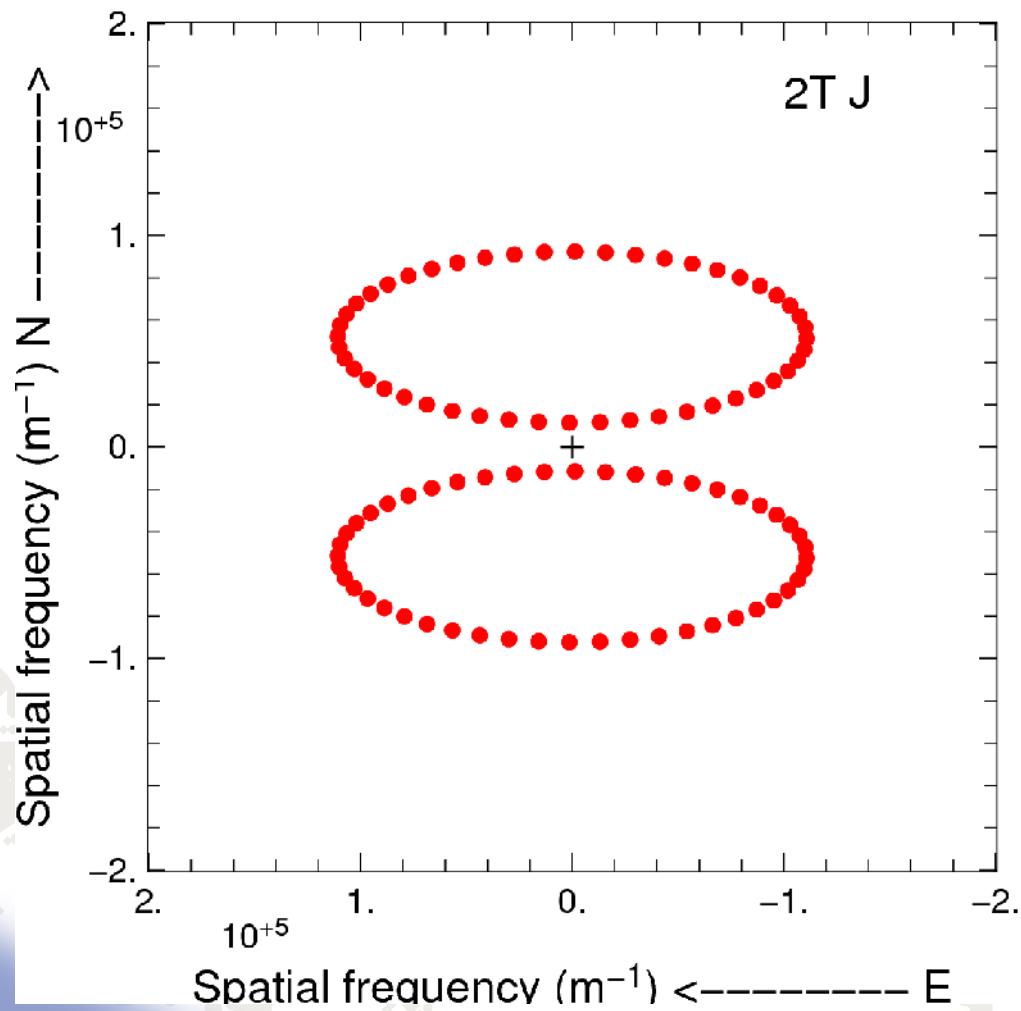
Supersynthesis (2T)



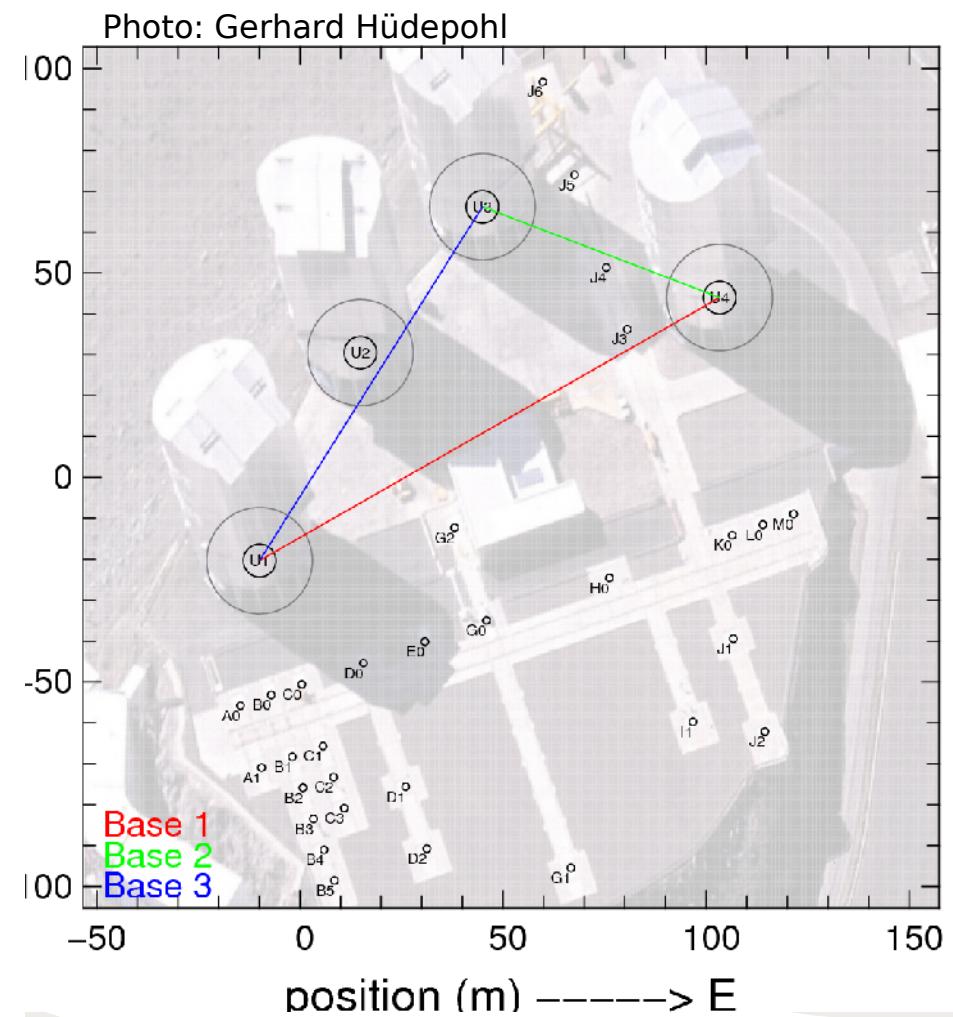
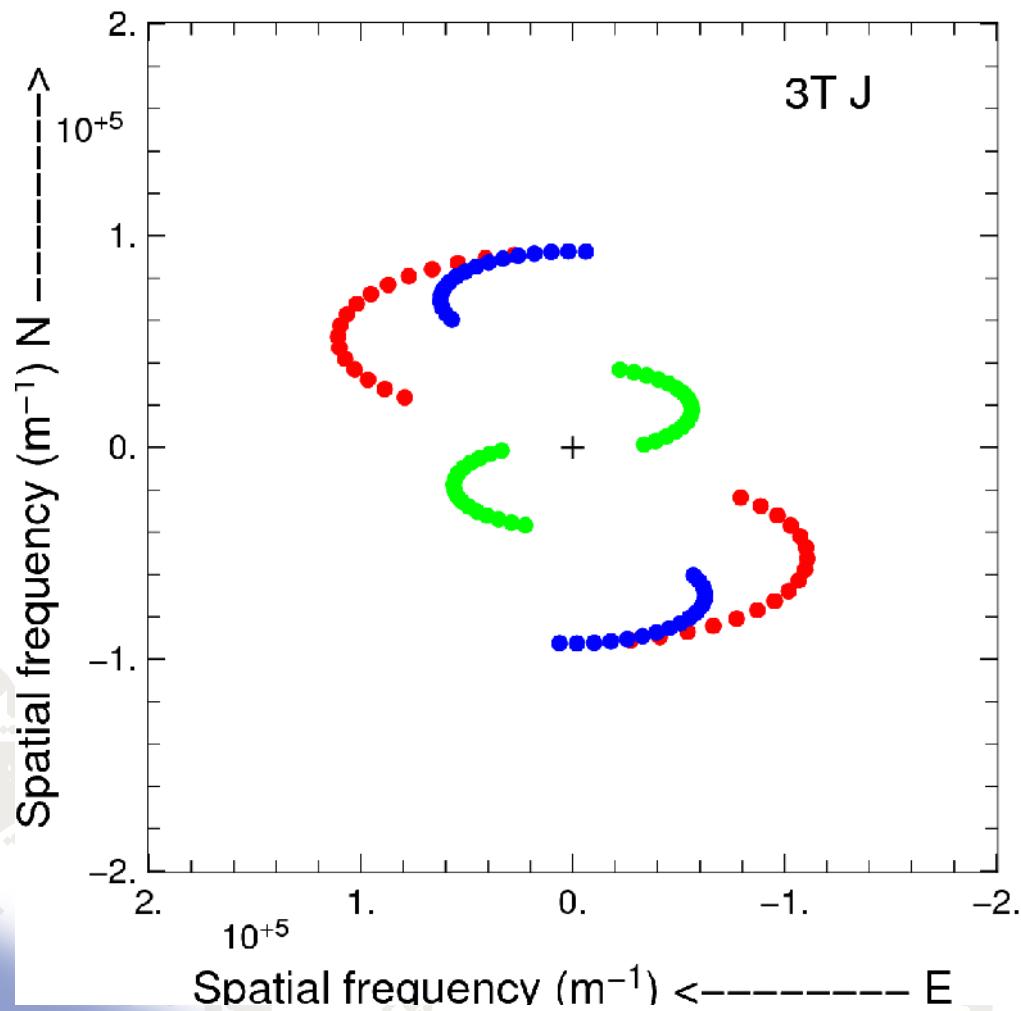
Supersynthesis (2T)



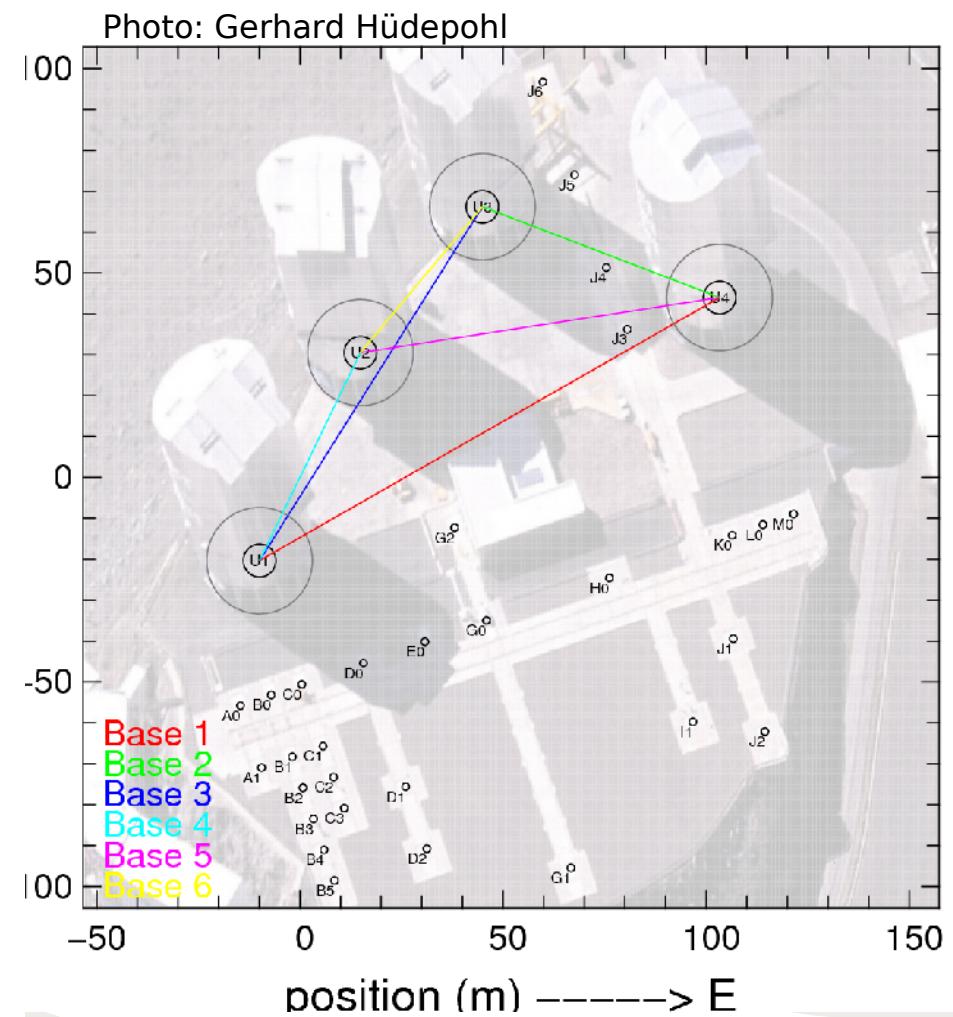
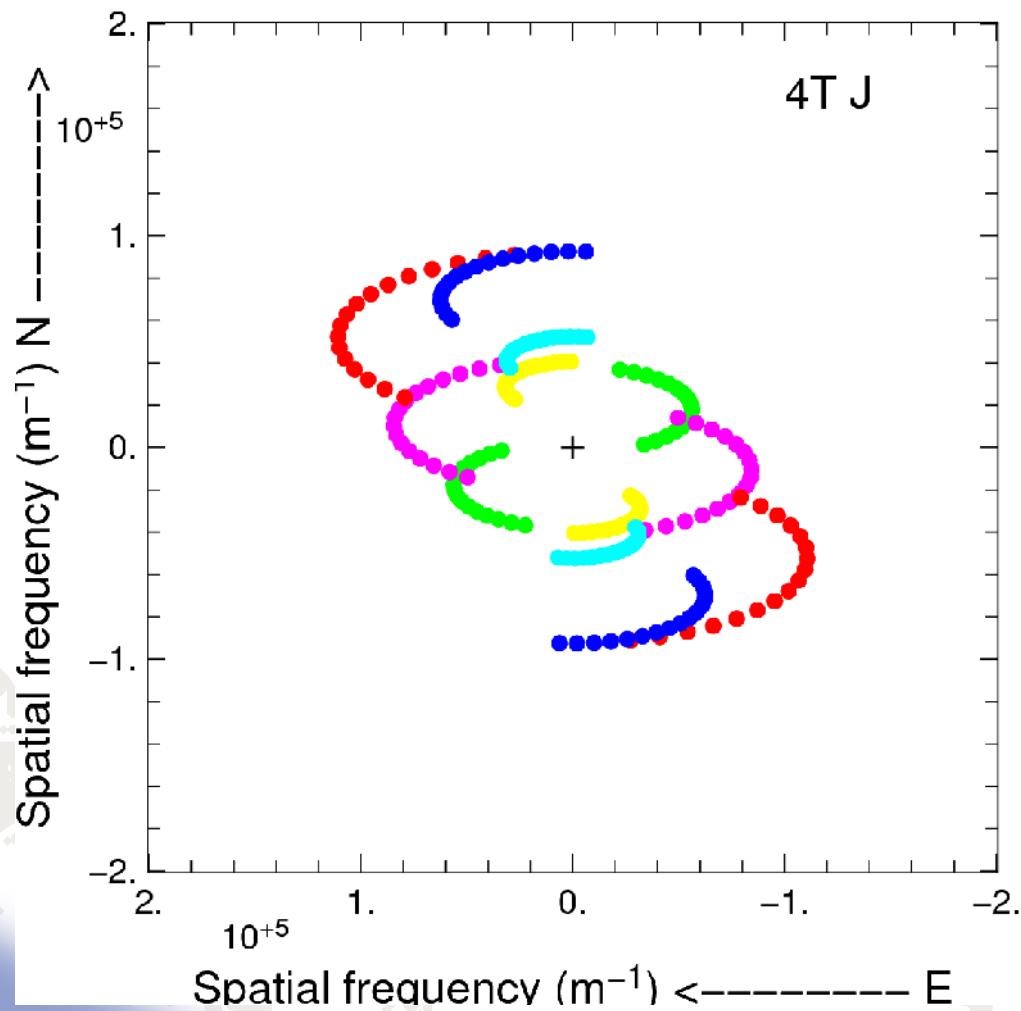
Supersynthesis (2T)



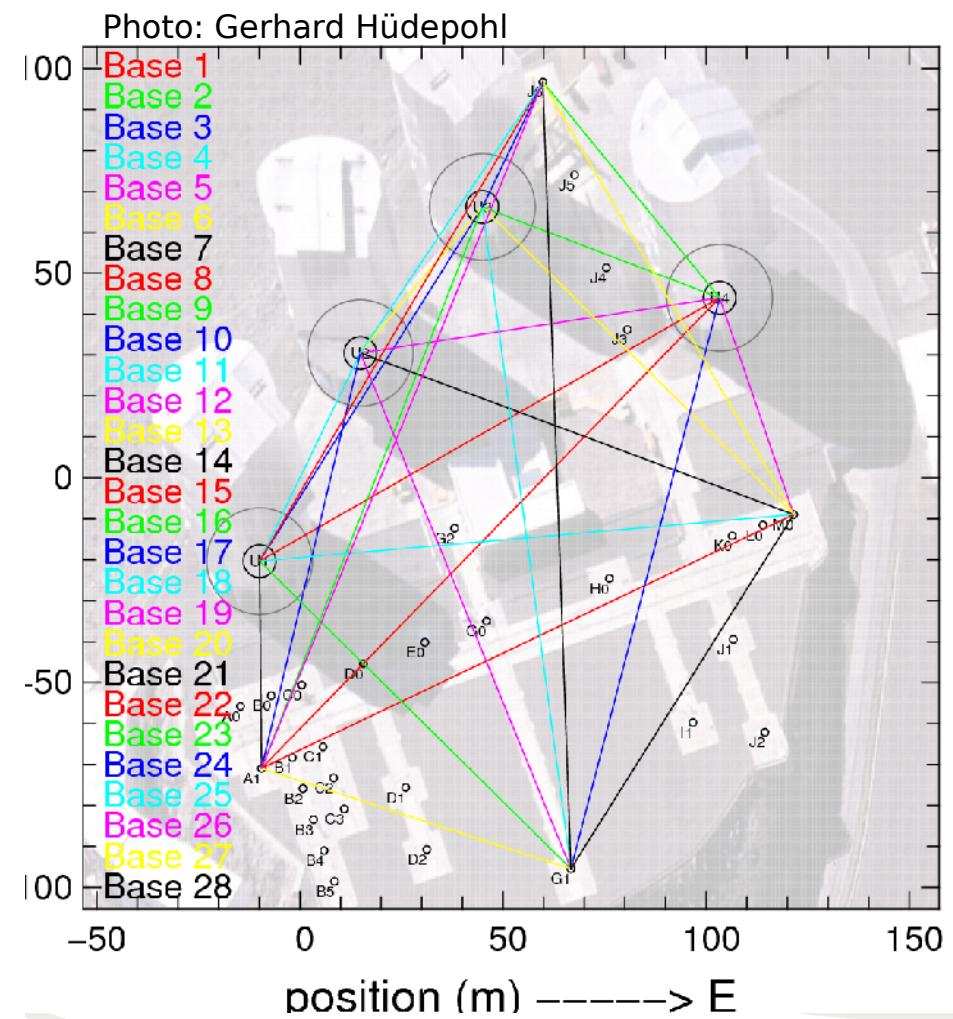
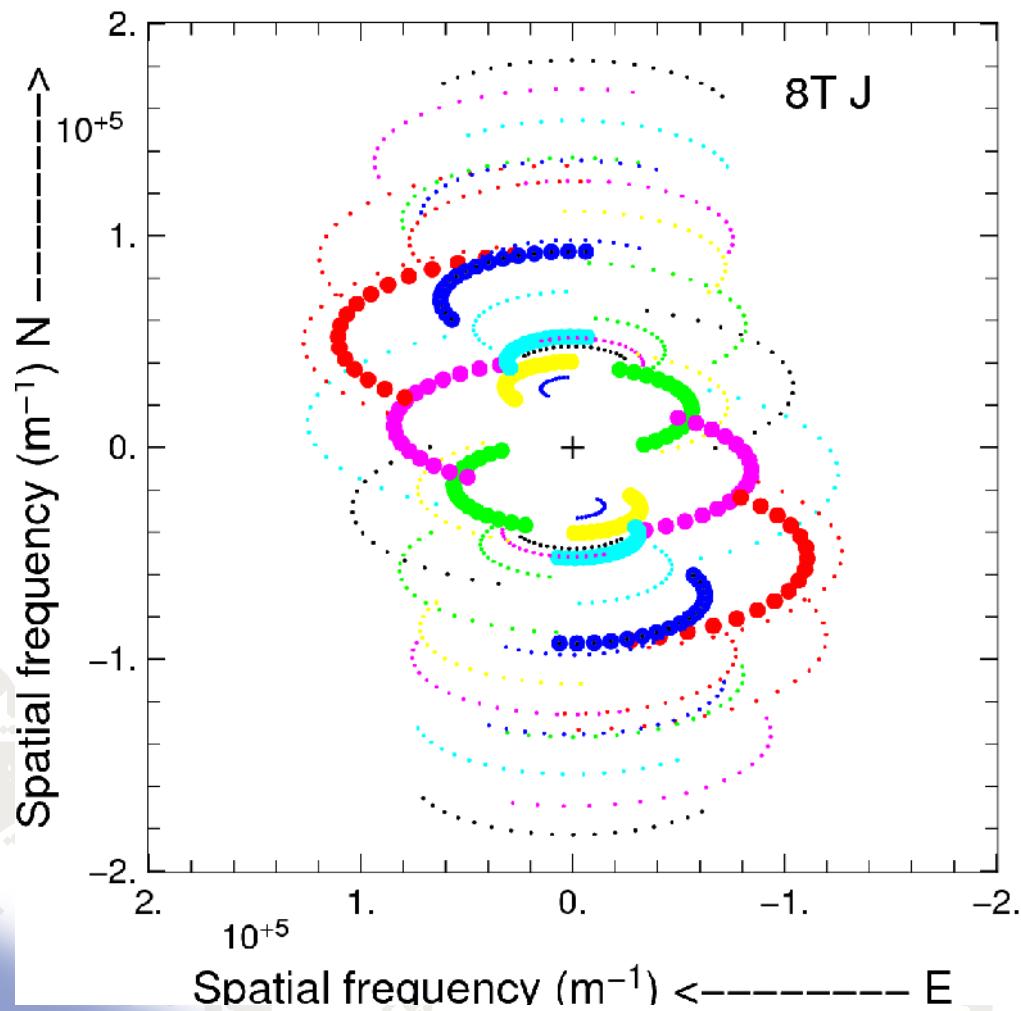
Supersynthesis (3T)



Supersynthesis (4T)



Supersynthesis (8T)

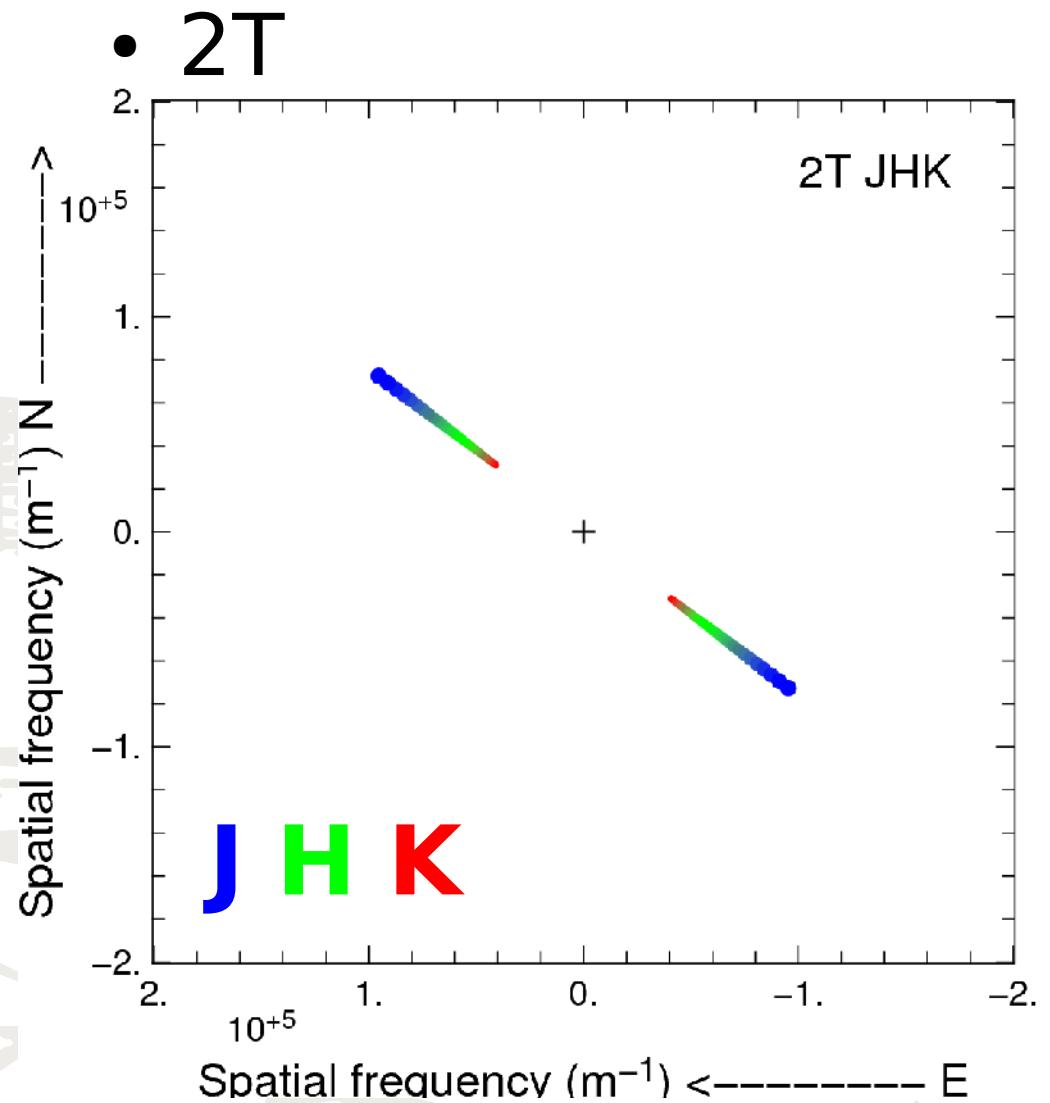


(u,v) plane filling with spectral coverage

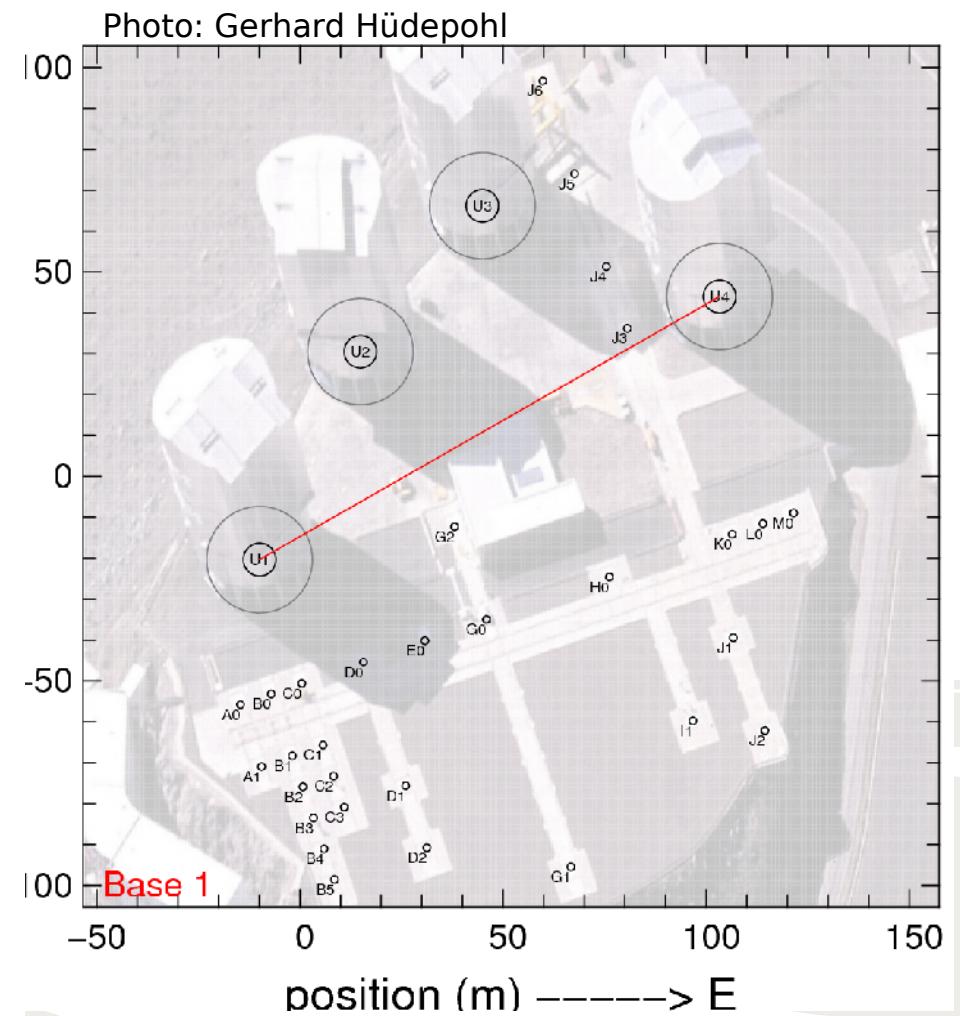
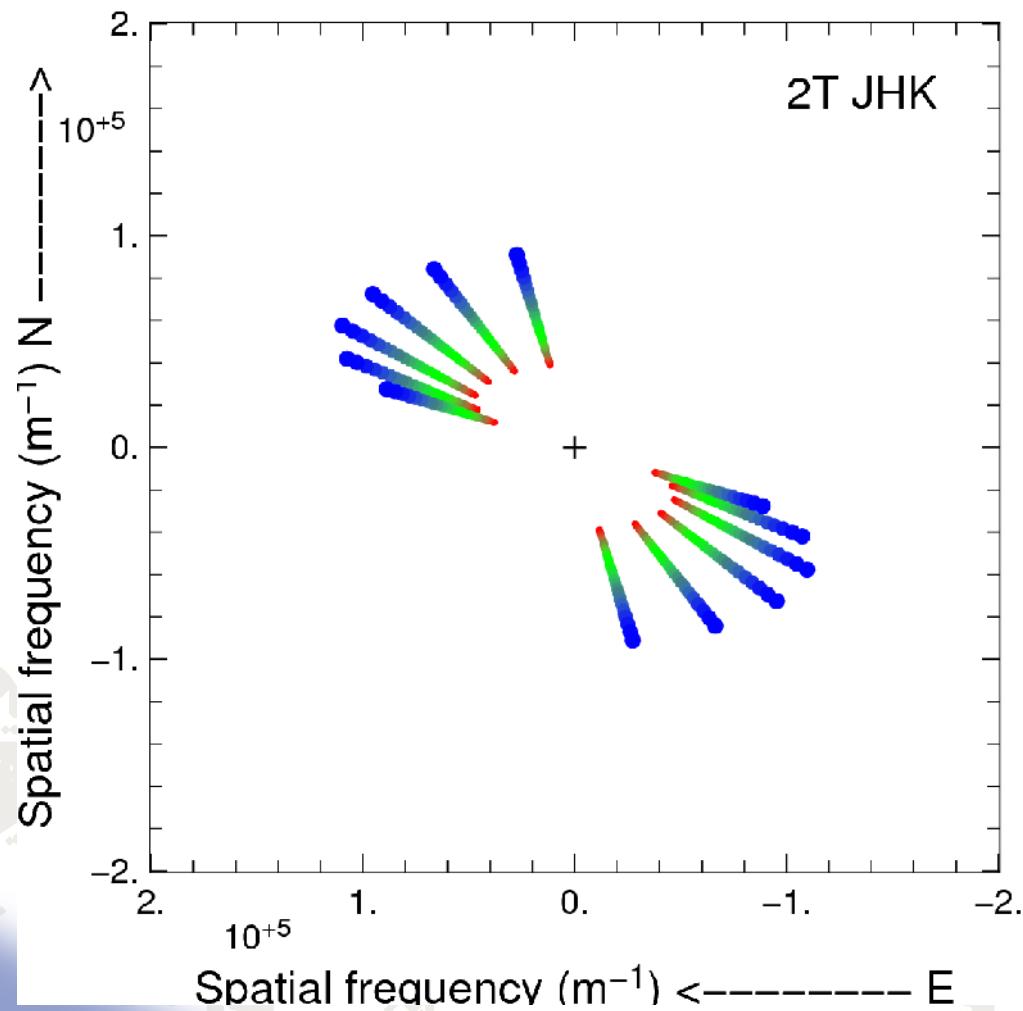
- Spatial frequencies:

$$f = B/\lambda$$

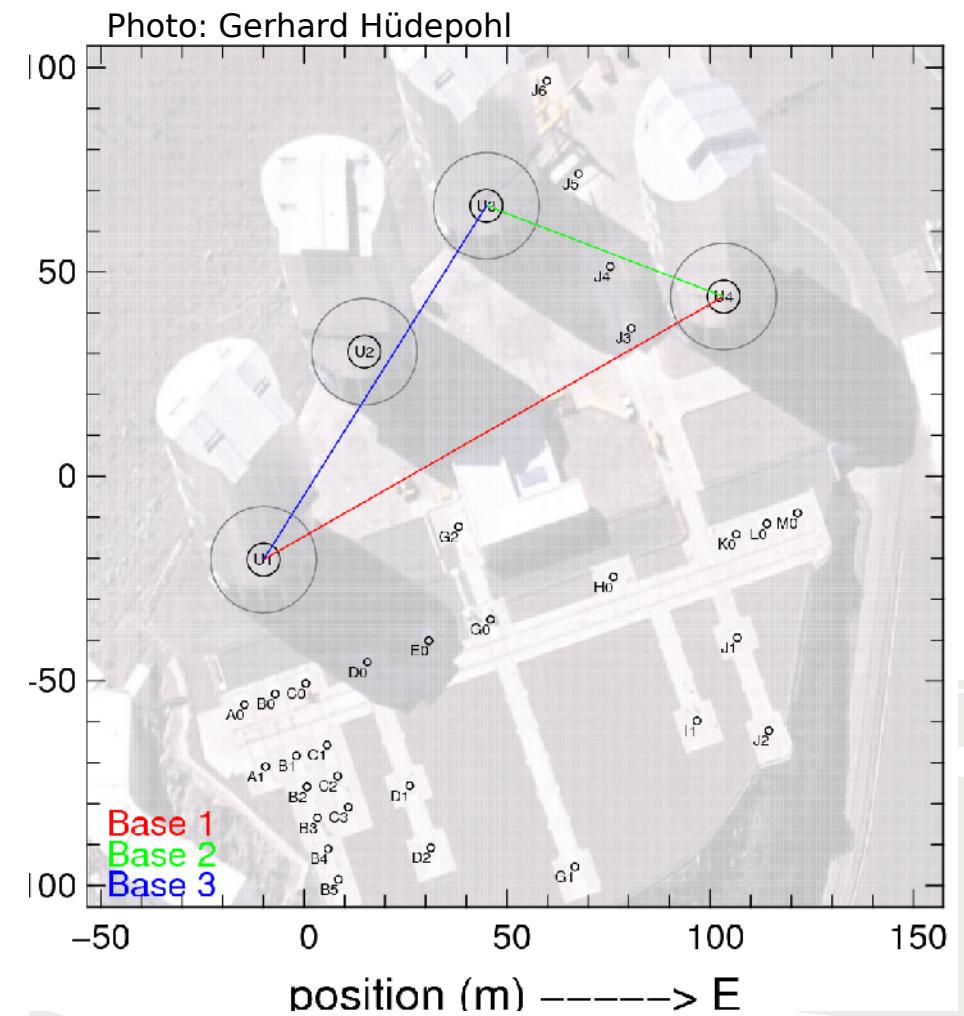
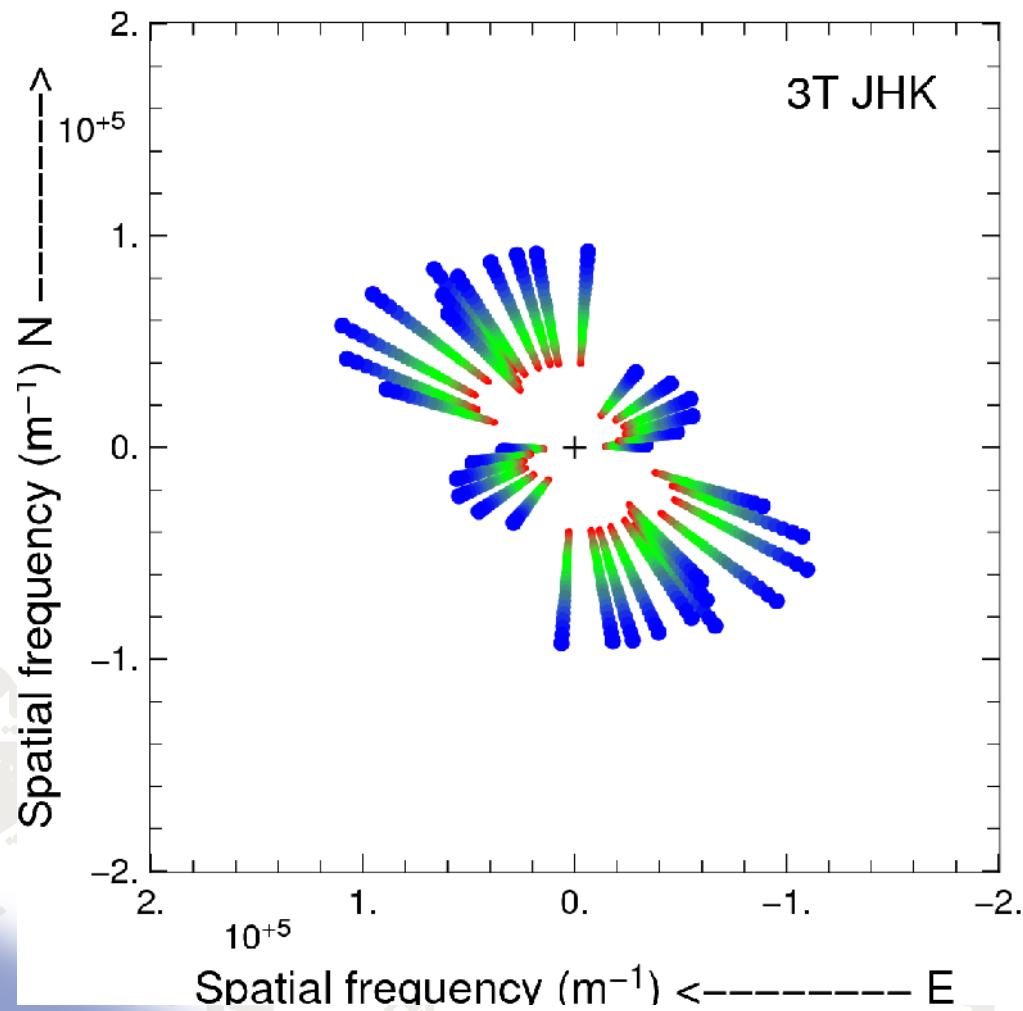
=> You scan different spatial frequencies at different wavelengths for a given baseline (achromatic object) !



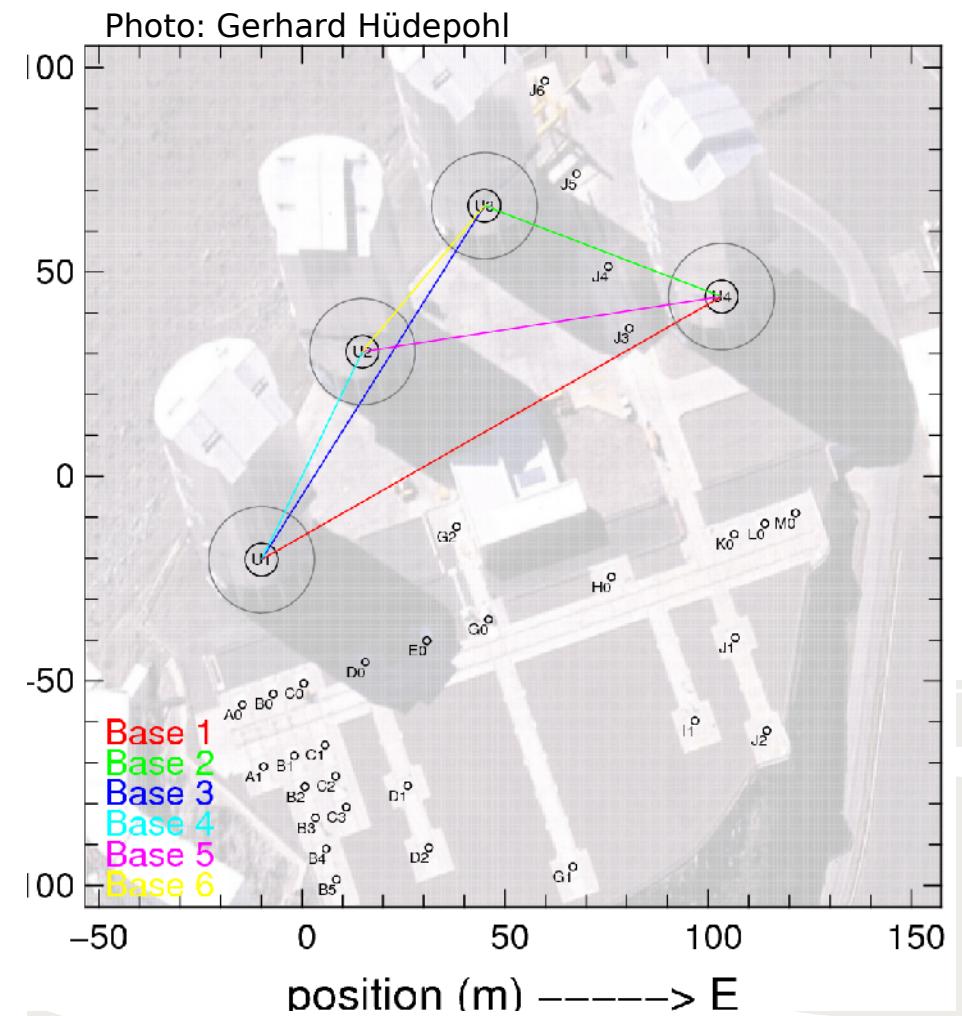
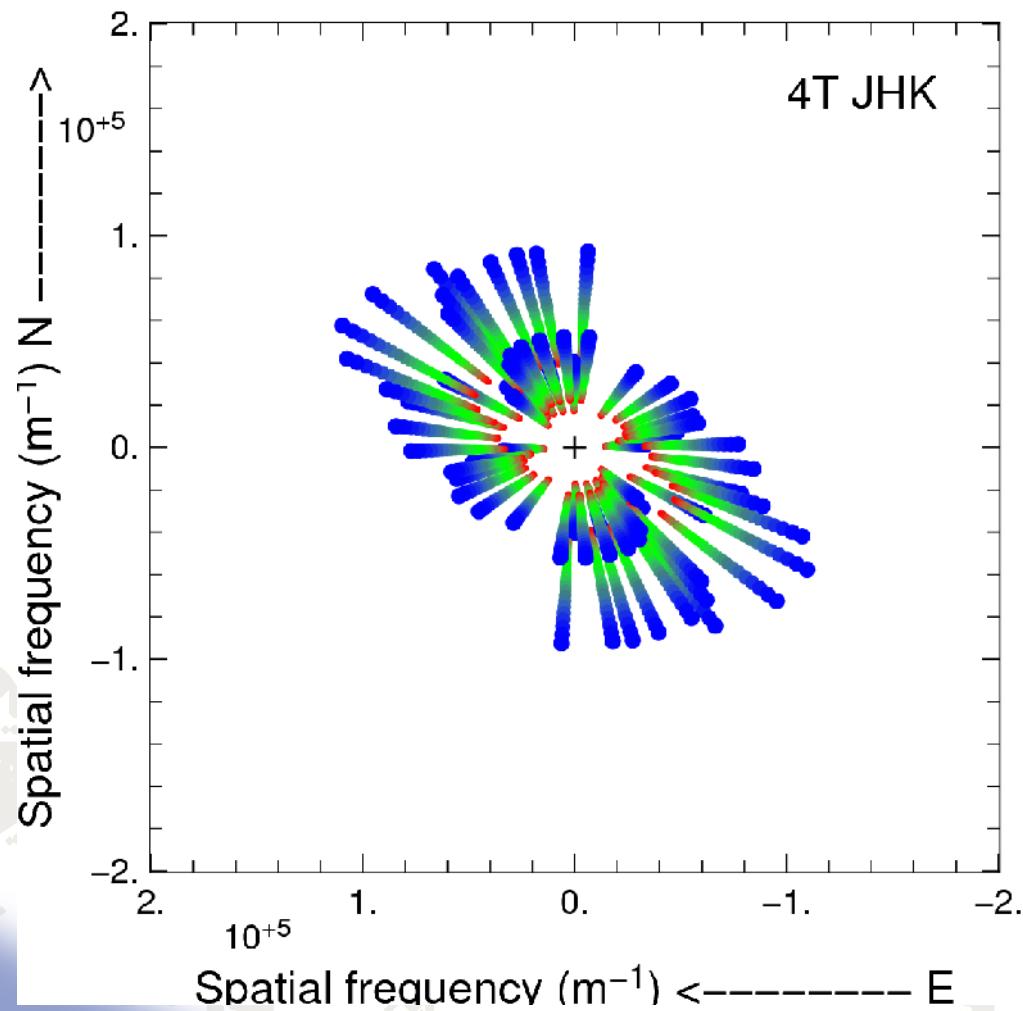
Supersynthesis + spectral coverage (2T)



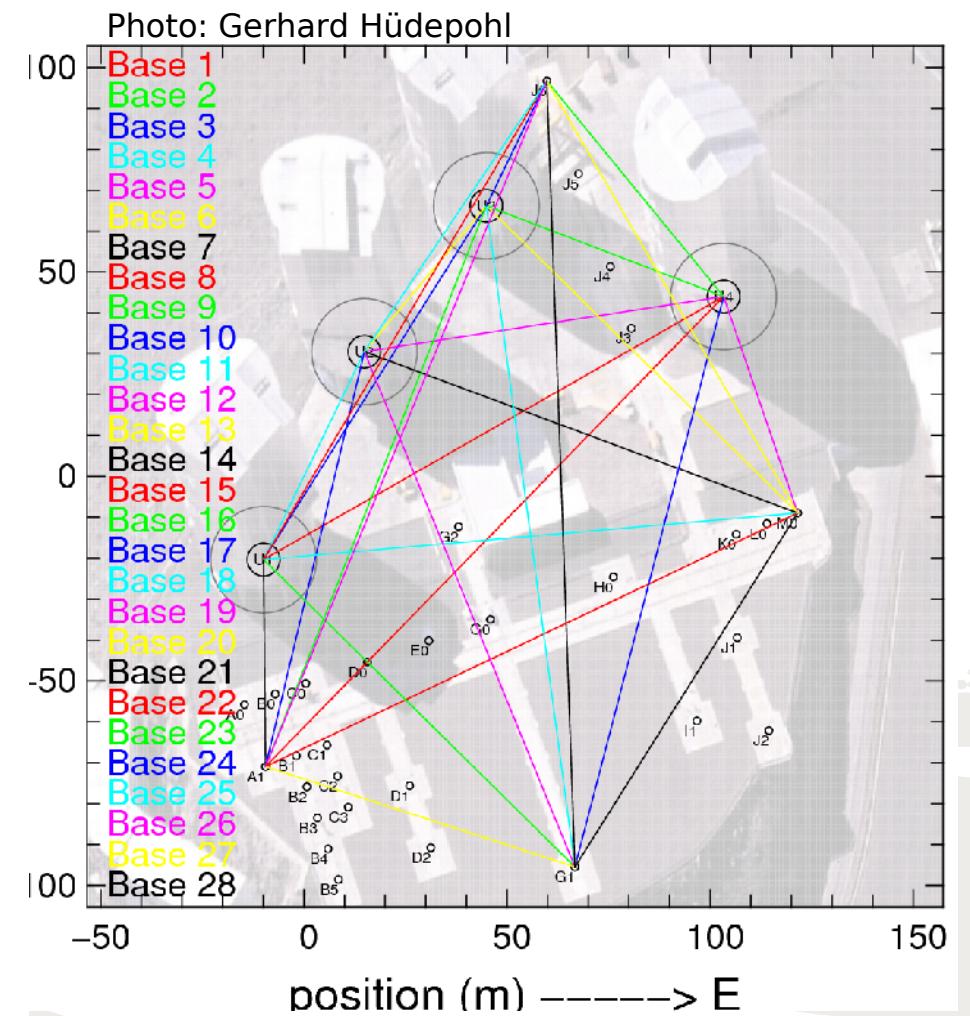
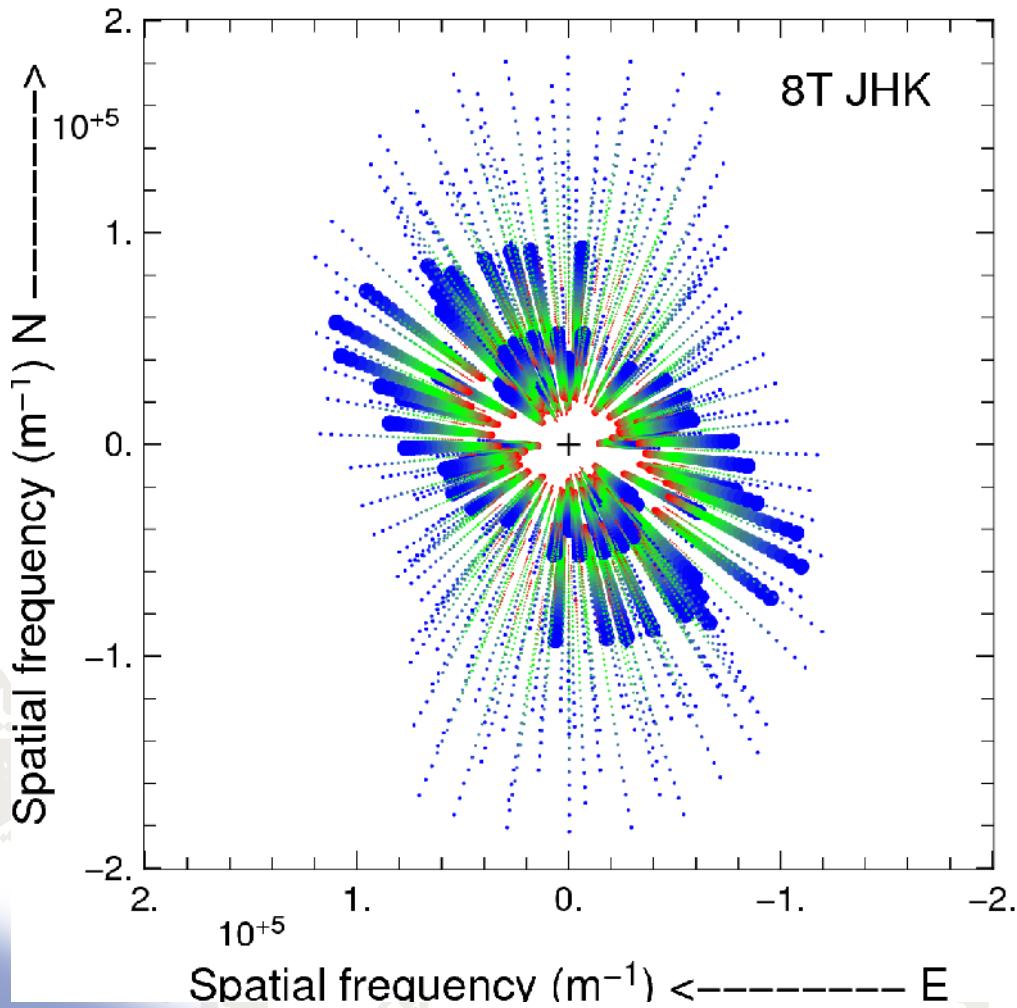
Supersynthesis + spectral coverage (3T)



Supersynthesis + spectral coverage (4T)



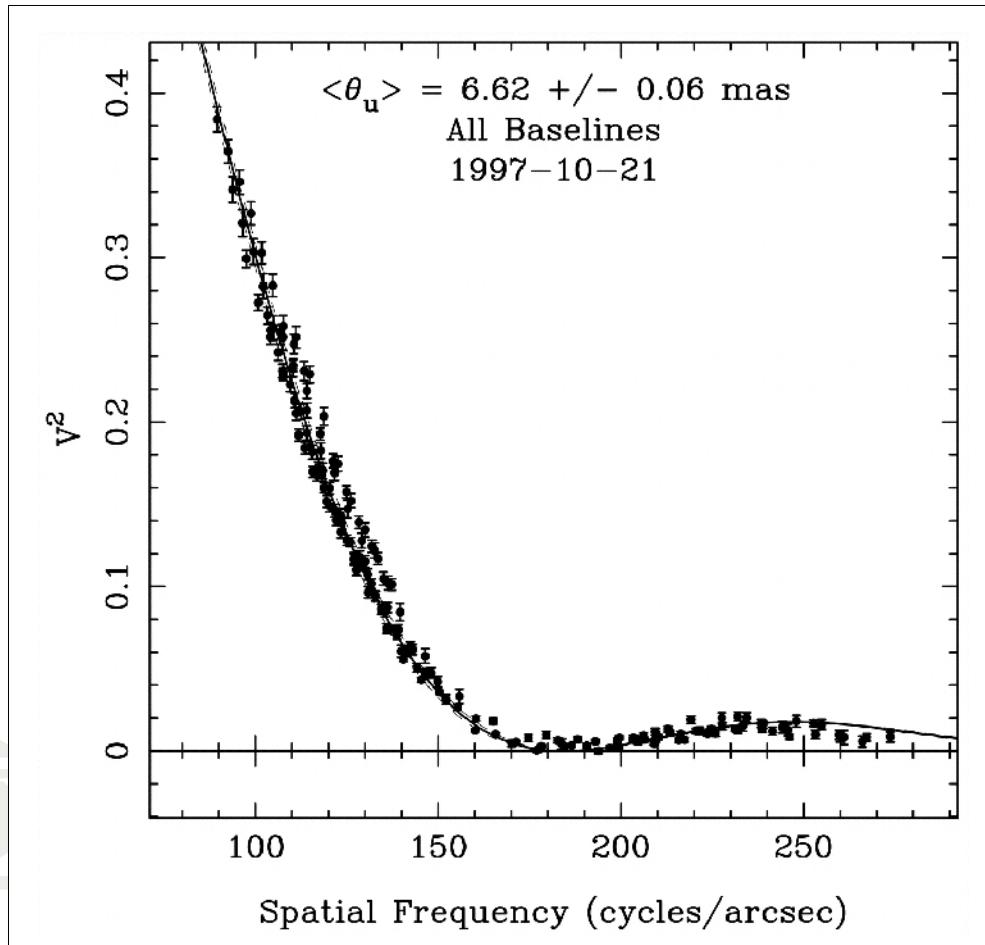
Supersynthesis + spectral coverage (8T)



What is an appropriate UV-plane sampling?

- Well, it depends ...
- on **the object you are observing**
 - angular size of the source
 - simple vs. complex source
 - model fitting vs. image reconstruction
- on **the instrument you are using**
 - accuracy on visibilities
 - spectral resolution

Example (1)



γ Aql, Germain et al. 1999

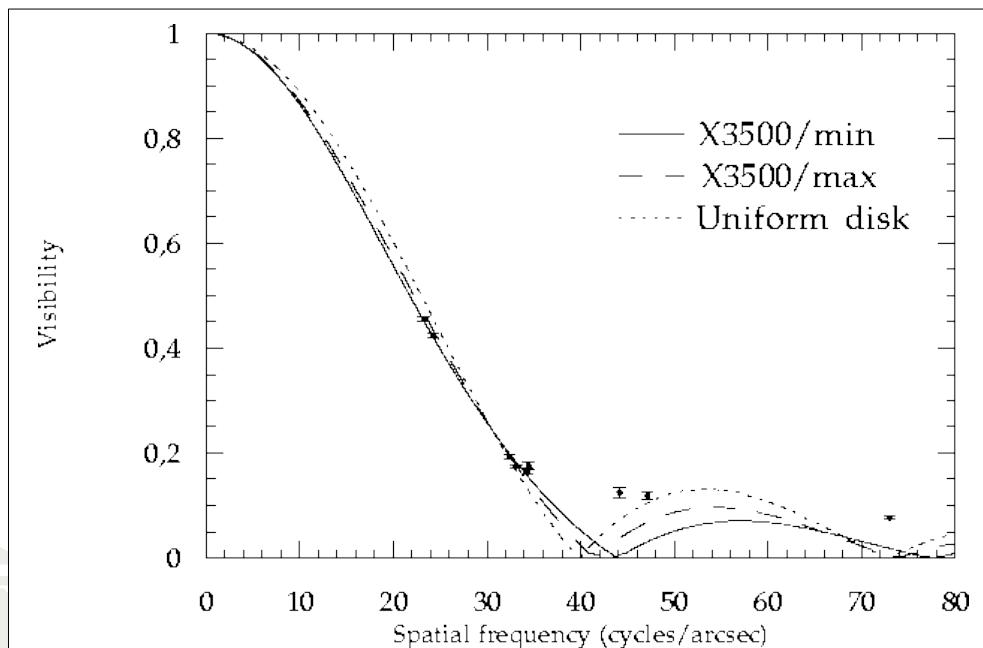
Radius measurement
with NPOI

- N telescopes > 2
- accuracy on $V^2 > 1\%$
- big UV coverage
- use of spectral resolution to improve UV coverage

Example (2)

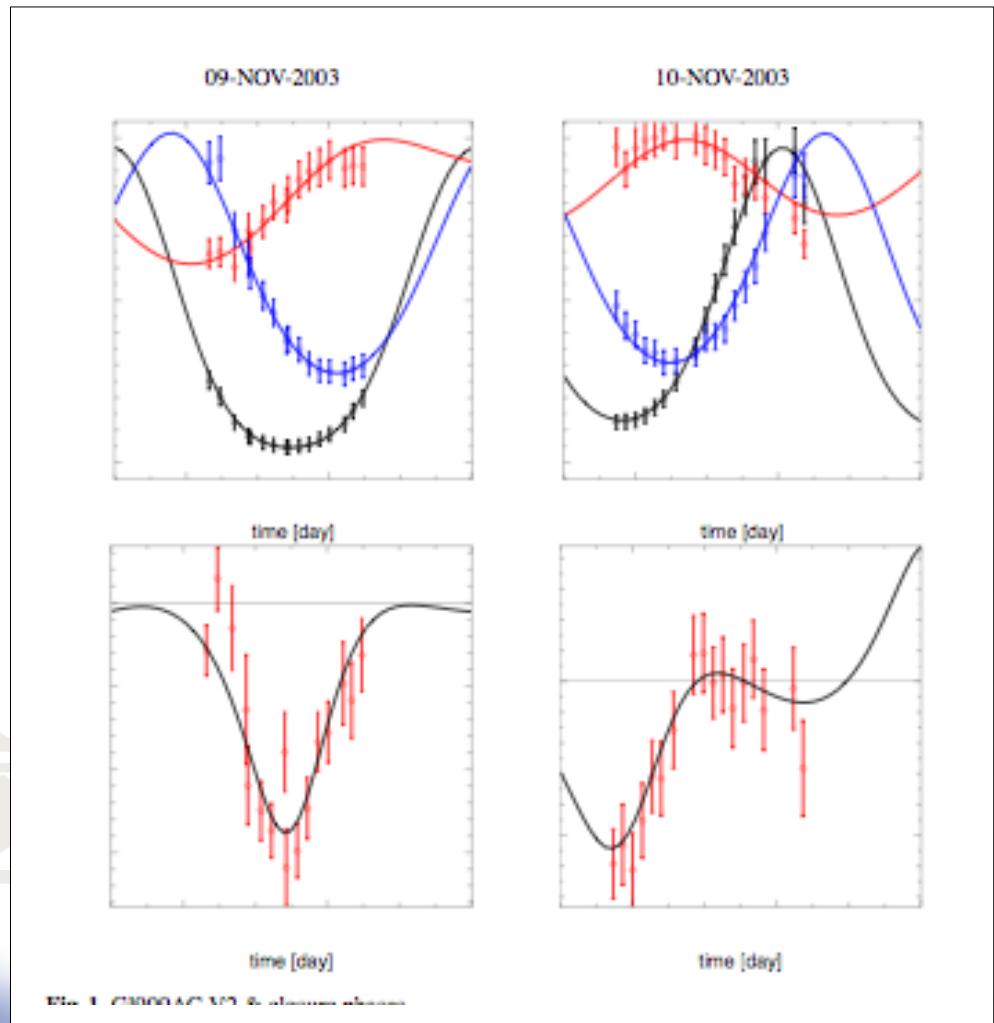
Radius measurement
with IOTA/FLUOR

- N telescope = 2 (at that time)
- accuracy on $V^2 \ll 1\%$
- poor UV coverage but ... a few points at the right place do the job



R Leo, Perrin et al. 1999

Example (3)

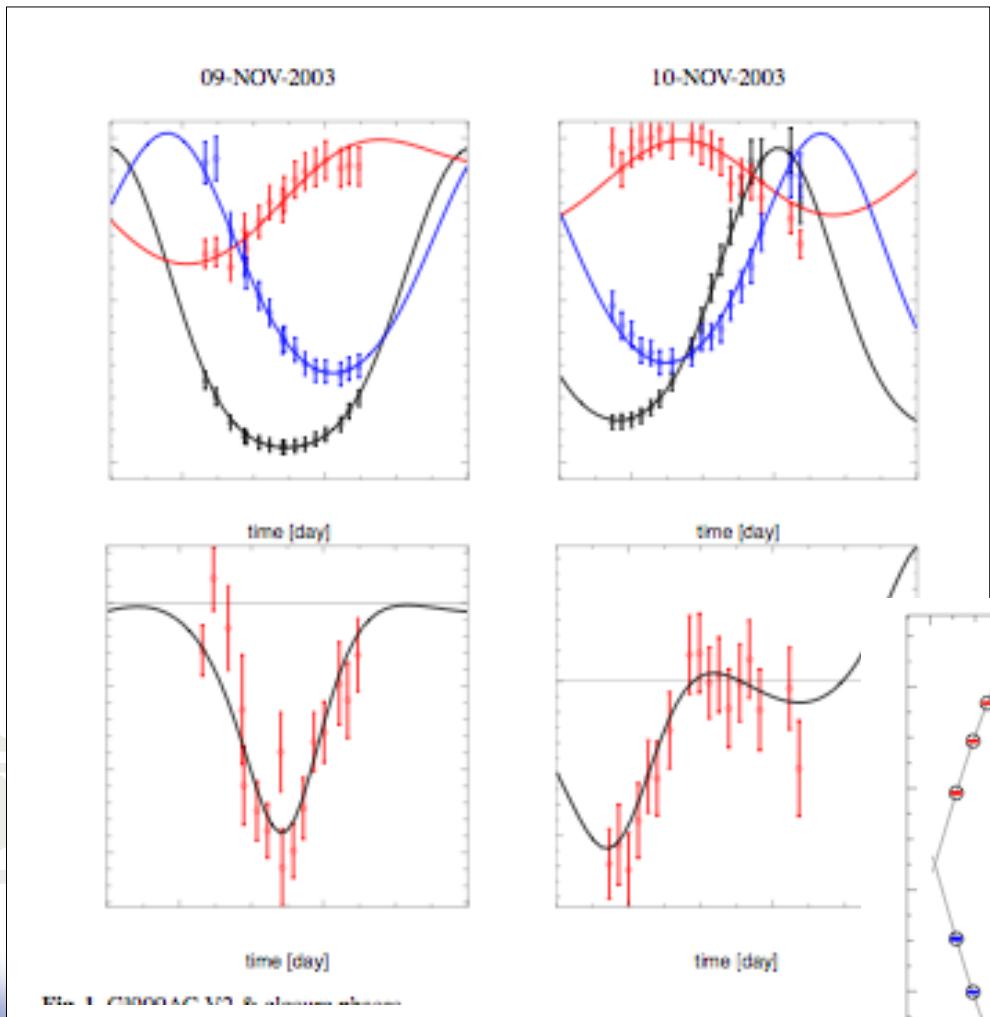


Segranson 2006 (Goutelas)

Binary star observation with IOTA

- accuracy on $V^2 > 1\%$
- limited UV coverage

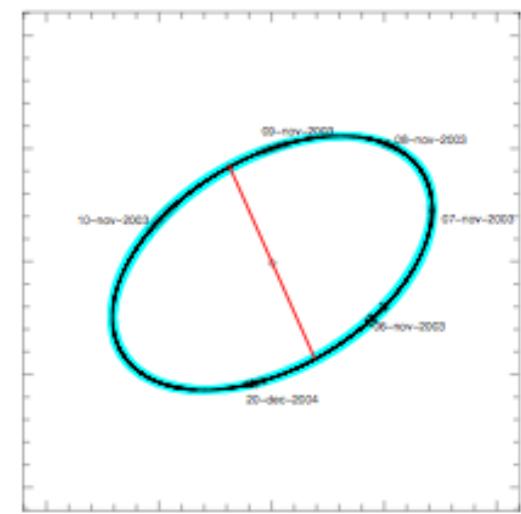
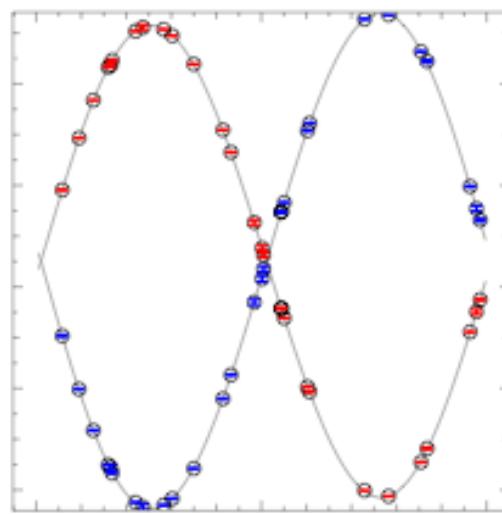
Example (3)



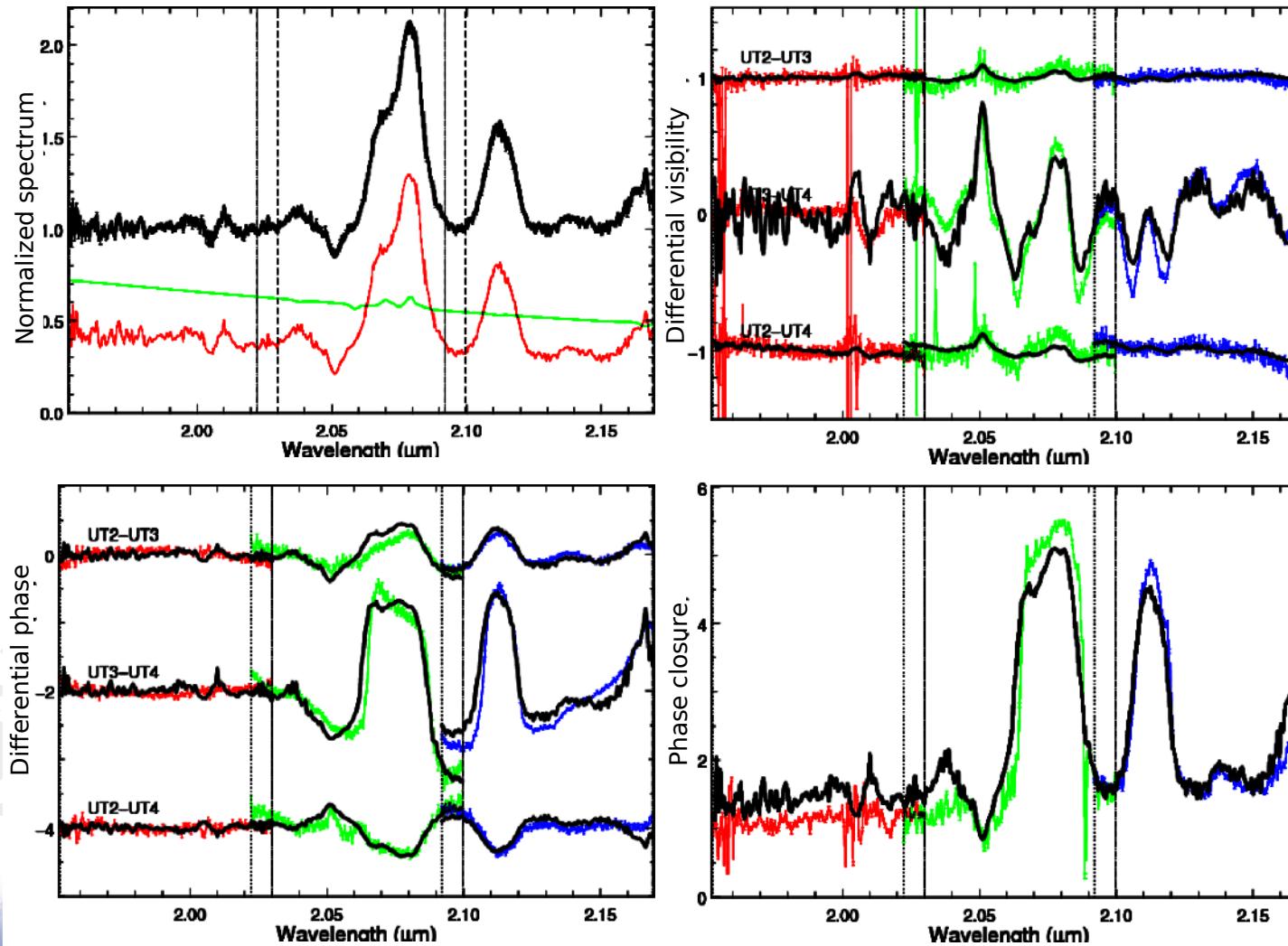
Segransan 2006 (Goutelas)

Binary star observation with IOTA

- accuracy on $V^2 > 1\%$
- limited UV coverage
- but ... binary observed at different orbital phases
- and ... radial velocities



Example (4)



γ^2 Vel, Millour et al. 2007

**Very poor
(u,v) coverage
(1 snapshot),
but ...**

**Spectrally
varying flux
ratio makes it
working !**

What is an appropriate (U,V)-plane sampling?

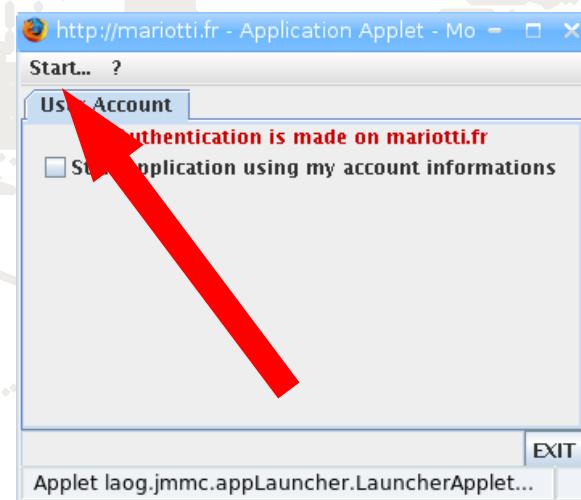
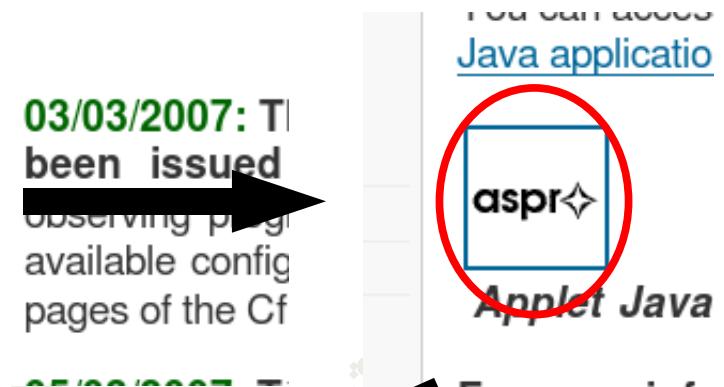
There is no simple answer.

This is why ASPRO
was created

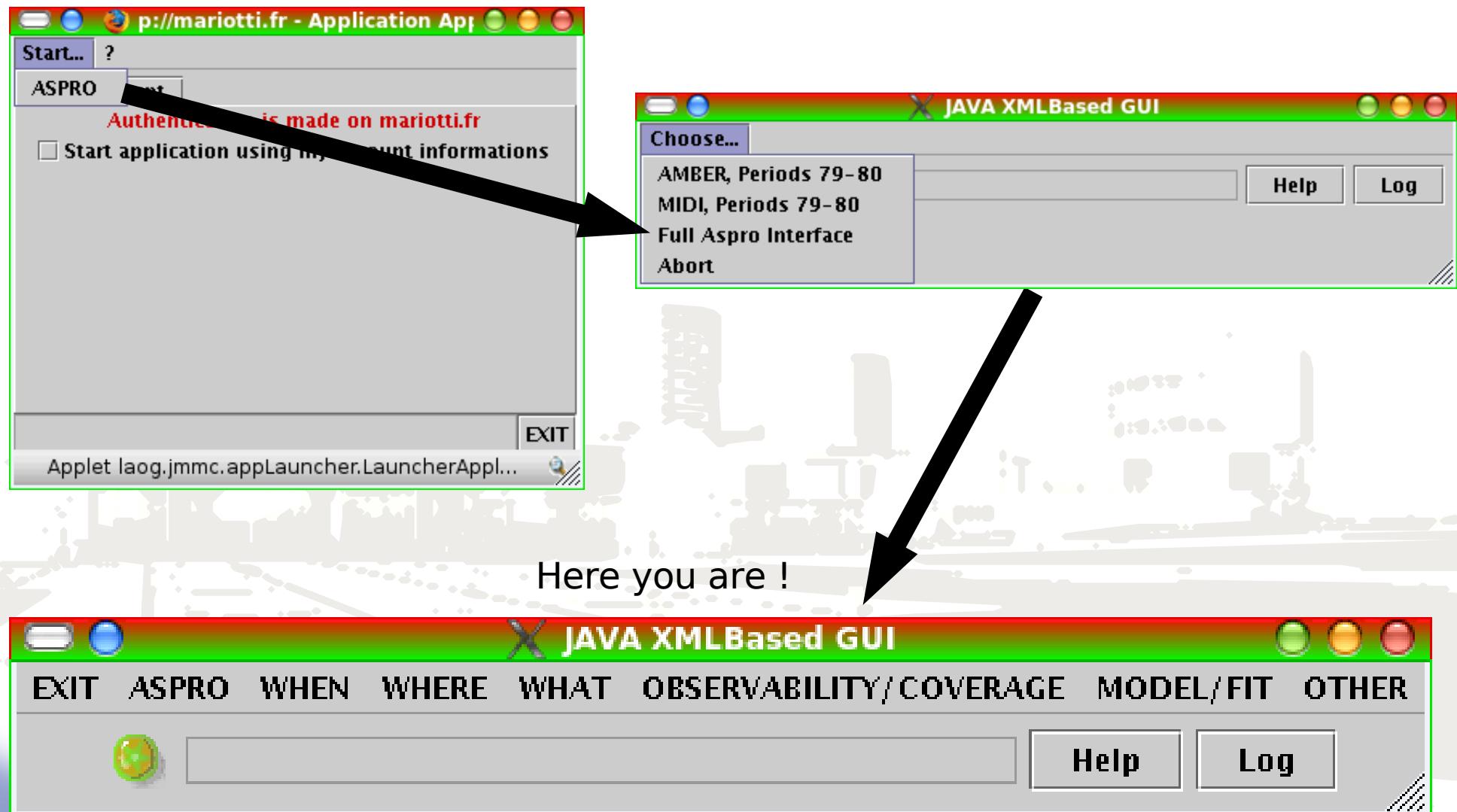


How to launch ASPRO (on the web)

- Start your favourite browser



How to launch ASPRO (on the web, continued...)



How to launch ASPRO (local installation)

