#### **Observations of Achernar with VINCI**

**EuroSummer School** 

Observation and data reduction with the Very Large Telescope Interferometer

Goutelas, France June 4-16, 2006

P. Kervella Observatoire de Paris 5 June 2006

# Why observe Achernar (α Eri) ?

- m<sub>v</sub>=0.50
- Spectral type: **B3Vpe**
- Teff ~ 15000 K
- Luminosity ~  $3000 L_{\odot}$
- Distance = 44 pc +/- 1 pc
- $M \sim 6 M_{\odot}$ ,  $R \sim 10 R_{\odot}$
- Rotational velocity:  $v_{eq}$ .sin i = 225 km/s

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## Rotational velocity

How do we know the rotational velocity of a star?



Achernar:  $v_{eq}$ .sin i = 225 km/s Sun:  $v_{eq} = 2$  km/s

This very fast rotation distorts the star... but by how much?

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# Flattening... in a simplified way



- A particle at the equator of the star is subject to its weight *P*, the pressure reaction *R* and the centrifugal force *C* created by rotation
- For a given central mass, the flattening is then simply given by (Huyghens approximation):

$$\frac{R_{eq}}{R_{pol}} = 1 + \frac{C}{2P}$$

For the matter to stay on the star, we have C < P, and then  $R_{eq}/R_{pol} < 1.5$ 

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### How can we « see » the effects of Achernar's rotation ?

We need to *resolve* the star...

But it is *extremely* small angularly:  $D = 10 D_{\odot} @ d = 44 \text{ pc gives } \theta = 2 \text{ mas}$ Useful formula:  $\theta [\text{mas}] = 9.305 D[D_{\odot}] / d [\text{pc}]$ 

No single telescope has this resolving power (even ELTs...)

### Long baseline interferometry !





## Principle of VINCI



The total VLTI + VINCI photon efficiency is low... 1% ! (22 mirrors in each arm, injection, fibers, filter,...)

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## Data produced by VINCI (and FLUOR)

The raw data consist of 4 signals:

- two photometric signals PA and PB
- two interferometric signals I1 and I2



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### In real time...

~2 to 10 interférograms are produced per second

One observation is typically made of 500 interferograms, or ~5 minutes

A calibrator is observed before an/or after the scientific target



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## Data processing: Normalization

$$I_{1 \text{ cal}} = \frac{1}{2\sqrt{\kappa_{1,A} \kappa_{1,B}}} \frac{I_{1} - \kappa_{1,A} P_{A} - \kappa_{1,B} P_{B}}{(\sqrt{P_{A} P_{B}})_{\text{Wiener}}}$$
$$I_{2 \text{ cal}} = \frac{1}{2\sqrt{\kappa_{2,A} \kappa_{2,B}}} \frac{I_{2} - \kappa_{2,A} P_{A} - \kappa_{2,B} P_{B}}{(\sqrt{P_{A} P_{B}})_{\text{Wiener}}}.$$





- This first operation allows to remove almost completely the atmospheric corruption of the data
- except the *piston effect*

See G. Perrin's course next week

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 $I = \frac{I_{1\,\text{cal}} - I_{2\,\text{cal}}}{2} \cdot$ 

this allows to remove most of the correlated noise introduced by the normalization



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## Mesurement of the coherence factor

## Estimator used for VINCI: based on the Fourier transform



 $\Rightarrow$  Value of the squared coherence factor  $\mu^2$ 

#### Transfer Function: the Calibration of the visibility

The efficiency of the interferometer is not perfect, and it does not transmit 100% of the modulation of the fringes

We have to measure this loss to take it into account

For this purpose, we observe a star with a known angular diameter: **the calibrator** 

Knowing the expected  $V^2$  of the calibrator, we can estimate the transfer function  $T^2$ , and correct the squared coherence factor  $\mu^2$  of the scientific target



$$V_{\rm target}^2 = \frac{\mu_{\rm target}^2}{T^2}$$

How to predict the angular diameter of a calibrator ?

Answer Thursday ! (Lecture by A. Boden)

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## From visibility to angular diameter...

We need a model of the light distribution of the star



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# Observations

Achernar was observed with the VLTI in 2001-2002 Interspersed Achernar-calibrator observations

- in order to estimate the VLTI interferometric transfer function
- 4 different calibrators

Two small telescopes (0.35 m aperture), in the *K* band (2.2  $\mu$ m) Two almost orthogonal baselines

60 V<sup>2</sup> mesurements in the K band (over 16 nights)
14 V<sup>2</sup> mesurements in the H band (over 7 nights)

#### Supersynthesis

- Achernar = dec -60 deg  $\Rightarrow$  efficient supersynthesis
- observations at different hour angles
- variable projected baseline

V<sup>2</sup>(B) of Achernar



Obviously, Achernar is not a uniform disk !

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## Supersynthesis



Almost complete azimuth coverage: nice coverage with only 2 baselines !

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 $\theta$  (Azimuth)



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# Differential rotation ?



# Many fast rotating stars...



## A « Bonus » data set...



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Troublesome data...



# Something along the pole ?

The polar visibilities are not in line with the model... There is apparently something extended in this direction (lower V<sup>2</sup>) Let's limit ourselves to the polar and equatorial directions +/- 30 degrees



This is strange... A disk is expected, but along the equator...

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# An « ad hoc » simple model

A uniform ellipse for the star +

an elliptical Gaussian for the extended component (aligned with star)

$$V_{\text{star}}(u, v, \theta_{\text{eq}}, \theta_{\text{pol}}, \alpha_1) = \frac{2 J_1(x')}{x'}$$
  
where  $x' = \pi \sqrt{\theta_{\text{eq}}^2 u'^2 + \theta_{\text{pol}}^2 v'^2}$ .

$$W_{\text{env}}(u, v, \rho_{\text{eq}}, \rho_{\text{pol}}, \alpha_1) = \exp\left[-\frac{\left(\pi \sqrt{\rho_{\text{eq}}^2 u'^2 + \rho_{\text{pol}}^2 v'^2}\right)^2}{4 \ln 2}\right]$$

$$V_{\text{model}}(u, v, \theta_{\text{eq}}, \theta_{\text{pol}}, \rho_{\text{eq}}, \rho_{\text{pol}}, \alpha_1, f) = \frac{V_{\text{star}} + f V_{\text{env}}}{1 + f}$$

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*Contrast CSE-star* ~ 5% *in the K band* 

Most likely explanation: free-free radiation from the polar wind of the star

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#### Fast rotating stars observed by interferometry



## Some references...

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