

# The PRIMA Fringe Sensor Unit: Operating Principle and Calibration Procedure

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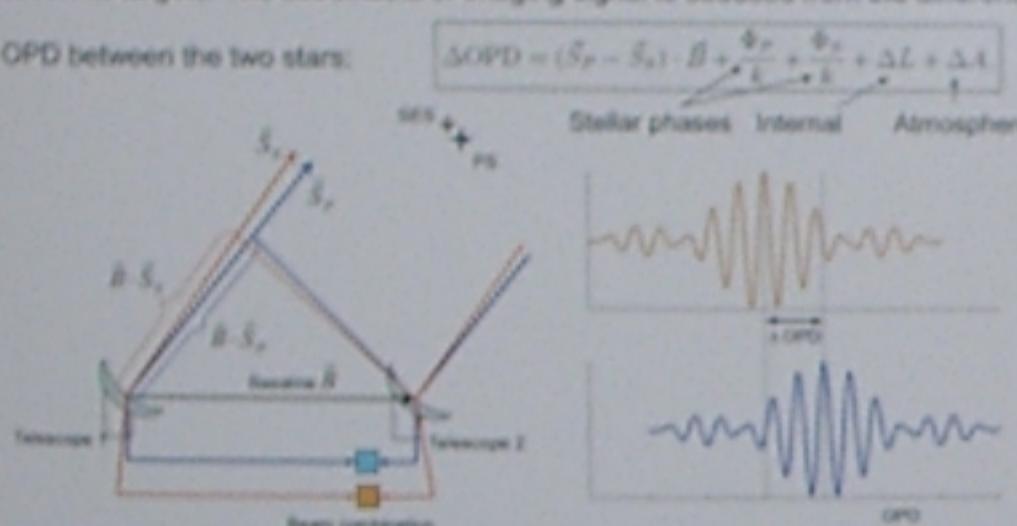
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## Introduction

The ESO Very Large Telescope  
Interferometer<sup>1</sup> (VLTI),  
future host of PRIMA,  
the Phase Referenced Imaging and Micro-arcsecond Astrometry facility<sup>2</sup>.



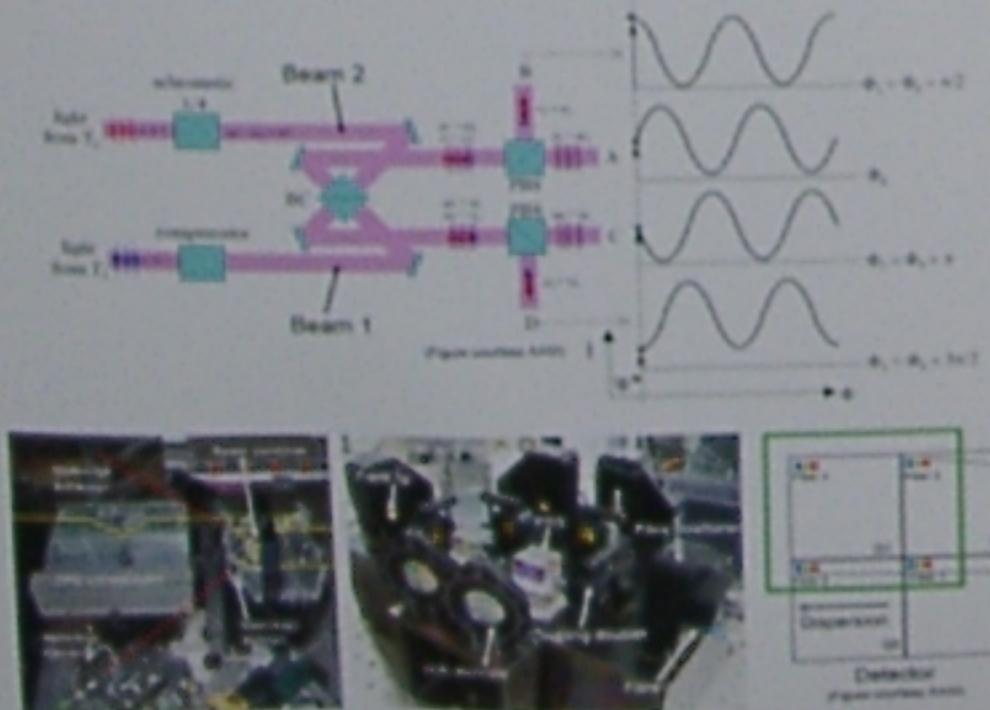
The Fringe Sensor Unit<sup>3</sup> (FSU) is the central element of the PRIMA dual-beam facility. The stellar beams are combined in the FSU, which both produces the scientific data and provides the fringe tracking signal. The FSU delivers estimates of optical path difference (OPD), group delay (GD) and fringe visibility for the two observed targets. The astrometric or imaging signal is deduced from the differential OPD between the two stars:



## Layout and principle



- The FSU operates in the infrared K-band and beams are combined in bulk optics
- Spatial phase modulation of input beams to create ABCD channels separated by 90°
- Spatial filtering with single-mode fibres that route the light to the cold camera
- Cryogenic infrared camera with dispersive element to obtain 3 spectral channels



## The PRIMA Fringe Sensor Unit



The two fringe detectors FSU A and FSU B are identical and share the cryostat for their cold optics and detectors. Each unit combines two stellar beams originating either from the primary star or the secondary star.

## OPD and GD algorithms

- The phase delay is computed from the central spectral channel with a modified ABCD algorithm, that takes the phase shift errors into account:

$$\tan \phi = \frac{(I_A - I_C) \gamma - (I_B - I_D) \alpha}{(I_B - I_D) \beta - (I_A - I_C) \delta} \quad \text{OPD} = \frac{\lambda}{2\pi} \phi$$

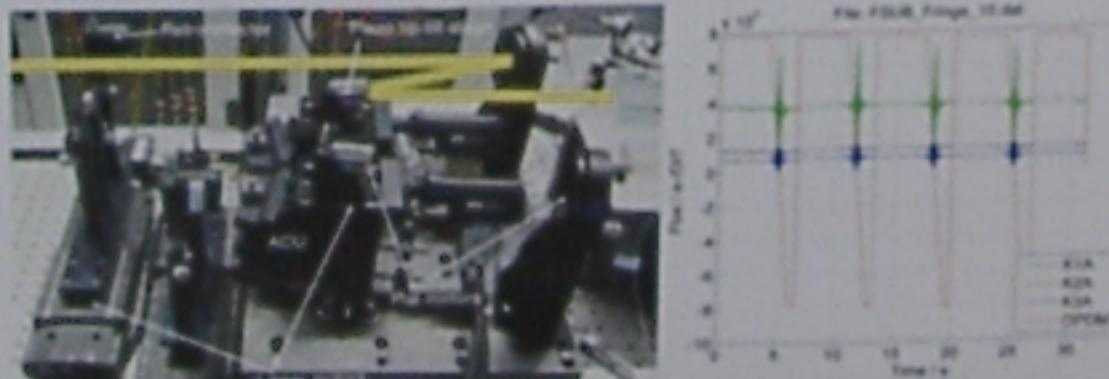
- The Group Delay is derived from the phase delays in the two exterior spectral bands:

$$\text{GD} = \frac{1}{2\pi} \frac{\lambda_3 \cdot \lambda_1}{\lambda_3 - \lambda_1} \cdot (\phi_3 - \phi_1)$$

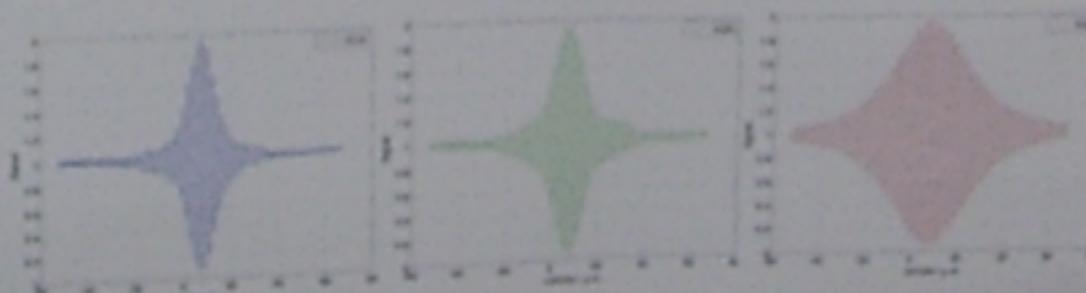
- The parameters that need to be derived from the calibration are the effective wavelengths  $\lambda$  and the phase error coefficients  $\alpha, \beta, \gamma, \delta$  in the 3 spectral channels.

## Calibration Procedure

- Fourier Transform Spectroscopy is used to derive the effective wavelengths
- Several OPD scans over the fringe packet are performed with a linear motor while the FSU fluxes and the internal OPD (measured with the internal metrology) are recorded simultaneously

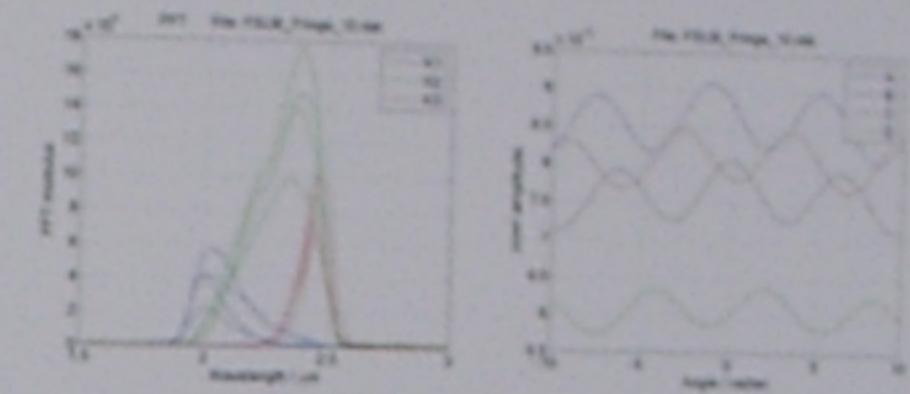


- The obtained fringes are collapsed, resampled and smoothed



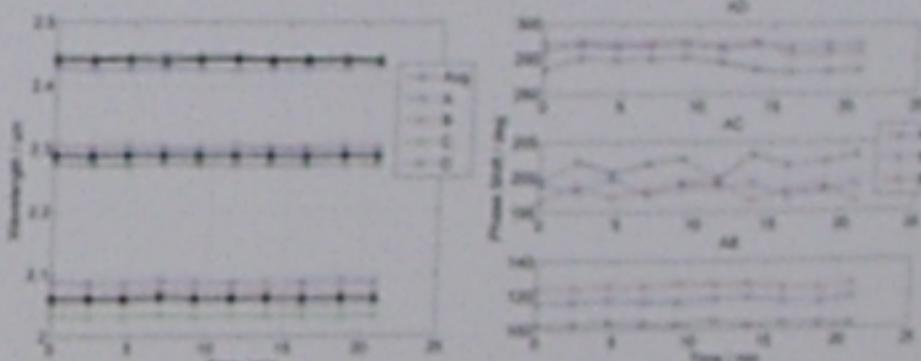
## Parameter Computation

- Each fringe packet is Fourier transformed and the effective wavelengths are computed from the barycentre of the FFT modulus
- The phase shifts are derived from the crosscorrelation of the fringe packets with respect to the channel A fringes

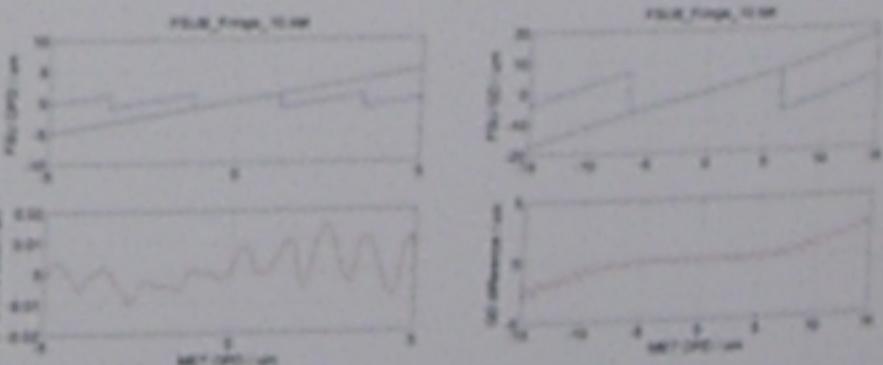


## Results

- Parameter stability over 10 consecutive calibrations:
  - Effective wavelength PTV variation is below 4 nm
  - Phase shift variation PTV variation is below 4°



- OPD measurements show low deviation from expected values, the derived linearity is good (<10%)
- GD measurements exhibit large cyclic errors, linearity is not satisfactory



## Conclusions

A calibration procedure for the FSU is established and methods to derive the calibration parameters are presented. The OPD measurement capability of the calibrated FSU is found to be satisfactory. In contrast, the GD estimations exhibit large errors. Both the GD algorithm and the calibration procedure need to be improved.

## References

- M. Schöller et al., "Recent progress at the Very Large Telescope Interferometer", Proc. of SPIE, vol 6268, 2006
- F. Delplancke et al., "PRIMA for the VLTI: a status report", Proc. of SPIE, vol 6268, 2006
- M. Gil et al., "The VLTI Fringe Sensors: FINITO and PRIMA FSU", Proc. of SPIE, vol 5491, 2004

<sup>3</sup>The FSU has been built by Ascatel Alenia Space Italy (AASI)