VLTI: current facility and prospects

EuroSummer School

Observation and data reduction with the Very Large Telescope Interferometer

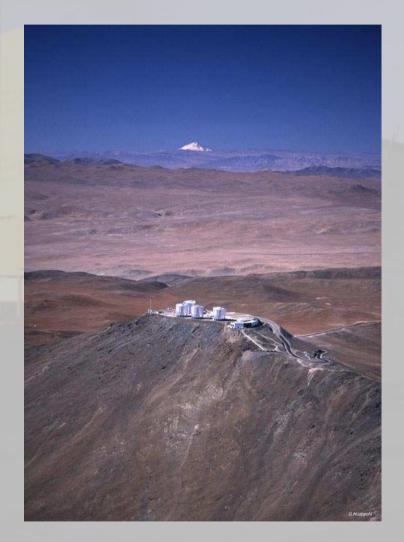
Goutelas, France June 4-16, 2006

Markus Schöller (with input from Jason Spyromilio and Francoise Delplancke, among others at ESO) European Southern Observatory June 09, 2006

A brief history of VLTI

- 1980s Interferometry integral part of the VLT project, early linear array design for UTs goes to trapezium structure
- Early 1990s engineering of the general layout
- 1993 council stalls the VLTI, infrastructure implementation (light ducts, tunnel, lab) continues
- 1996 MPG/CNRS/ESO tri-partite agreement for third AT
- 1997 MIDI and AMBER proposed by community
- 1998 contracts for ATs and Delay Lines awarded, MIDI and AMBER instruments started
- 2000 start of implementation on Paranal (siderostats and delay lines)
- March 2001 first fringes with VINCI on siderostats

VLTI



Four 8.2m telescopes (UTs) All equipped with AO (MACAO) Six Baselines 47m-130m

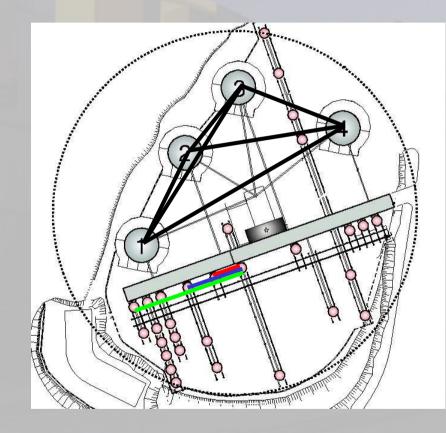
Four 1.8m telescopes (ATs) Movable to 30 stations Baselines 8m-202m

Six delay lines **PRIMA dual feed facility** FINITO fringe tracker IRIS lab tip/tilt tracker MIDI/AMBER/VINCI

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Status

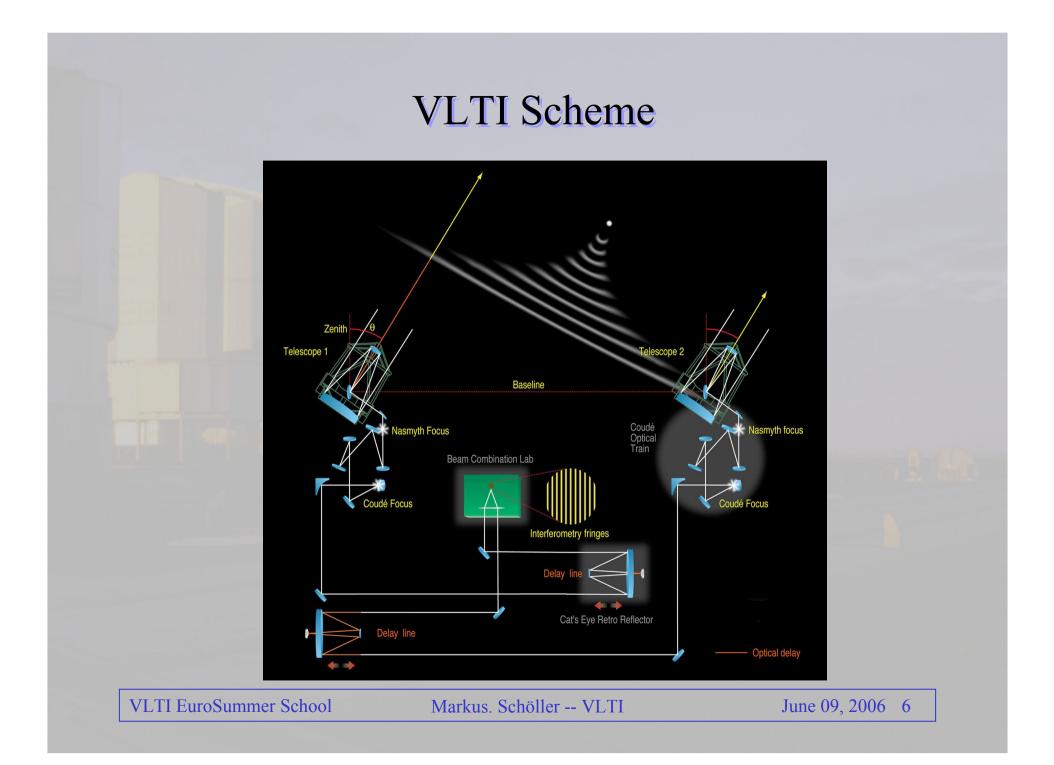


All UTs operational with full AO, all six baselines and all four baseline closures used for science AT1/2/3 in operations on three baselines AT4 will arrive in Aug 2006 4 Delay Lines in operations for UTs, 2 Delay Lines for ATs MIDI offered since April 2004 on UTs and October 2005 on ATs AMBER offered on UTs since October 2005 38+40 nights of VLTI science operations in P76 (Oct 05-Mar 06) Six operations astronomers, three fellows, several TIOs to run VLTI 40+ refereed papers

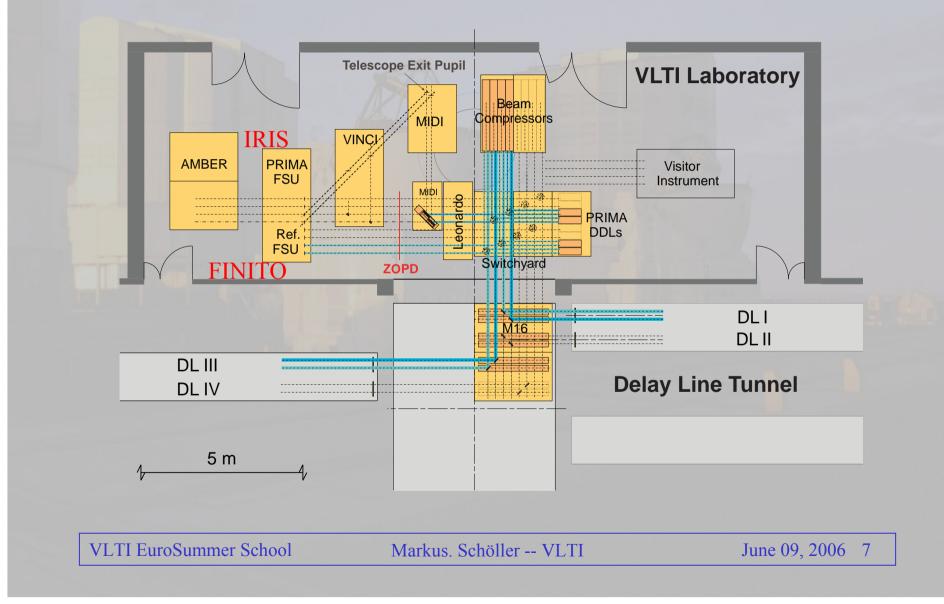
Some acronyms

- OPL optical path length
- OPD optical path difference
- ZOPD zero optical path difference
- UT Unit Telescope (8.2m)
- AT Auxiliary Telescope (1.8m)
- MACAO Multi Application Curvature Adaptive Optics
- STRAP System for Tip-tilt Removal with Avalanche Photo diodes
- VINCI VLT INterferometer Commissioning Instrument
- AMBER Astronomical Multiple BEam Recombiner
- MIDI MID Infrared interferometric instrument
- FINITO Fringe sensing Instrument NIce TOrino
- IRIS InfraRed Image Sensor
- ISS Interferometer Supervisor Software

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The interferometric laboratory



What does the VLTI infrastructure do?

Put the light in the one place at the one time.

- Inject the image plane in the lab
- Make the pupils coincide
- OPD variations should only be atmospheric

How does VLTI do it?

Each UT has a MACAO system that concentrates the bulk of the photons within the Airy ring.

The beam is propagated via the relay optics to the delay lines

The delay lines correct in 'open loop' geometric OPD (telescope and star locations)

The VCMs on the delay lines move the pupil in the 'axial' direction.

IRIS corrects for drifts in the conjugation between the MACAO reference and the lab reference

FINITO corrects for atmospheric OPD variations through the delay lines

The VLTI Telescopes



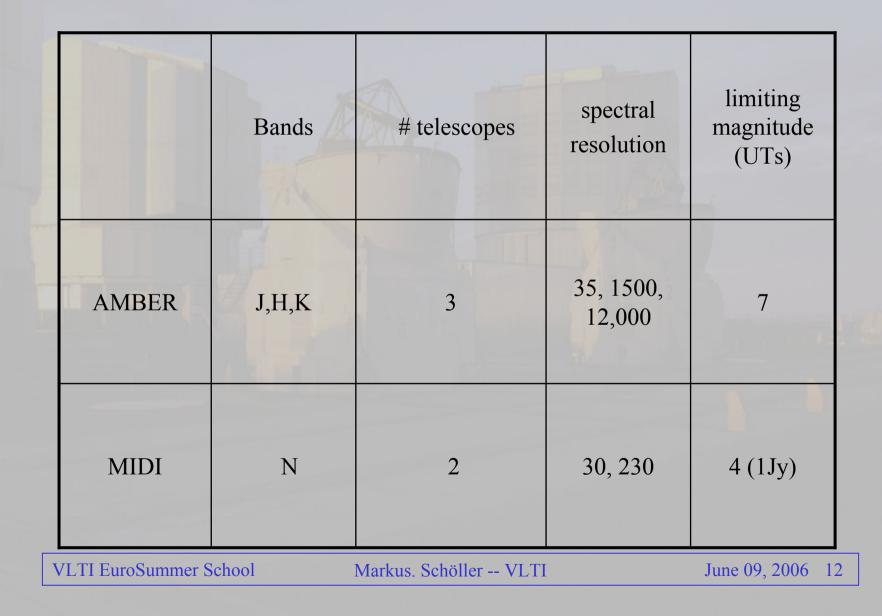
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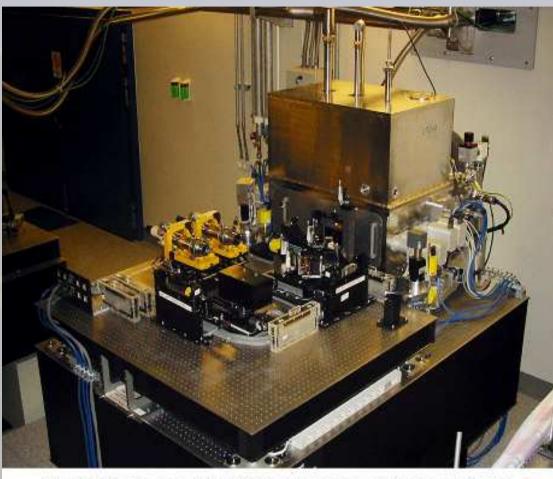
Delay Lines



VLTI 1st gen Science Instrumentation



MIDI in the VLTI lab



The MIDI Instrument at the VLT Interferometric Laboratory on Paranal

ESO PR Photo 30c/02 (18 December 2002)

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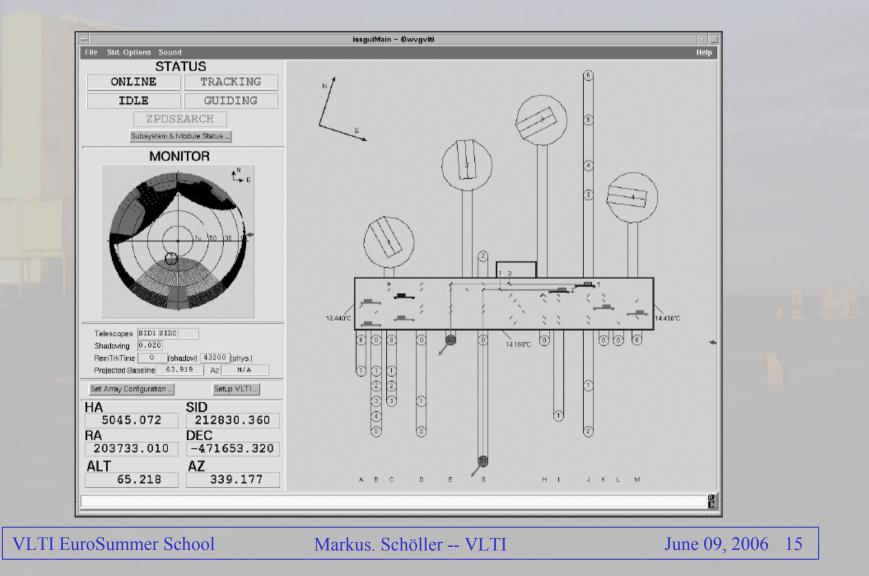
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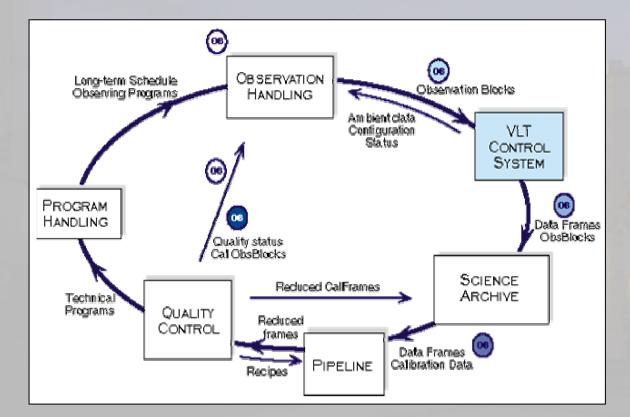
AMBER in the VLTI Lab



Interferometer Supervisor Software



VLTI Operations



VLTI follows the VLT data flow: proposal form, OB preparation and execution, FITS data, archive

Observations performed in Visitor and Service Mode

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VLTI offered modes

- P70 (Oct 2002) VINCI on siderostats
- P72 nothing offered
- P73 MIDI on two UT baselines, prism only, 5Jy
- P74 MIDI on three UT baselines, grism, 1Jy
- P75 MIDI on all UT baselines
- P76 MIDI on three AT baselines
 - science photometry mode
 - slightly better limiting fluxes
 - -AMBER offered on all four UT triples
 - LR-HK, MR-K (low/medium resolution)
- P78 (Oct 2006) AMBER also offered in HR-K
 - reduced overheads on AMBER
- P79 AMBER on AT baselines (?)

Operating the VLT

- One shift leader (24h on call)
- Two day time astronomers (DA) for all UTs plus one for VLTI
- One engineer per UT and VLTI for coordination of daytime access (UT and VLTI managers)
- One night astronomer (NA) per UT single telescope use and one for VLTI
- One telescope instrument operator (TIO) per UT and one for VLTI
- Typically at least one DA or NA in training (e.g. 13 new fellows in 2006, each with at least three weeks of initial training)
- VLT is based on line replacable units (LRU) !!!

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VLTI staff

- Six VLTI support astronomers: Stephane Brillant, Christian Hummel, Sebastien Morel, Fredrik Rantakyrö, Thomas Rivinius, Stan Stefl
- Three + two fellows: Carla Gil, Daniel Kubas, Jean-Baptiste LeBouquin; Emmanuel Galliano, Martin Vannier
- Instrument scientists:
 - AMBER Fredrik and Stan
 - MIDI Sebastien and Thomas

La Silla/Paranal schedule P77 (now)



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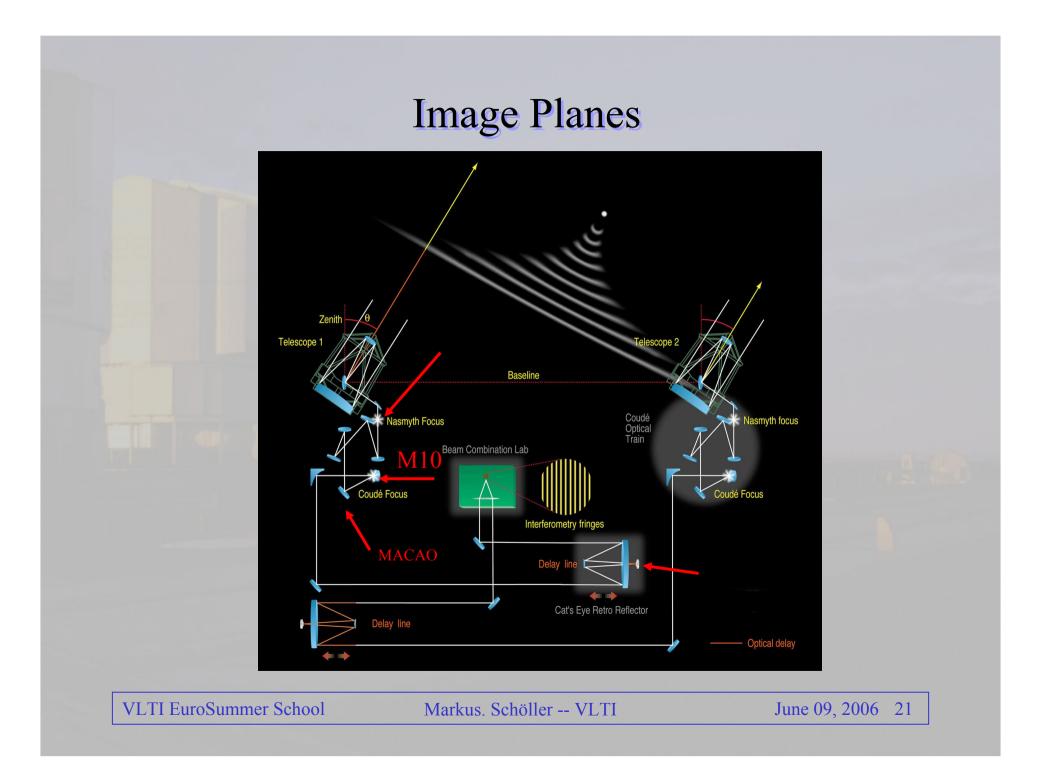
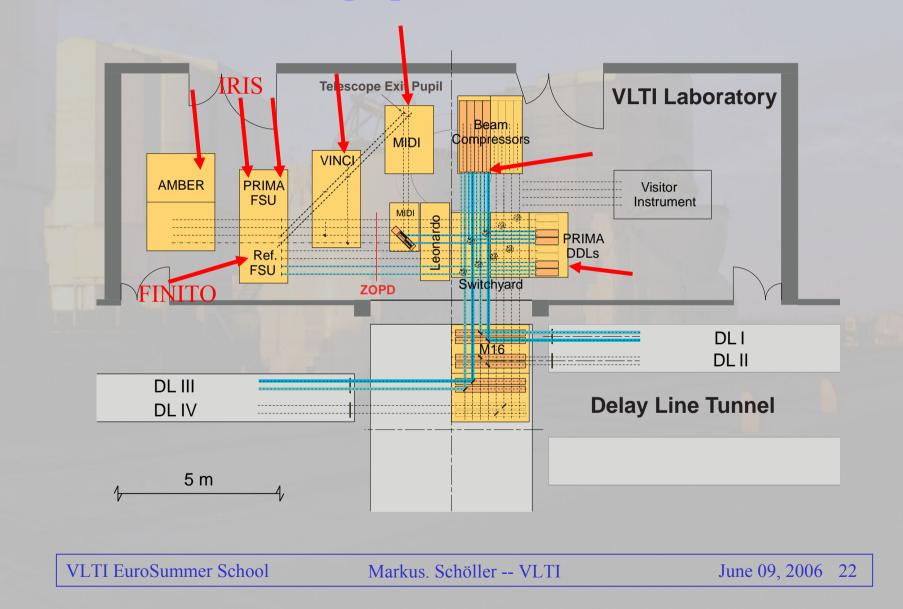
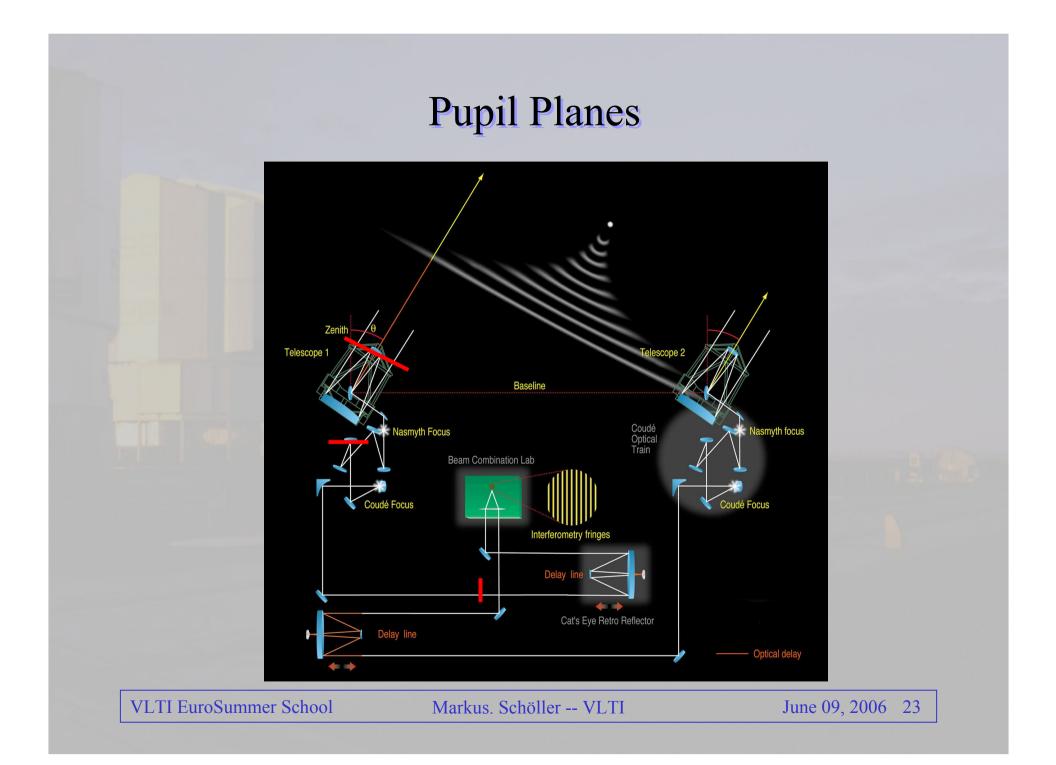
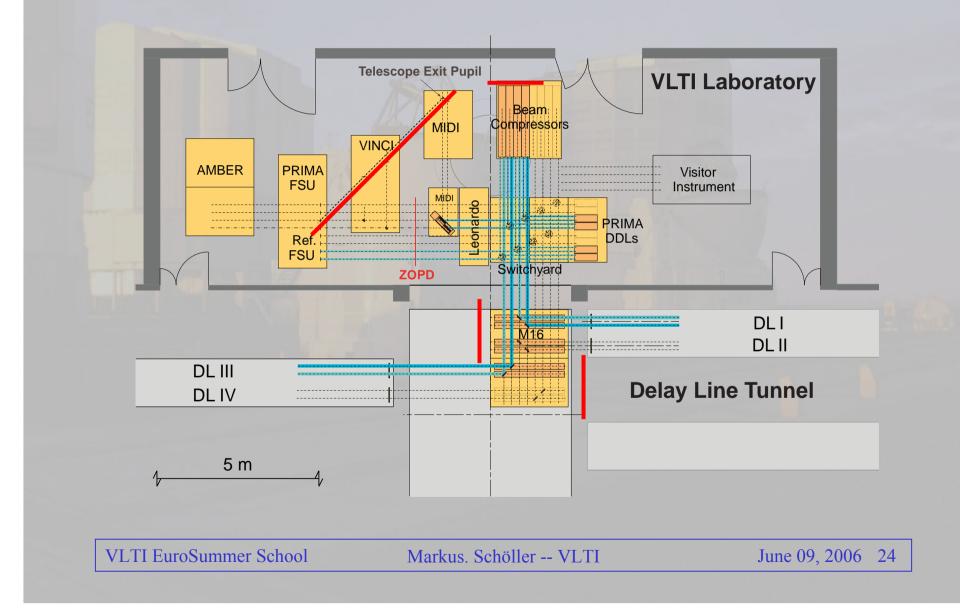


Image planes in the lab





Pupil planes in the lab



Fringe acquisition

- Preset telescopes and delay lines to the positions given by the object coordinates (including proper motions), taking the pointing models of the telescopes and the OPD model of the interferometer into account
- UTs: acquire the Nasmyth focus guide star 30'
- Acquire the Coude guide star on MACAO (UTs) or STRAP (ATs) 2'
- Acquire the science object on IRIS 2"
- Acquire the science object on AMBER or MIDI (includes chopping)
- Search for the fringe by modulating the OPD in small steps around the ZOPD

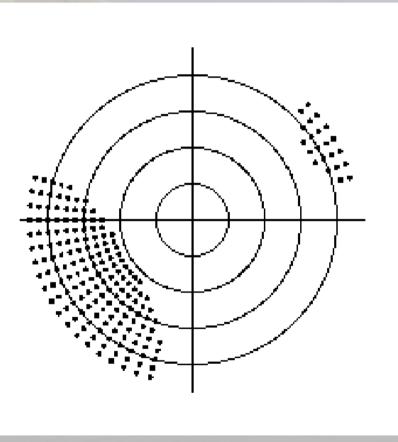
Sending image offsets

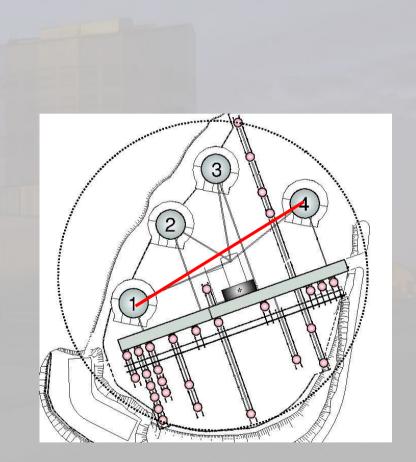
- AMBER sends an OFFSGUV (offset guide probe in UV (ie ground) coordinates) to ISS
- ISS forwards this command to IRIS, IRIS modifies its reference pixel
- IRIS sees that the guide star is not at the new reference pixel and sends an offset to the telescope main guider, eg on a UT the MACAO system
- This offset is applied to the xy-table which holds on top the MACAO curvature sensor
- The MACAO sensor sees that the star is moving away from its central reference point and will counteract by sending a command to the M8 tip/tilt stage,
- If the M8 tip/tilt stage is getting into its operational limit, it will offload the tip/tilt to the M2 mirror

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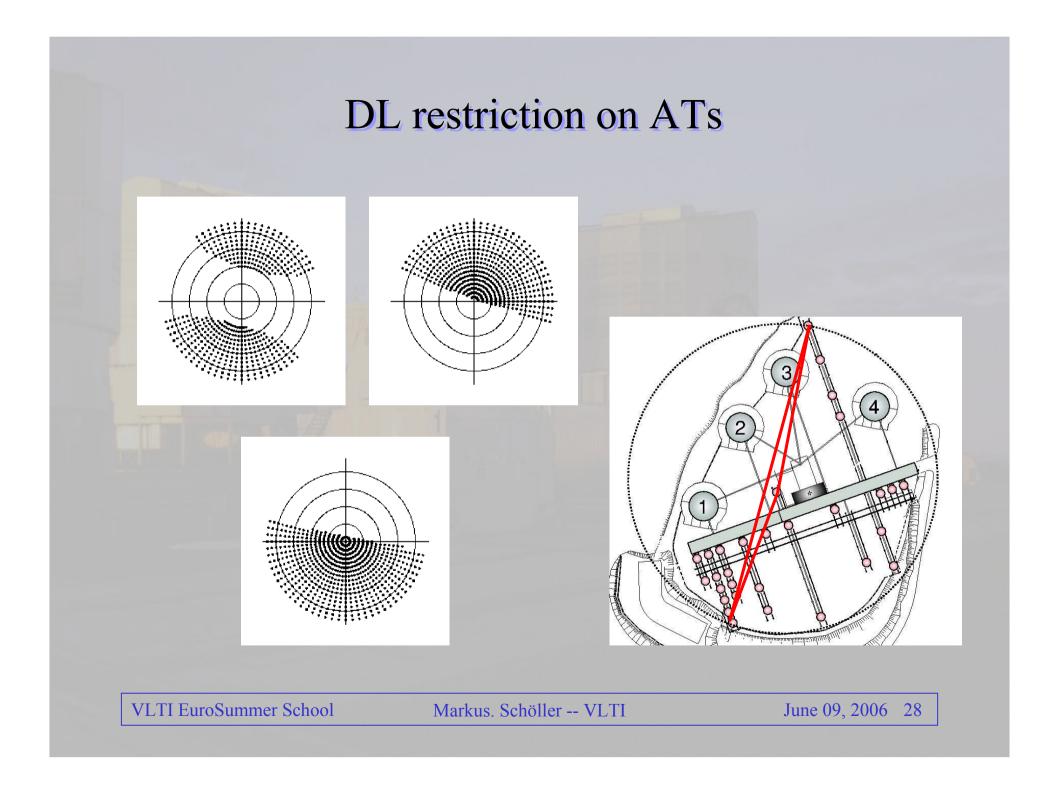
DL restrictions on UT1/4





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Dec 2004 VLTI Review results and actions

In late 2004 ESO held a review of the existing VLTI infrastructure to establish its performance, operability, maintainability, and capability to host PRIMA.
Although scientifically successful the VLTI infrastructure required certain subsystems to be brought to robust operation and some others to be fully commissioned to streamline the operations and allow further deployments.
In particular, before PRIMA deployment and second generation instrumentation we would need to know that we can fringe track.

Paranal accepted the infrastructure and launched the Interferometry Task Force (ITF) in Apr 2005 to seek the understanding necessary to make improvements to the system.

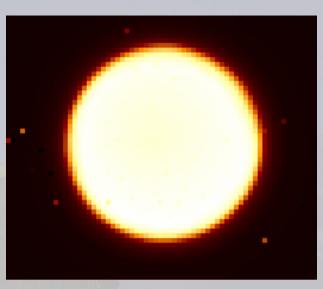
Focus: BFQ - the Big FINITO Question, i.e. fringe tracking on the UTs.

Delay Lines

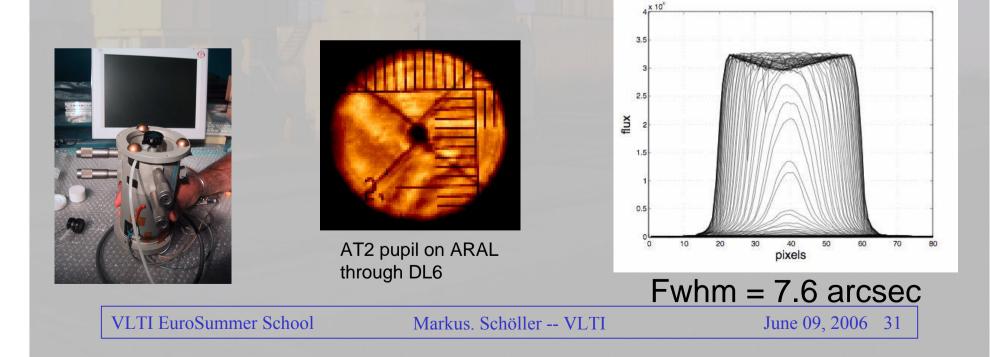
Align the Delay Line rails to better than 20µm and develop a maintenance plan for the alignment.
Install and control the Variable Curvature Mirror in the Delay Lines to allow control of longitudinal pupil position.
Ensure glitchless operations.

VCMs

Without the VCMs functioning the field of view of the ATs is limited to an arcsecond or so (approx the diffraction limit of a 1.8-m telescope at 10 microns).



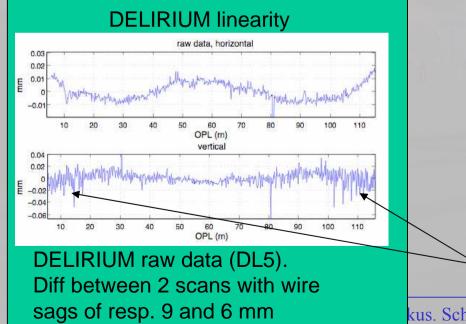
J moon in IRIS



Delay Lines : DELIRIUM



two 2D capacitive sensors (+water pots for earth horizon referencing)
One inclinometer for roll measurement
Metrology (laser or coarse)
Complete trajectory reconstruction



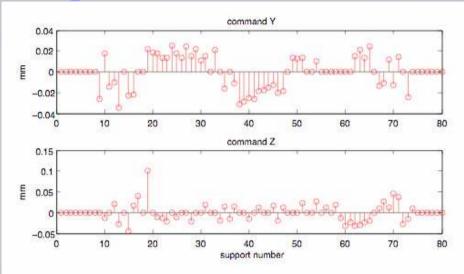
Weird, but goes away with laser metrology (TBC)

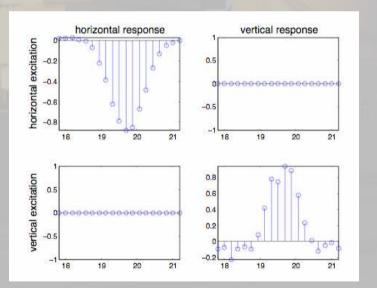
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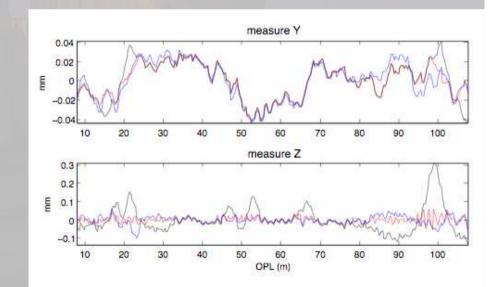
DL rail shape control

Closed loop control based on global reconstruction

- Influence function measurements (on one support)
- Construction of IM / CM (assuming same response on all supports)
- Scan results multiplied by CM to produce correction sequence (control gain = 1)
- Corrections clipped to 10% of max error (or 5 microns ~ limiting accuracy)



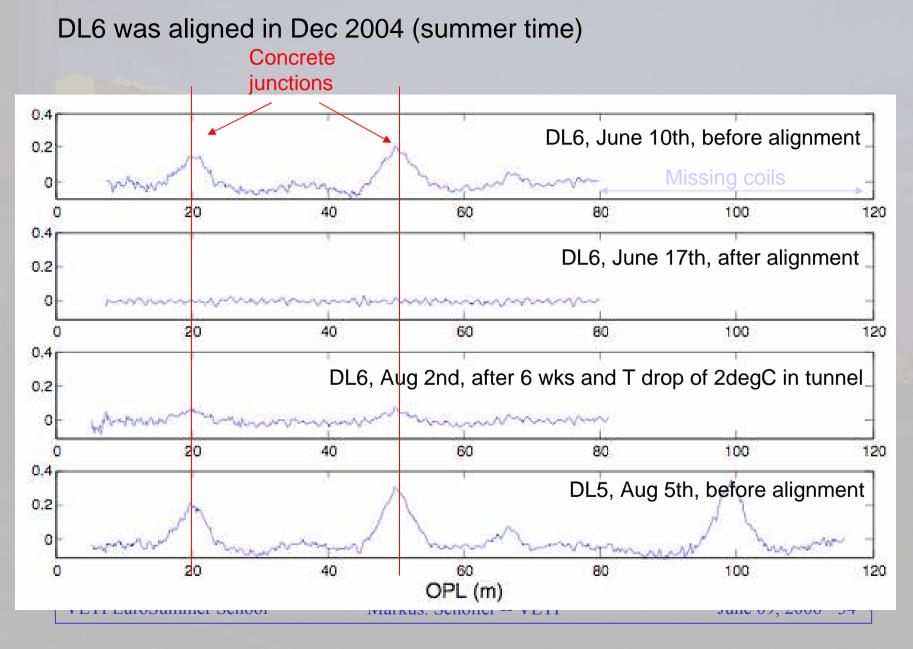




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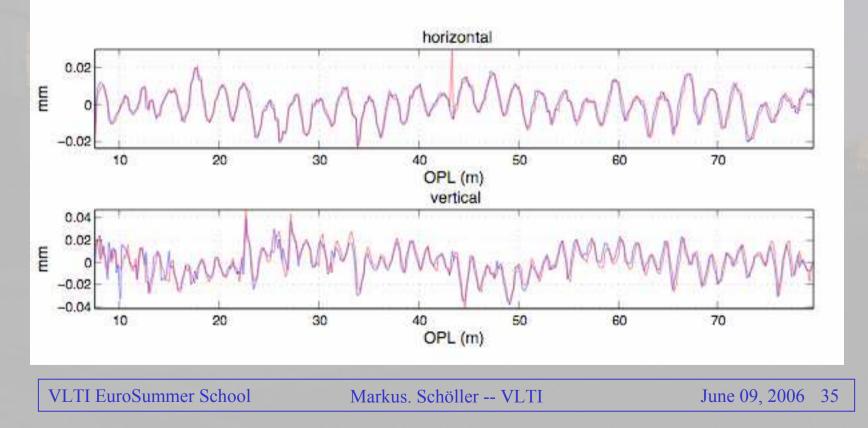
DL rail drift



Iquique Earthquake

June 13th, 22:44 UT (during rail alignment campaign) Richter 7.9 Distance 500 km north (i.e. wf // to rail) The rail did not deform at all

Blue: DL6 at 08:38 UT Red: DL6 at 23:23 UT



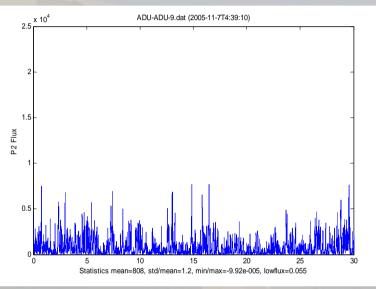
AT field of view

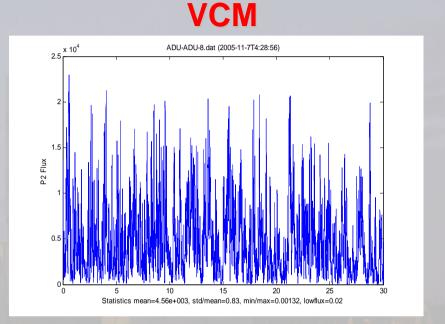


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AT Injection

No VCM





 Correcting the longitudinal pupil position with the VCM significantly increases the mean injected flux (factor 5 in this case).

• As expected the pupil longitudinal position has no impact on the injection fluctuations.

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Beam injection

Beacon from Nasmyth A to IRIS

QuickTime[™] and a decompressor are needed to see this picture.

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Beam injection

Star to IRIS

QuickTime[™] and a decompressor are needed to see this picture.

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Where should the IRIS signal be sent?

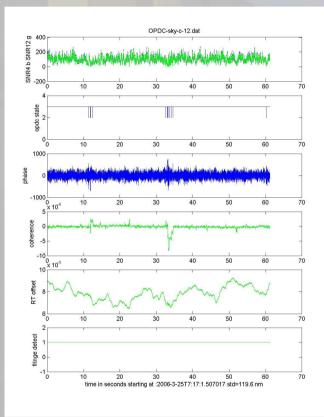
The ACU actuators directly in front of the fiber, normally used only to align the fiber, were retuned from a few Hz bandwidth to a few 100 Hz bandwidth and IRIS now drives them open loop (signal from IRIS feeds ACU but there is no feedback)

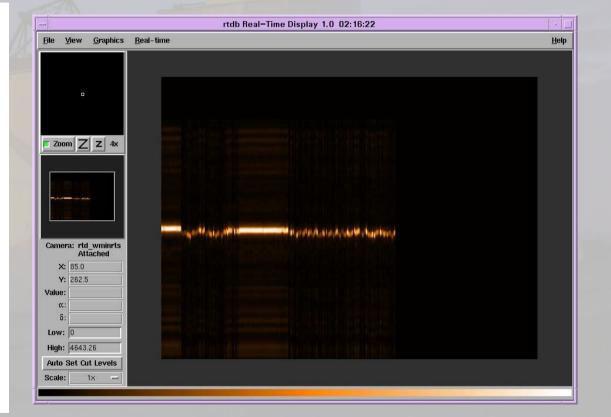




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24th March on the ATs





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The stable beam challenge on the UTs

MACAO although meeting specs for long term Strehl performance did suffer from saturation of the mirror creating PSF explosions and flux dropouts.

Long and frequent flux Dropouts are FINITO killers.

The ITF developed the SMA (saturation management) and AW (anti-windup) algorithms and deployed them in the RTC of MACAO

- SMA manages the expensive aberrations without loss of Strehl.

OPD variations

Vibrations coming from:
MACAO cabinets (50Hz)
acoustic waves from pumps through cooling circuits (96Hz)
M1 cell Eigenmodes
M3 tower Eigenmodes

Possible solutions: damp vibrations determine vibrations with accelerometers determine vibrations with other sensors, ie MACAO

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And the answer is:

We can fringe track on the ATs, night after night after night (24, 26, 27, 28, 29 of March all successful) in decent but not exceptional atmospheric conditions and for as long as tens of minutes (it glitches but recovers)

On the UTs we need to do more about the "vibrations". We have the injection part under reasonable control. By early June 2006 we can fringe track on the UTs, yet with poor performance (~450nm rms)

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Current step

Focus the core ITF on the BFQ residuals (UT vibrations). Deploy VCMs, SMAs, IFGs, DELIRIUMs and put them into operations.

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Immediate improvement installation - ATs

Installation of the variable curvature mirror (VCM) in all six Delay Lines Get FINITO operational on the ATs for three beams

Allow AMBER fringe tracking on three ATs: dichroics, injection stabilization



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Further prospects



Installation of PRIMA starting in 2007
Start of 2nd gen instrumentation phase A studies

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PRIMA motivation and principle

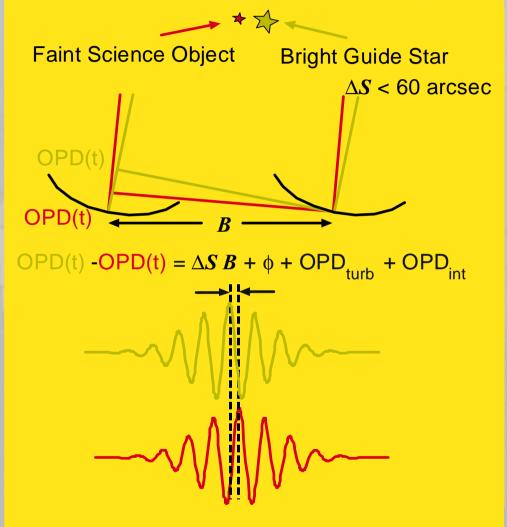
Main limitation of ground interferometers = atmospheric turbulence =>

- Fast scrambling of the fringes =>
 - need of snapshots to measure them =>
 - limitation of the integration time =>
 - low limiting magnitude (VINCI => ~K=8 on UT)
- Impossibility to measure the absolute position / phase of the fringes accurately
 - Fringe position (introduced OPD) <=> astrometry
 - Fringe phase <=> imaging

Solutions:

- "Adaptive optics for the piston term" => increase the limiting magnitude
- Find a phase reference (as quasars in radio astronomy) => phasereferenced imaging and differential astrometry

PRIMA principle



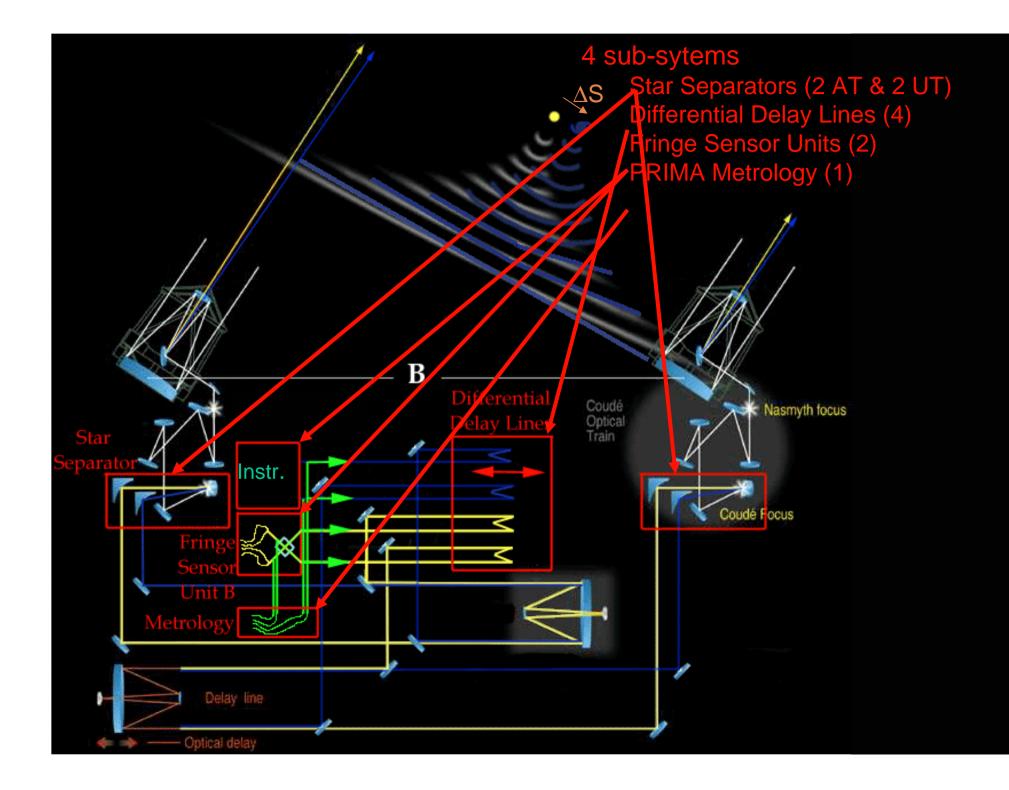
 $\Delta s = astrometry => goal of 10 \mu as (planets...)$

 ϕ = imaging with high dynamic range (AGNs, star environment...)

=> needs to know the dOPD with nanometric accuracy

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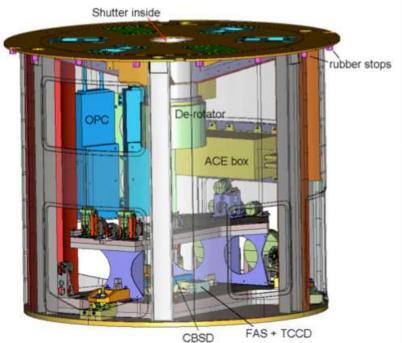
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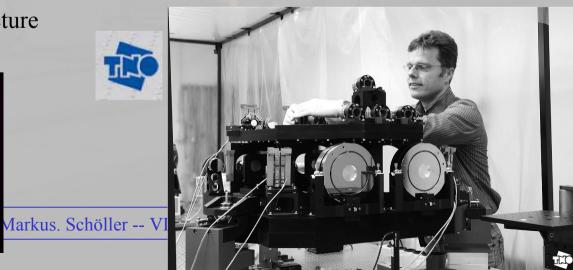


Star Separators AT

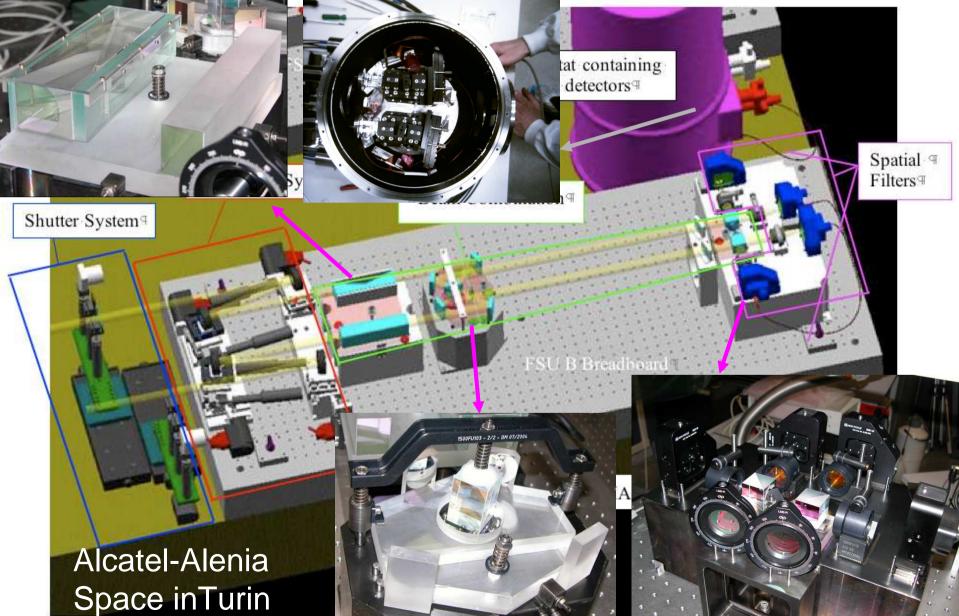
In cylinder below the ground: ø 1.25m x 1.5 m global FoV = 2' sub-fields diameters = 2'' completely symmetrical sharp roof mirror to split the PSF of the star in 2 fast tip-tilt and pupil actuators stiff, thermally insensitive structure done by TNO (Delft, Holland)



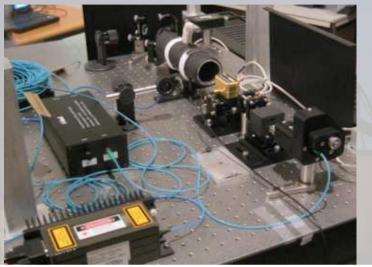


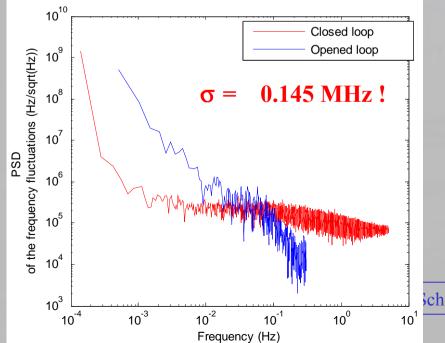


Fringe Sensor Units - OPD



PRIMA Metrology

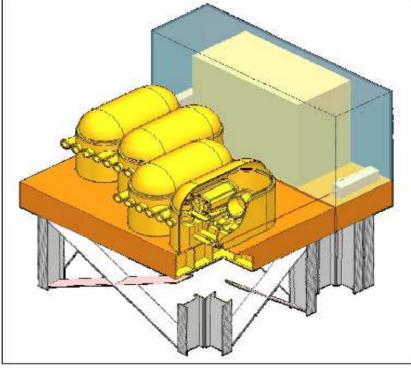


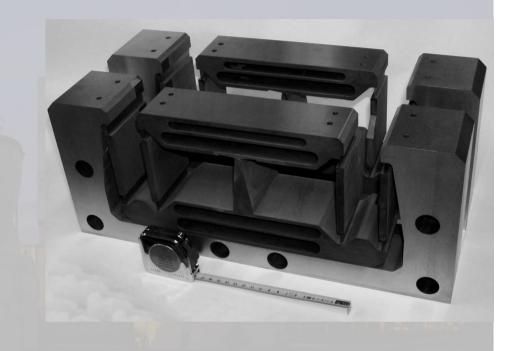






Differential Delay Lines





under vacuum bandwidth 200 Hz - actuation at 8 kHz pupil shift when moving $< 25 \ \mu m PTV$ nanometric resolution

Consortium: MPIA, Obs. Geneva & Heidelberg

Francesco Pepeis talki 6268-73

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