



Adverse effects in optical interferometry

EuroSummer School

Observation and data reduction with the Very Large Telescope Interferometer

Goutelas, France

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LAOG, CNRS and university Joseph Fourier

8 June 2006

What do we mean by « adverse effects »?

Phenomena that prevent the user to measure what he/she wants!

- what do we want to measure?
- how do we want to measure it?
- analyse the different steps where things can happen !

In the framework of the VLT interferometer
with AMBER and MIDI

- Reminder on formation of the interference signal
- Atmosphere is a main contributor to adverse effects
- Infrastructure and instruments
- Calibration

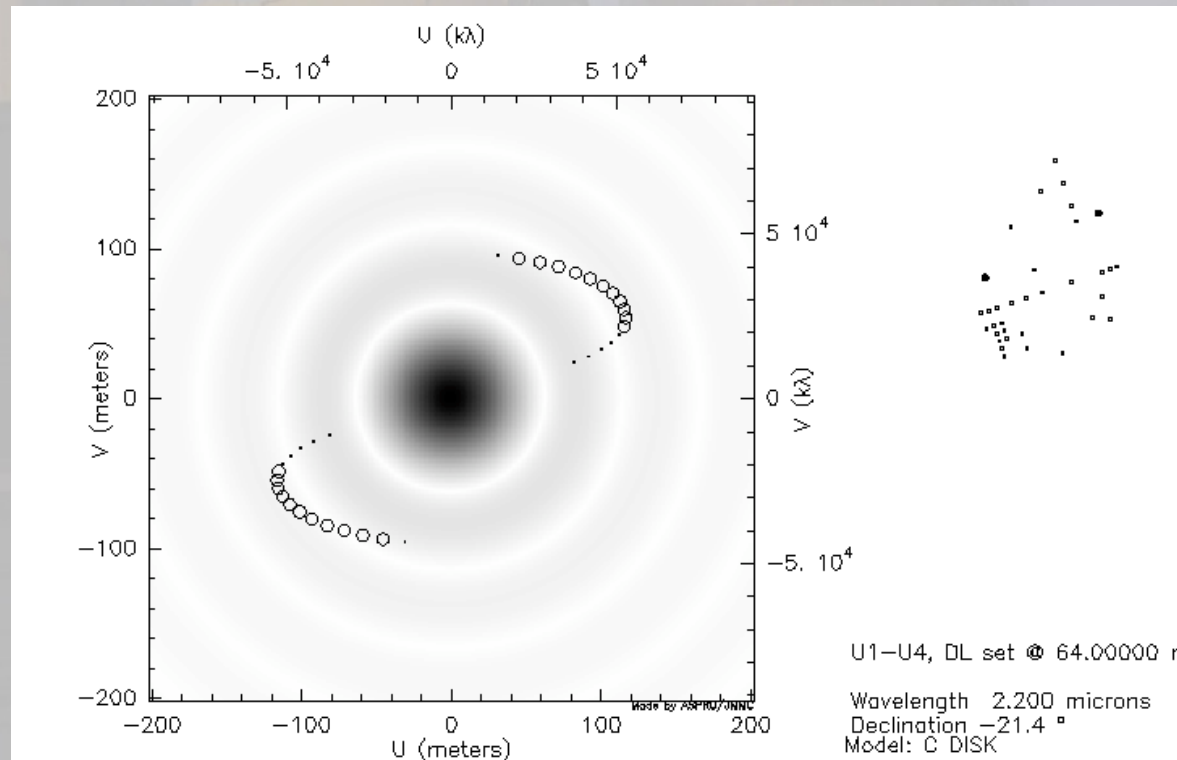


Some reminders

Objectives of interferometry observations

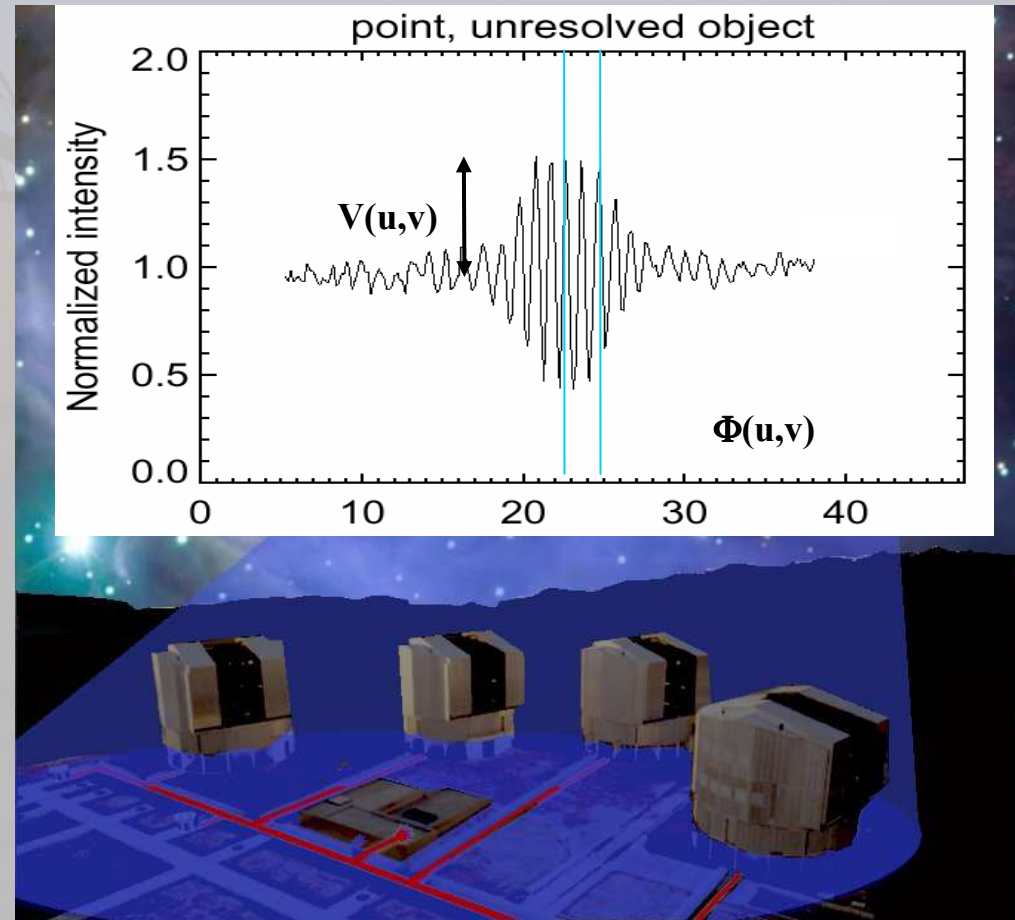
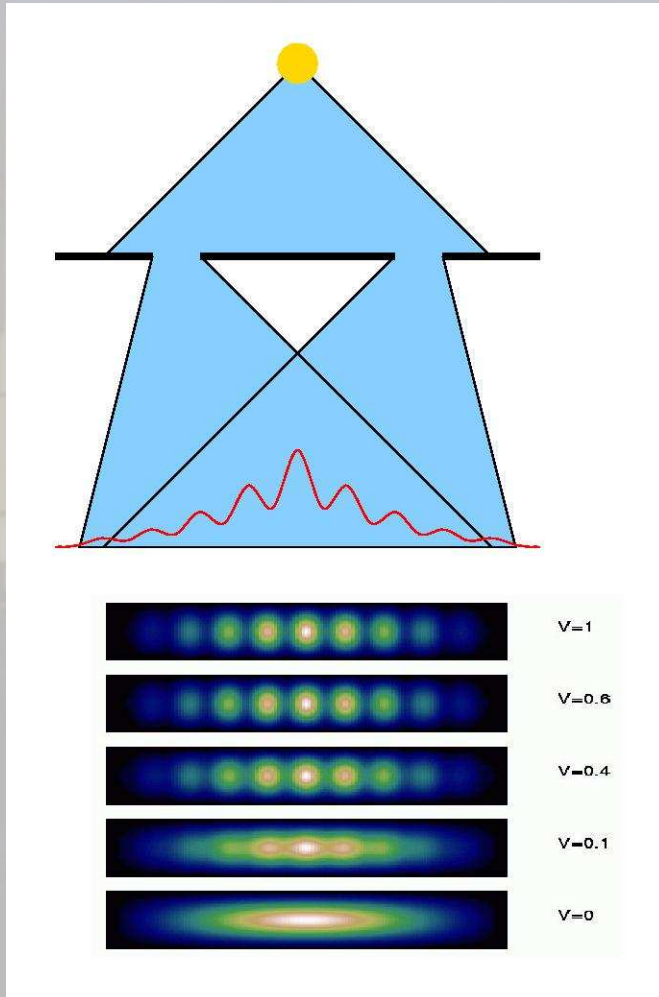
To get spatial information on the object by measuring several components of its Fourier transform (theorem of Zernike-van Cittert).

REMINDER

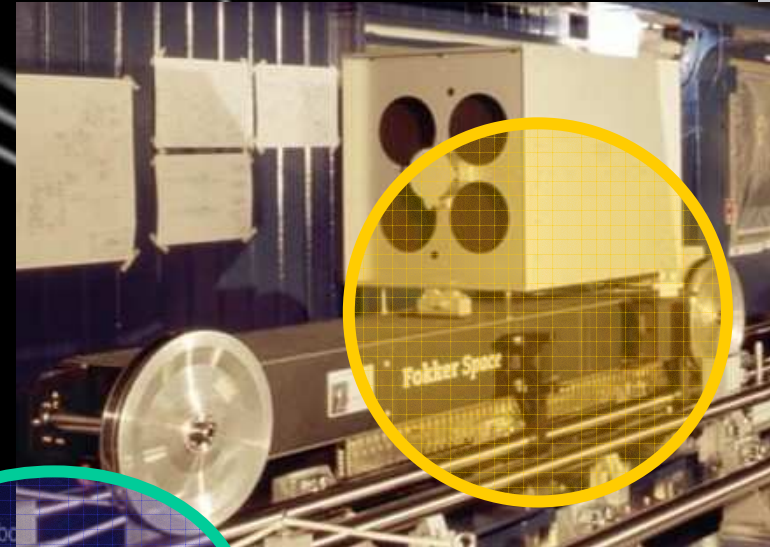


Apparatus to measure the Fourier components of a source with spatial resolution

REMINDER



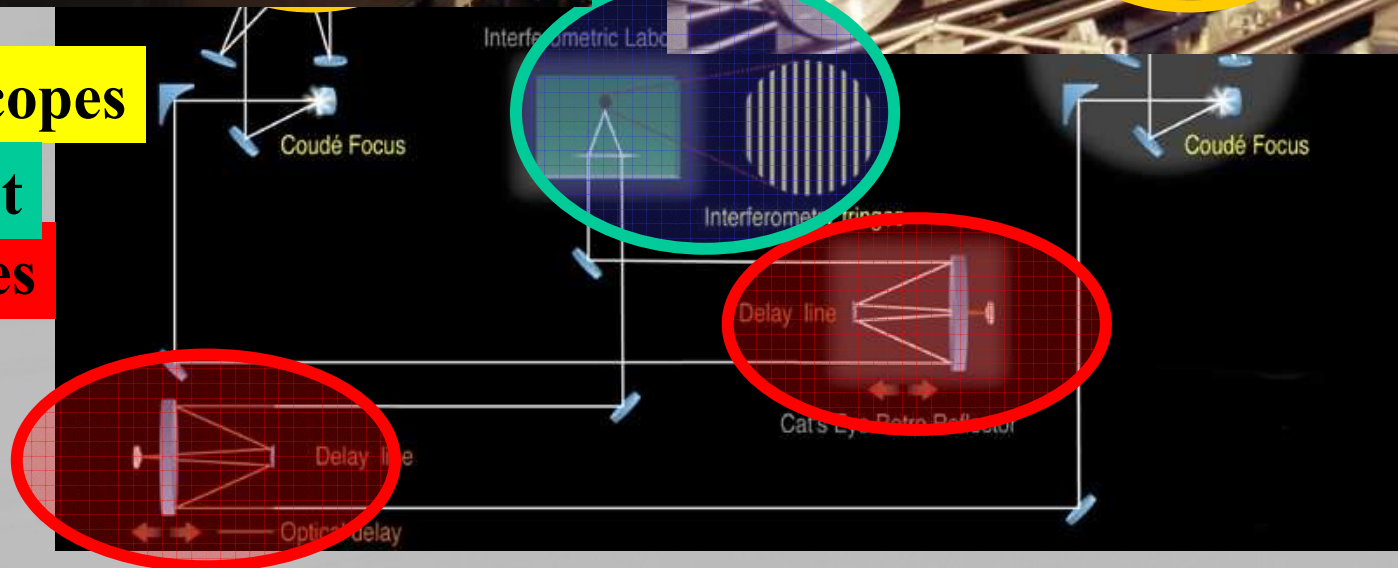
The infrastructure



The telescopes

The instrument

The delay lines



Interferometric basic equation

$$I_{12}(x_k) = I_1 + I_2 + 2\sqrt{I_1 I_2} V_{12}^{\text{inst}} V_{12}^{\text{obj}} \cos(2\pi\sigma[s \cdot B_{12} + d_1 - d_2])$$

Where the variables x_k are:

- I_k : input photometry
- V_{12}^{inst} : contrast including system and atmosphere
- σ : wavenumber ($1/\lambda$)
- s : input beam direction
- B : baseline
- d_k : delay

REMINDER

Realistic interferometric equation

The measurements are integrated over a number of variables:

$$P = \int_{x_1}^{x_2} I(x) dx$$

$$P = \frac{1}{x_2 - x_1} \int_{x_1}^{x_2} [I_1 + I_2 + 2\sqrt{I_1 I_2} V_{12} \cos(2\pi\sigma[s.B + d_1 - d_2])] dx$$

Where x_k can be:

- I_k : input photometry
- V_{12}^{inst} : contrast including system and atmosphere
- σ : wavenumber ($1/\lambda$)
- s : input beam direction
- B : baseline
- d_k : delay

Main sources of perturbations

- **Atmosphere:** spatial and temporal fluctuations of wavefront
- **Individual elements of infrastructure:** displacements (tip-tilts, optical path, piston), vibrations, drifts
- **Photon detection:** photon noise, read-out noise, dark current, cosmetics
- **Polarization:** light is naturally polarized
- **Human action**

REMINDER



The Atmosphere

Atmosphere

Key parameter: refraction index

$$n(\lambda, t, r)$$

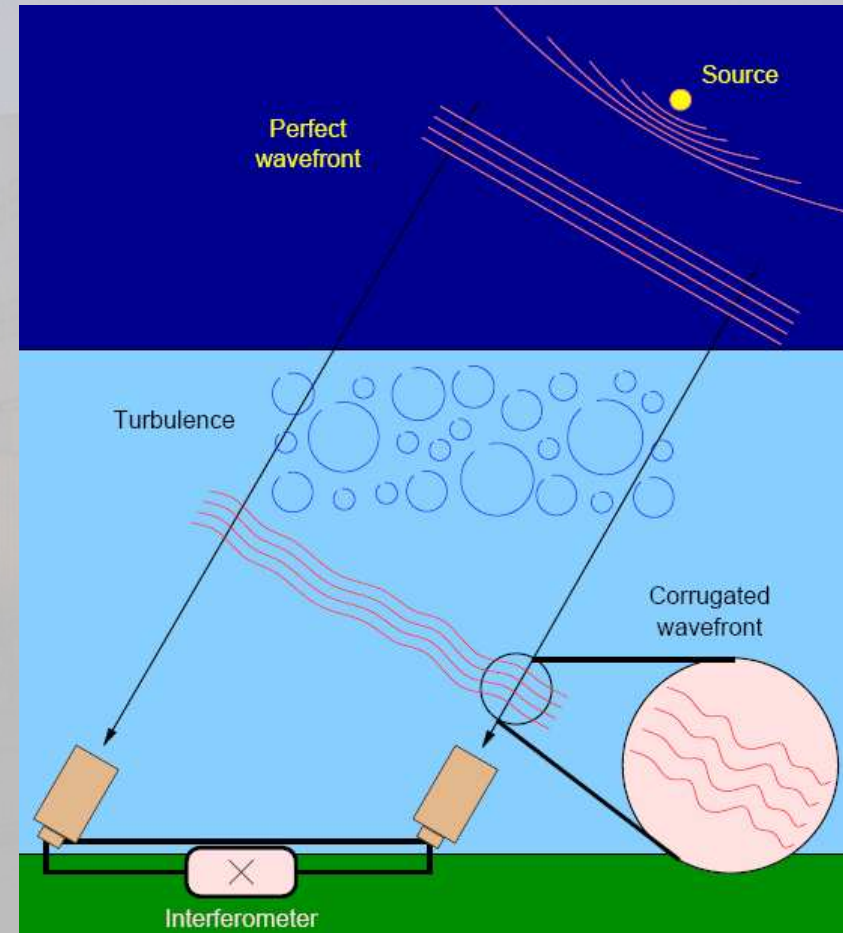
- Wavelength dependence

Eddies due to turbulence induce temperature fluctuations

- Spatial dependence
- Temporal dependence

→ corrugated wavefronts

→ OPD fluctuations

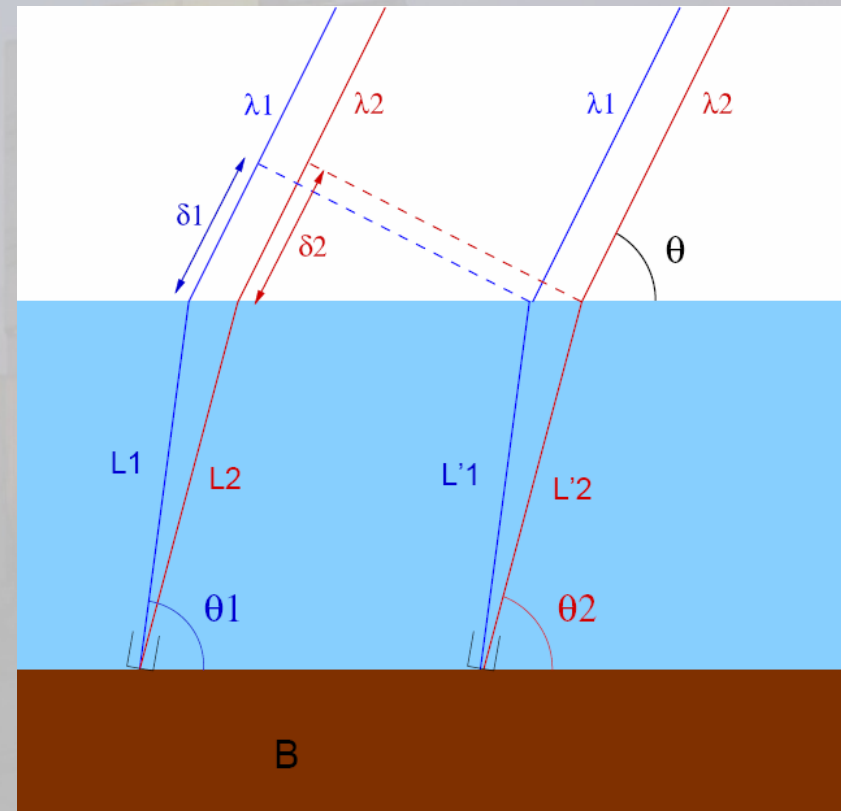


Transverse atmospheric refraction

Dispersion of the light for each incoming beam: **the focal image is replaced by a small spectrum**

BUT no delay problems

Main limitation is loss of optical throughput especially if light is injected in hole or fiber.



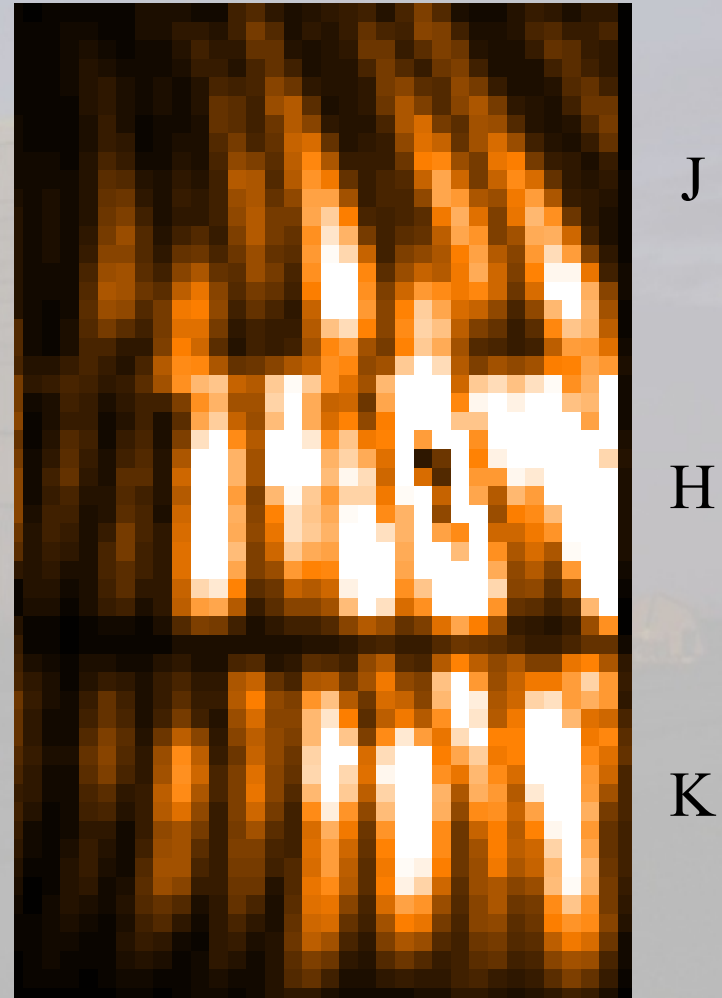
Longitudinal atmospheric dispersion

Unevacuated delay lines means that the delay corrected by the delay lines is valid only for a wavelength:

$$\text{OPD}(\lambda) = \left(\frac{n(\lambda)}{n(\lambda_0)} - 1 \right) \delta \quad \lambda$$

→ Curved fringes if spectral resolution

→ Loss of contrast if broad band observations



Wavefront corrugation

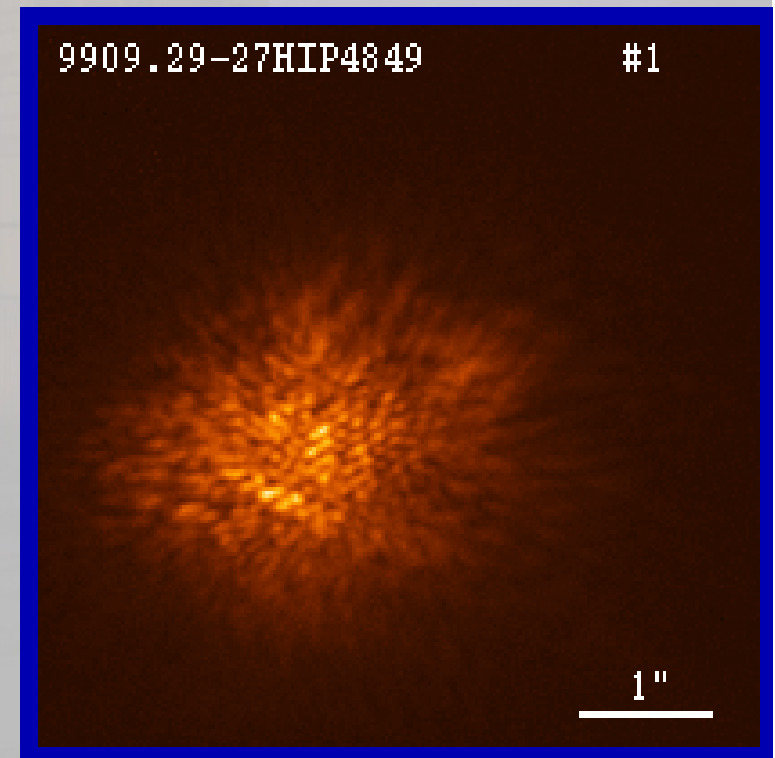
Speckles due to wavefront corrugation.

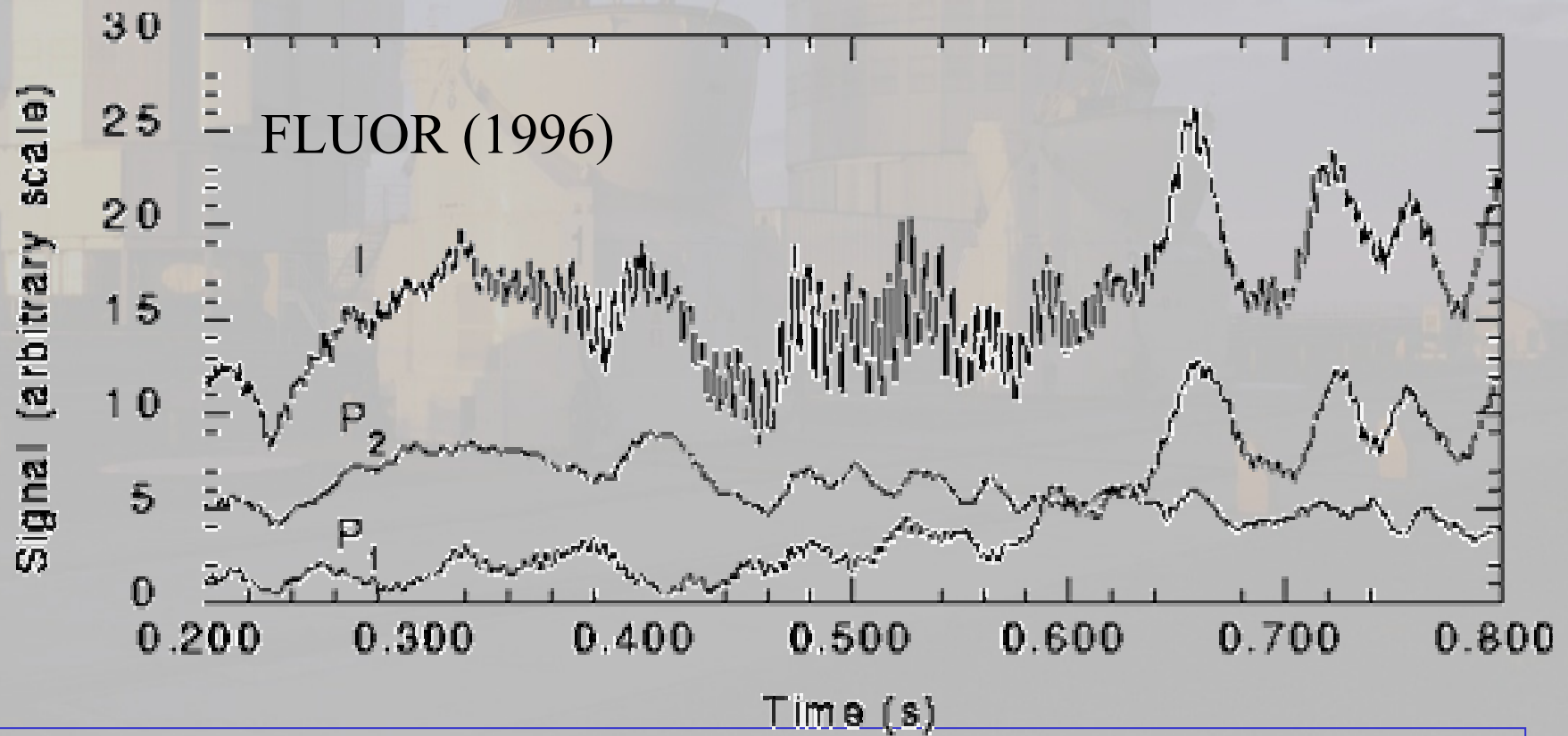
The key parameter is the **Fried parameter**:

- Size of coherence cell

$$r_0: \sim 60\text{cm}@2.2\mu\text{m}$$

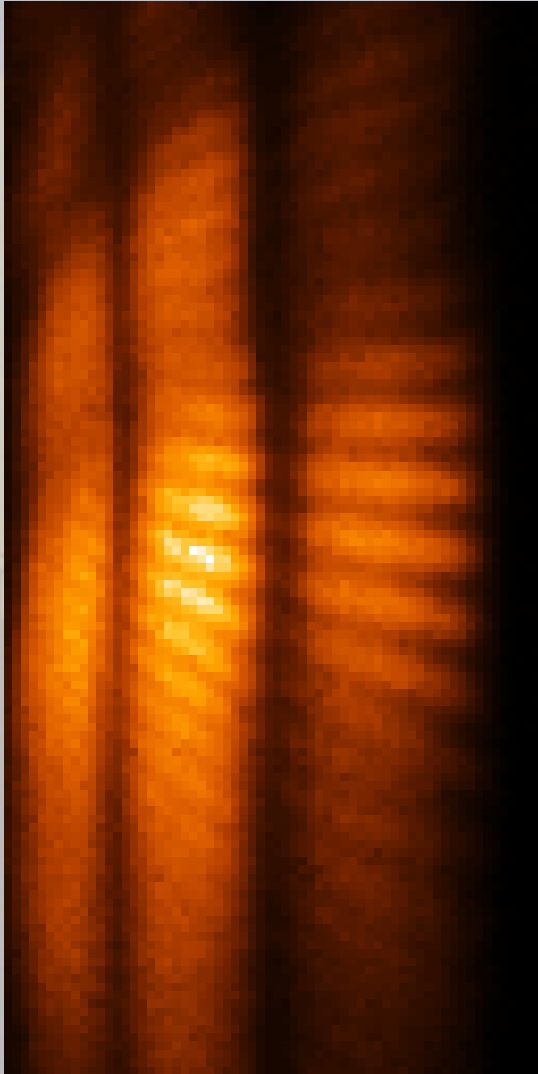
- Coherence time $\tau_0 \sim 50\text{ms}$
- Outer scale $L \sim 10\text{-}100\text{m?}$





Atmospheric piston

ATMOSPHERE



Piston corresponds to the phase difference of the wavefront between the telescopes.

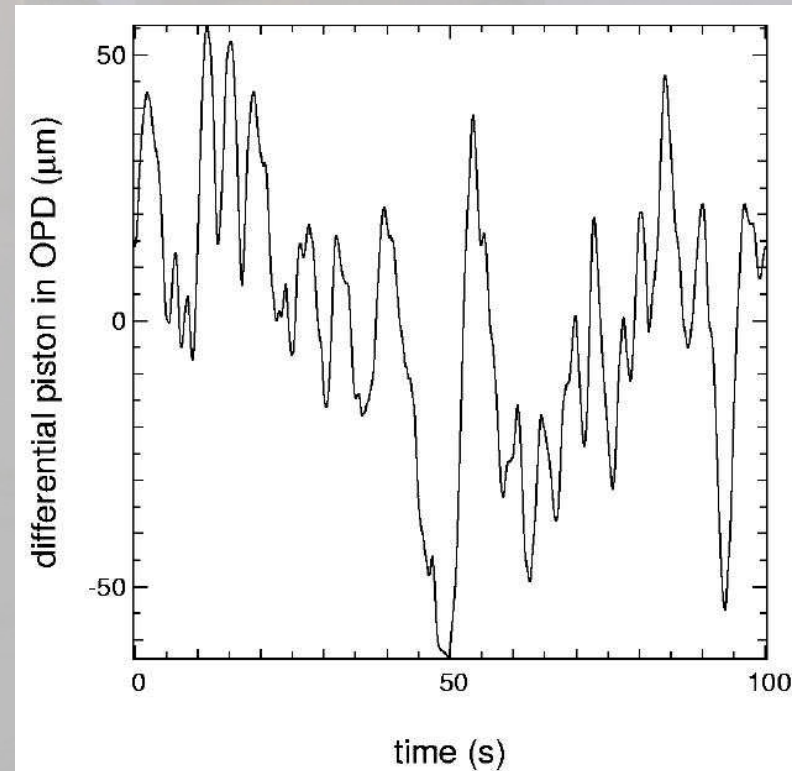
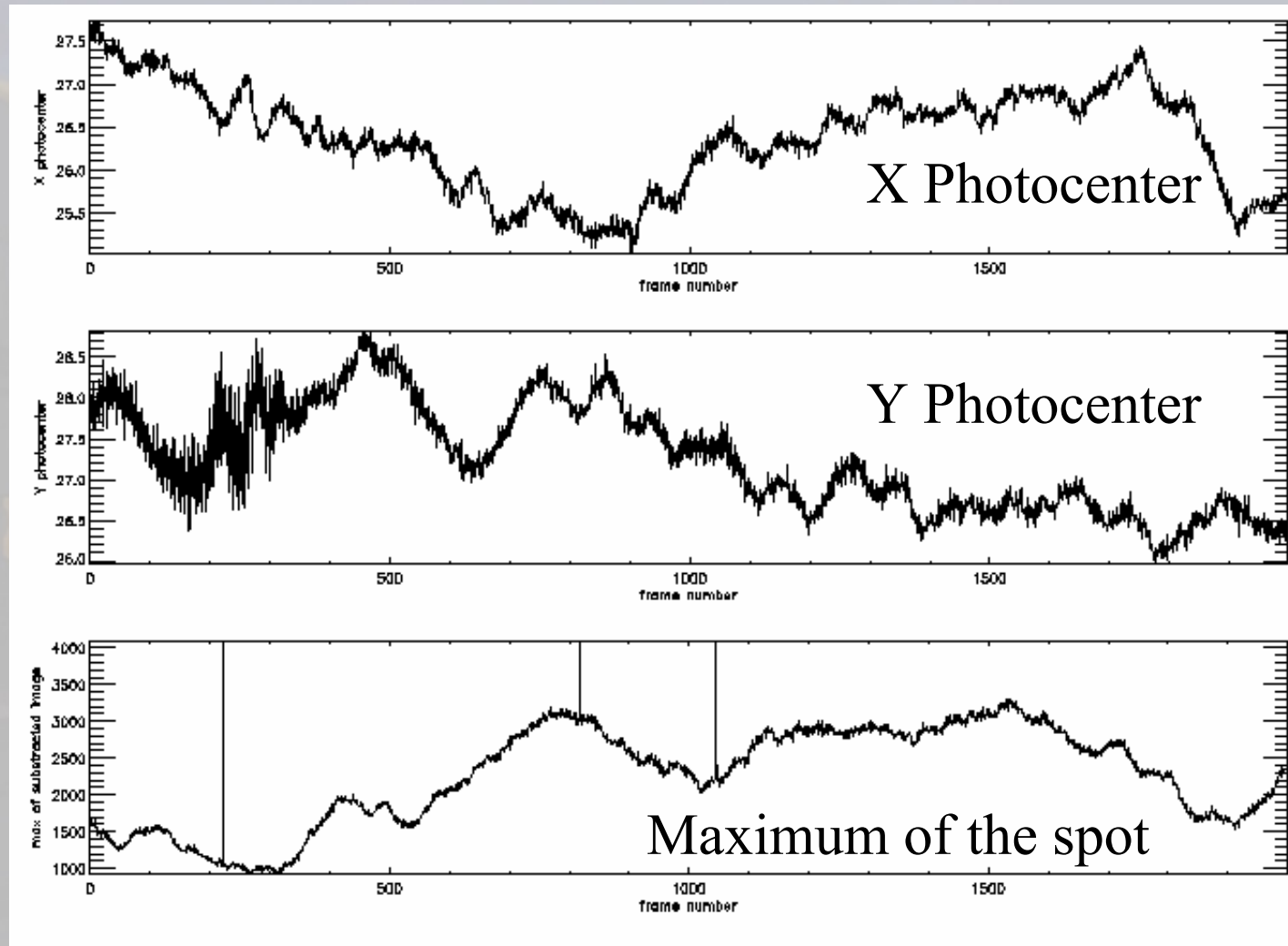


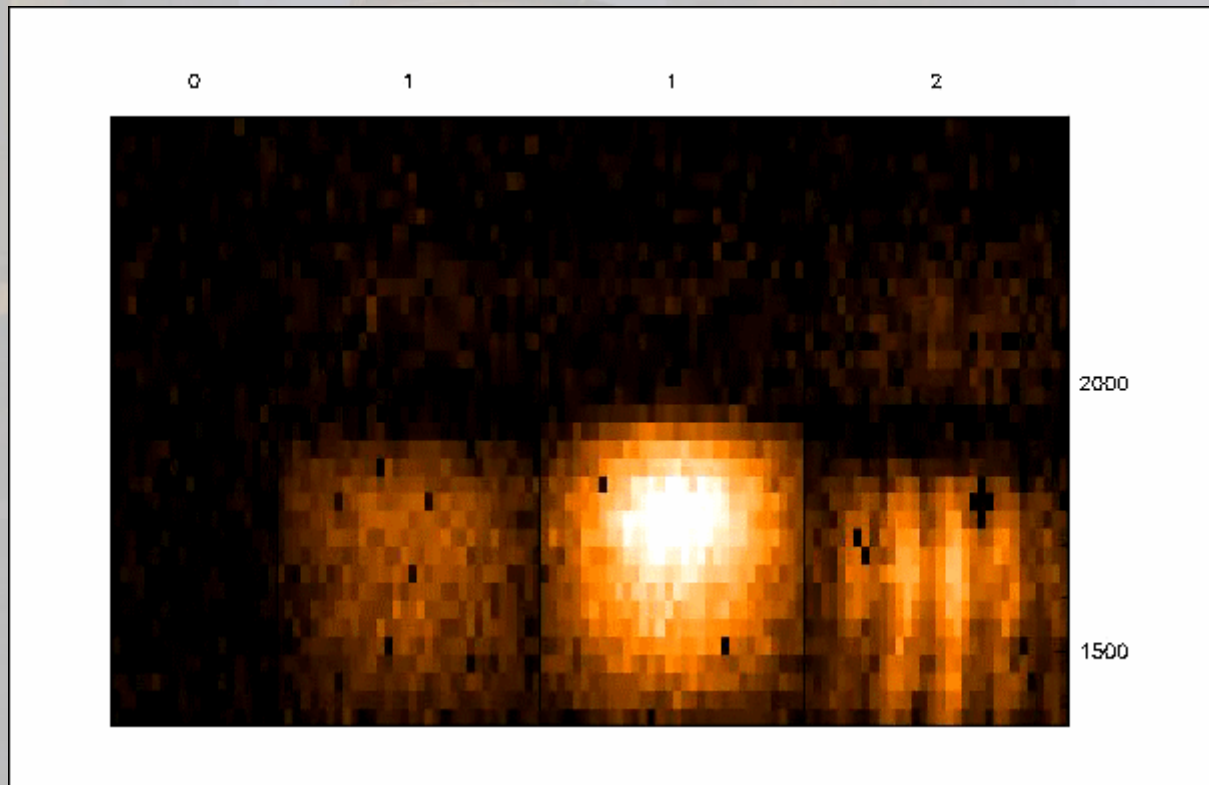
Image jitter as seen by MIDI

ATMOSPHERE



AMBER data

- Injection fluctuation
- Piston



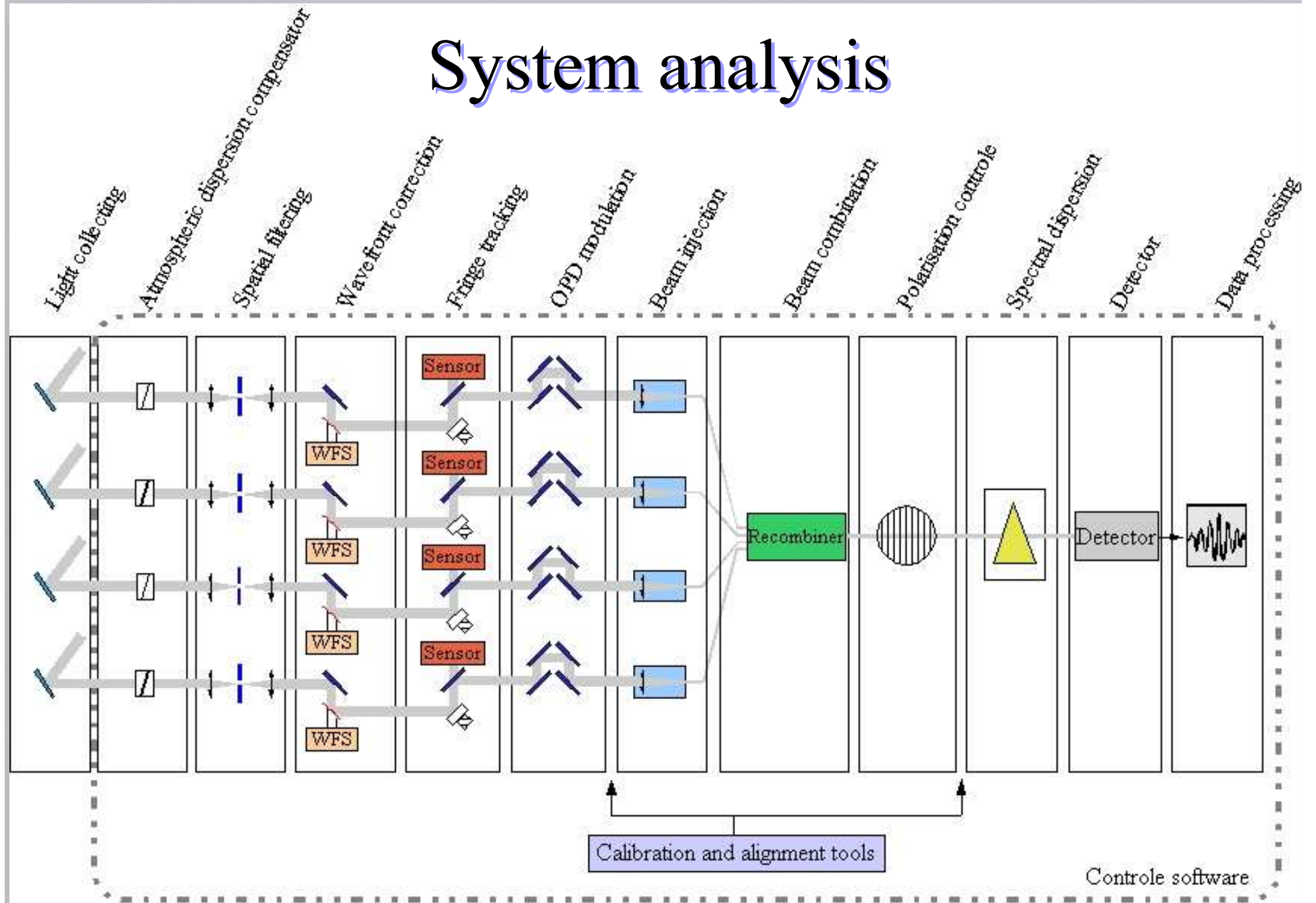


Infrastructure and Instruments

How to overcome atmospheric perturbations?

- **Atmospheric dispersion compensator (ADC):**
Made of pair of prisms to control the spectral dispersion
- **Beam stabilization** (wavefront sensor + actuator):
 - Tip-tilt correction → angle tracker
 - Adaptive optics: requires a deformable mirror
- **Fringe tracking** (fringe sensor to act on delay line actuator)
- **Spatial filtering:** pinhole or single mode fiber + photometric calibration

System analysis



But subsystems can introduce new perturbations

- When complexity increases, number of sources of perturbations too!
- Reliability becomes also an issue when the number of subsystems increases

Collectors: guiding, active optics

Beam routing: 32 motors

Adaptive optics: wavefront sensors, deformable mirrors, real-time control, configuration

Delay lines: carriage trajectory, 3 translation stages, metrology, switches,

Beam stabilisation: variable curvature mirrors, image and pupil sensors (ARAL/IRIS), sources (LEONARDO)

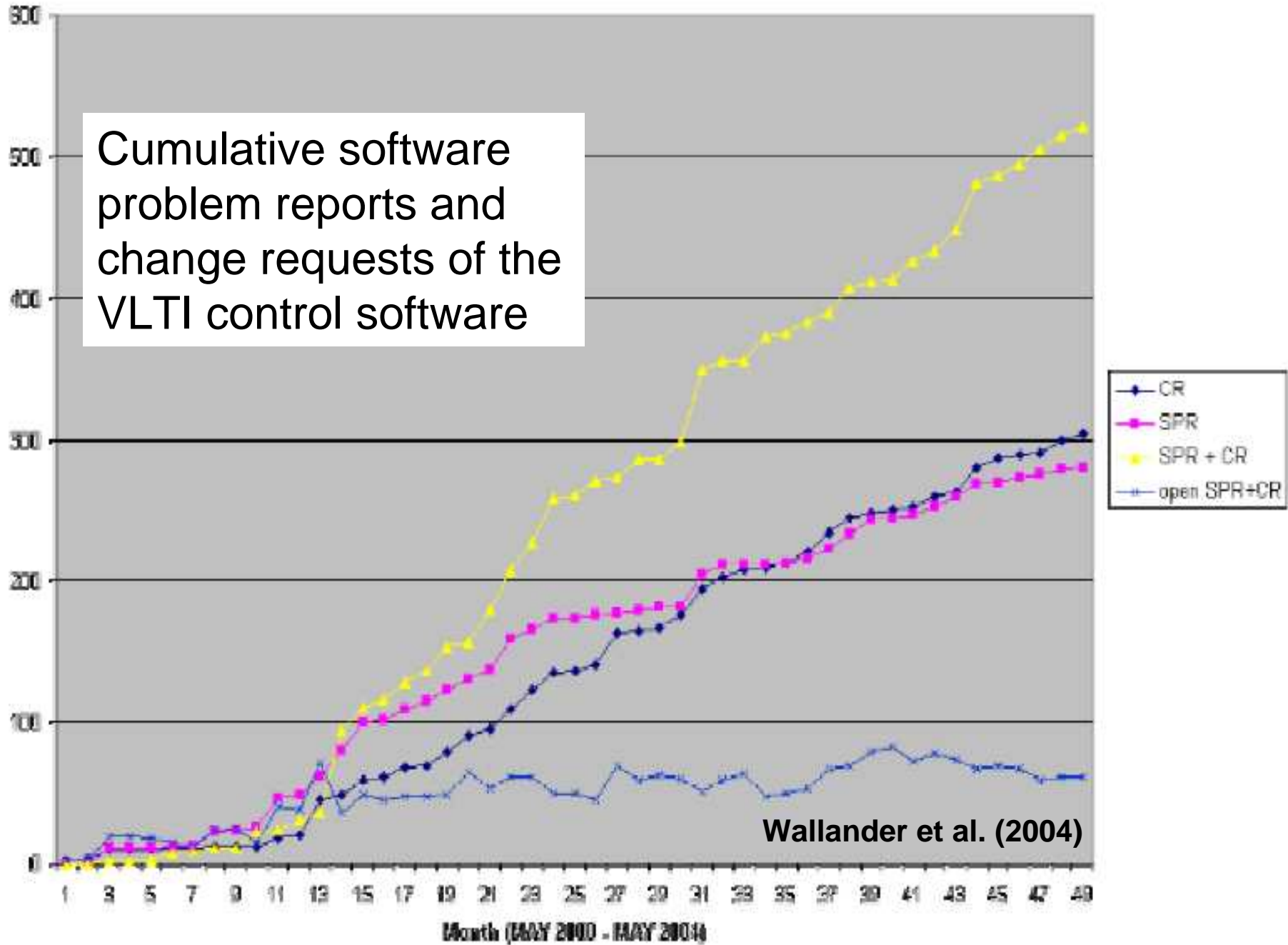
Fringe tracking: fringe search, group delay, phase tracking, locks

Beam combination: spectral resolution, spatial filtering, atmospheric dispersion, polarization, detection

Control software (cf. Wallander, SPIE April 2004):

60 computers, 750000 lines of code

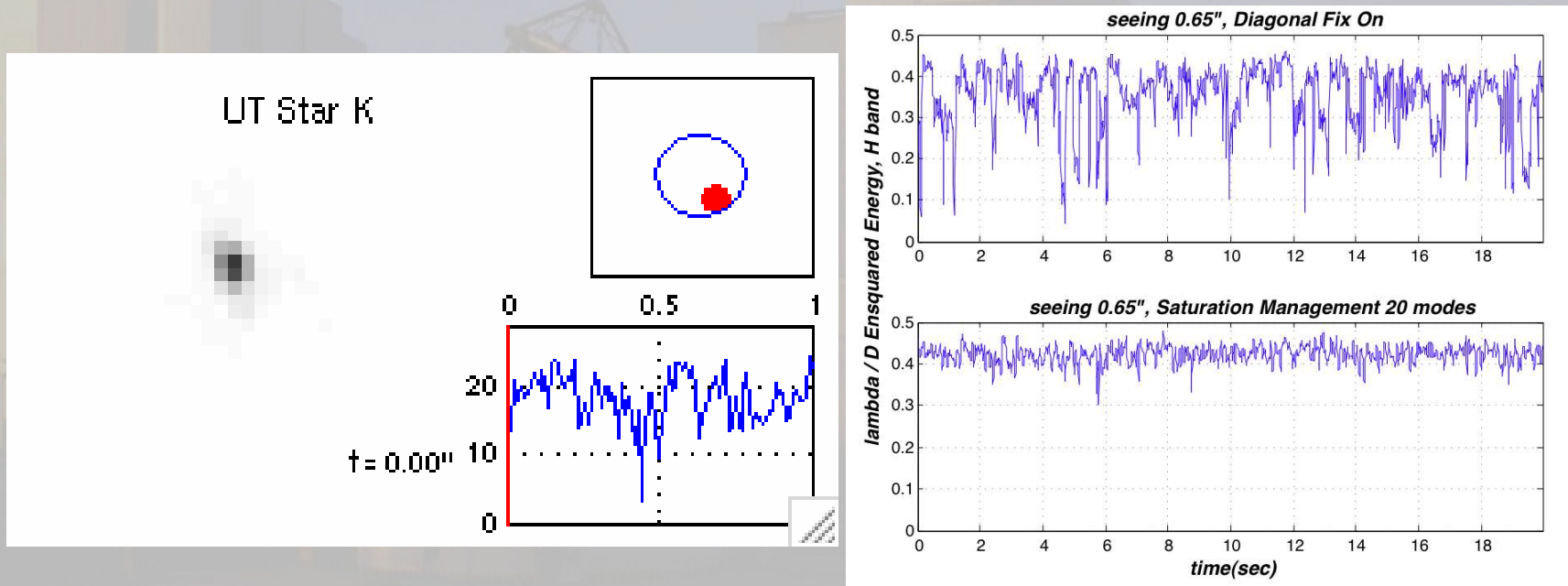
Cumulative software problem reports and change requests of the VLT1 control software



Wallander et al. (2004)

Wavefront correction can mess things up!

Observations made on a UT with IRIS (IR image sensor) in front of AMBER

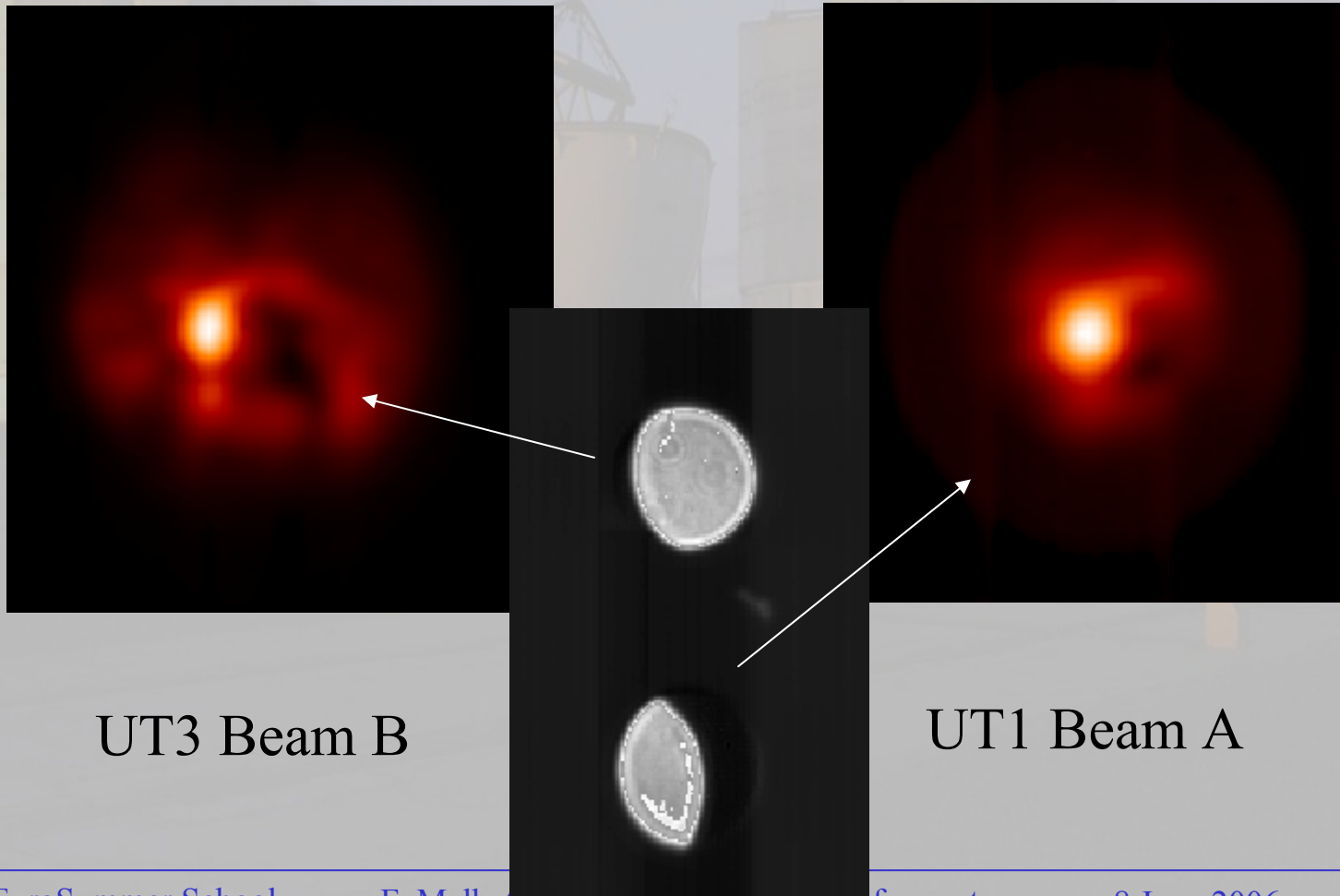


Classical AO algorithms are not necessarily the best ones for interferometry!

→ **saturation management** in MACAO on the VLTI

Alignment problems crucial for MIDI

INFRASTRUCTURE
INSTRUMENTS

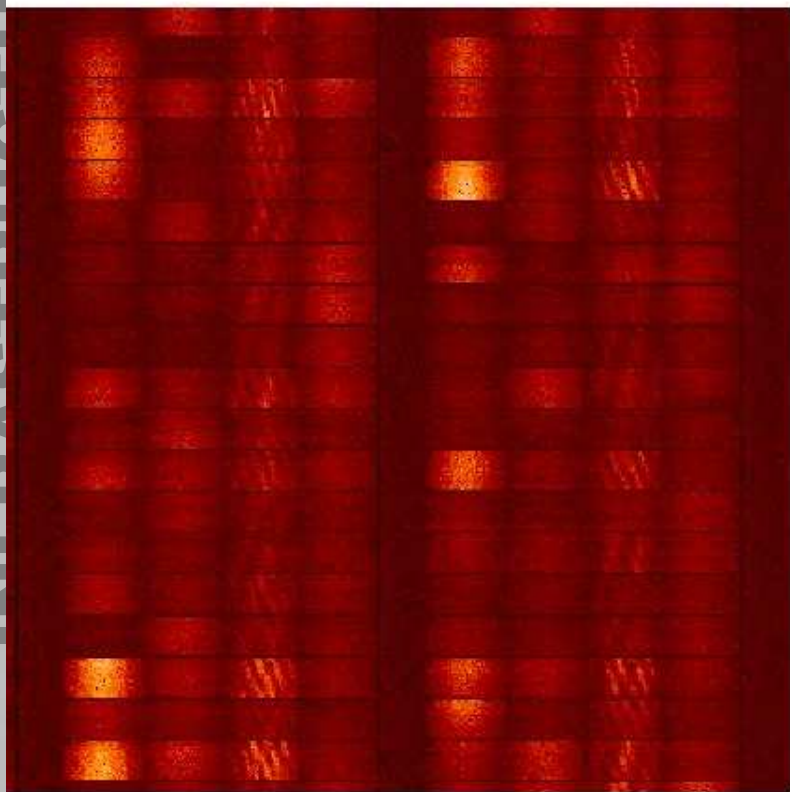


UT3 Beam B

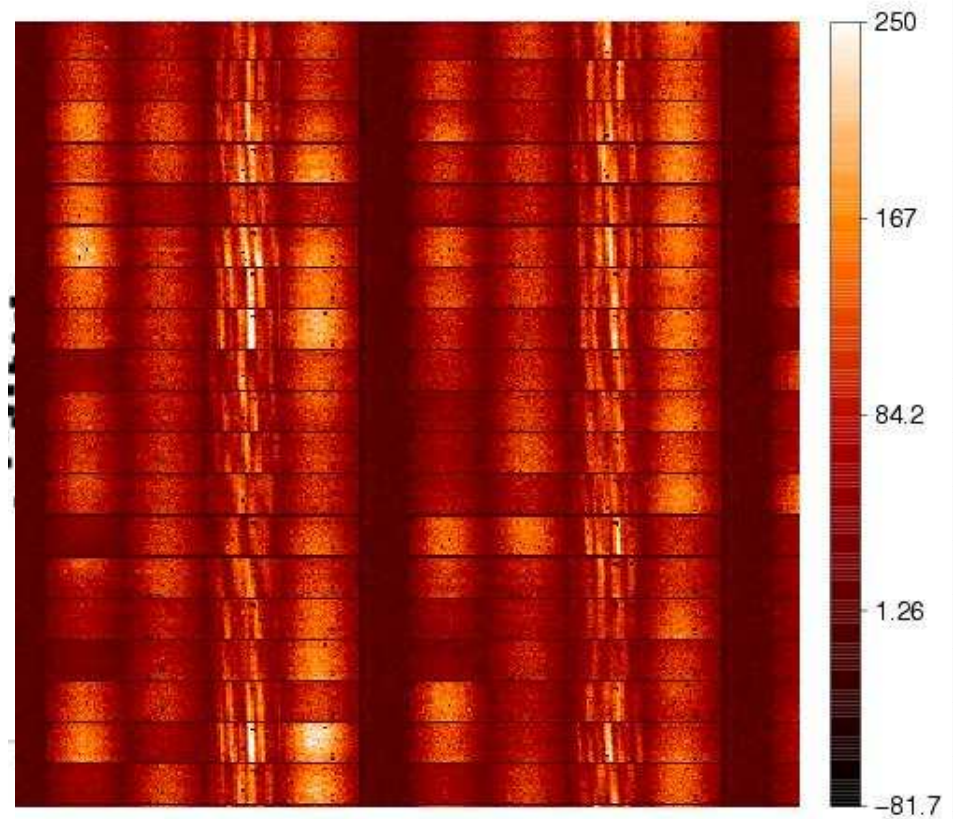
UT1 Beam A

Major vibrations seen by AMBER

0.8
images waterfall
wfans2.fits



images waterfall
wofans2.fits



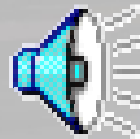
MACAO electronic rack: vibrating fans

Acoustic propagation?

Accelerometer measured the position of a mirror of the VLTI train and this is what one get when there is ...



... MACAO fans on



... outside music on



Wrong OPD models leads to drifts

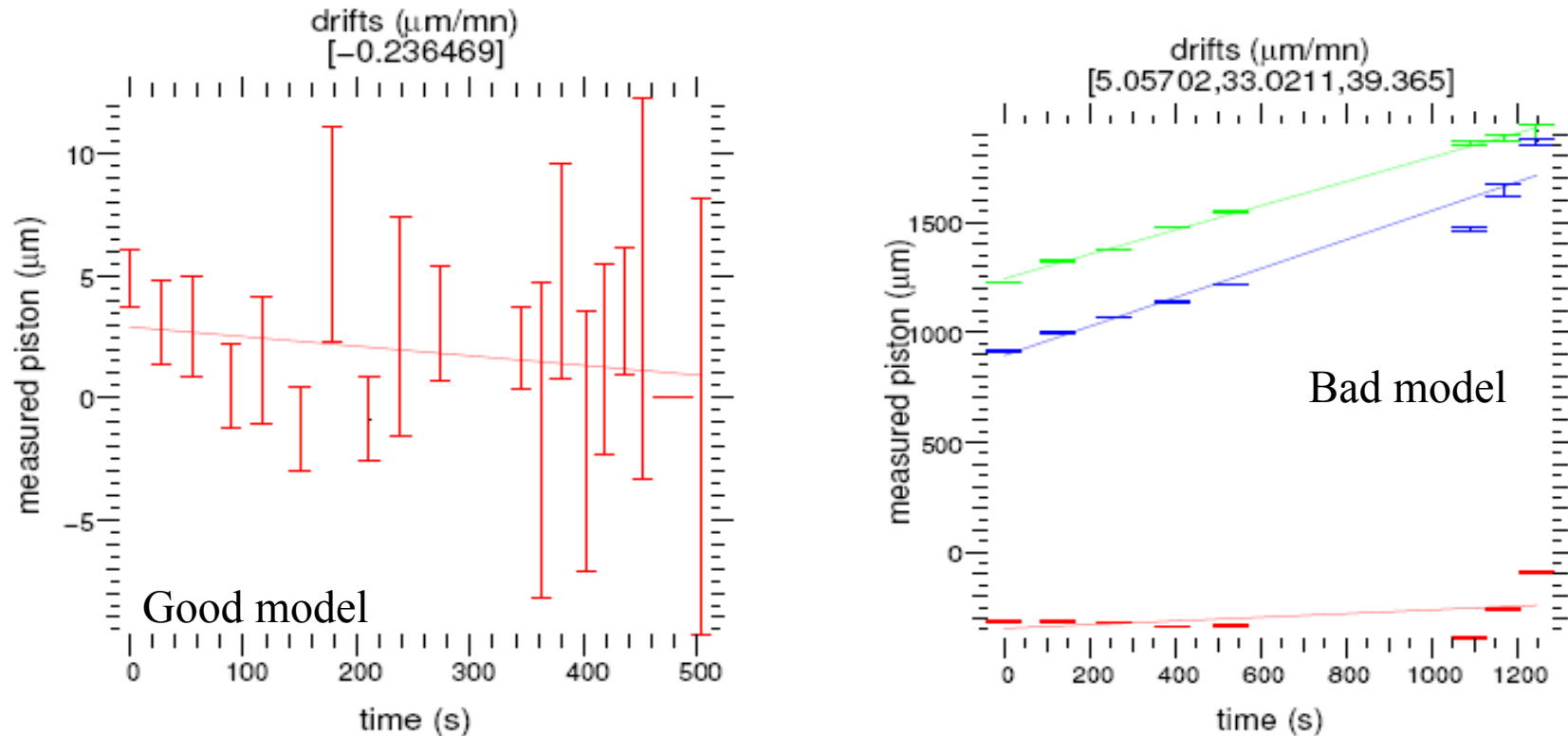
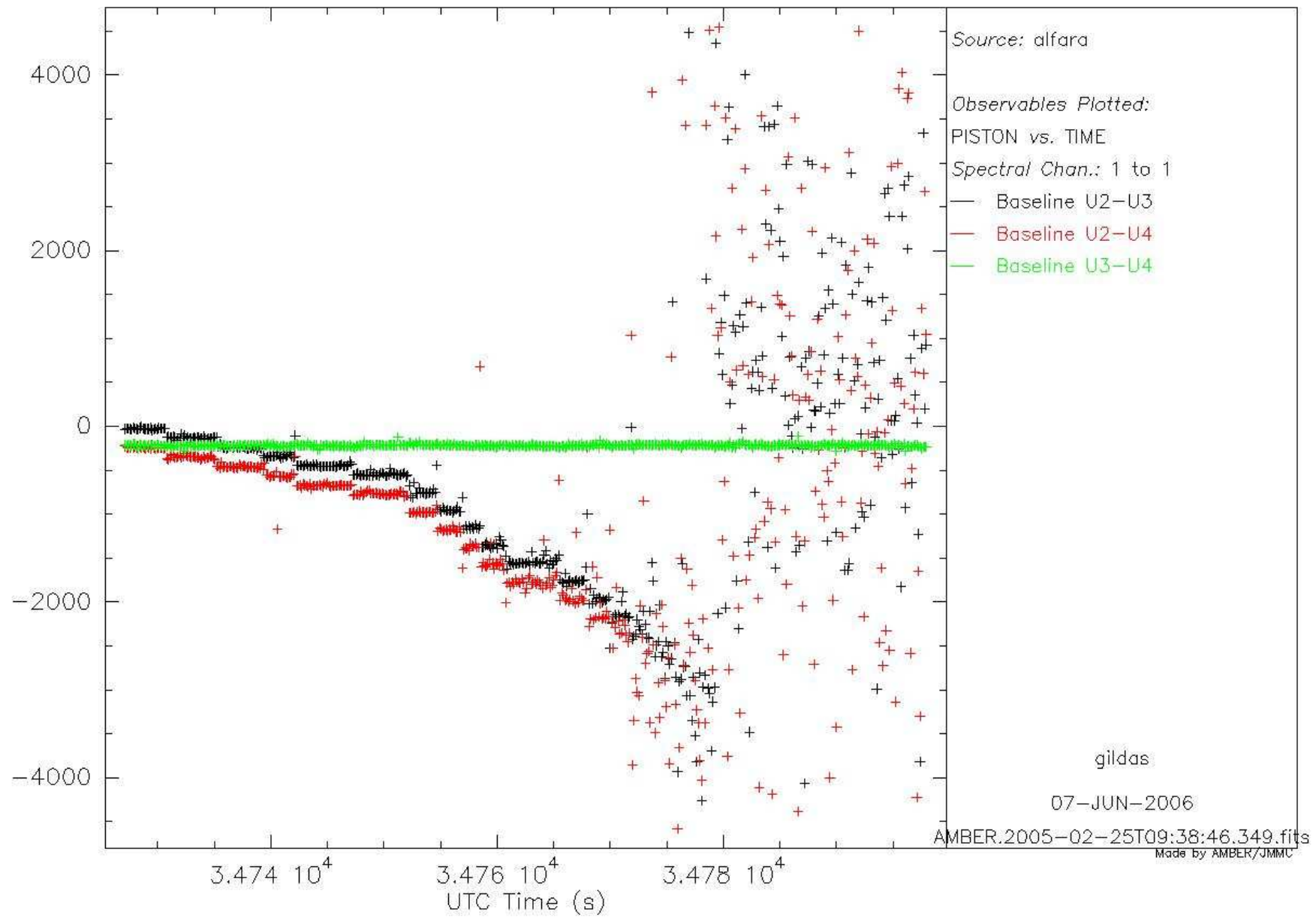


Figure 5: OPD measured during an observation without actuating the delay lines for an offset. Left panel: the siderostat baseline (D0-H0) has a drift of -0.24 microns/minute; right panel: the 3 UT baselines have a more rapid drift. UT2-UT3: 5.06 microns/minute (red), UT3-UT4: 33.0 microns/minute (green), UT2-UT4: 39.4 microns/minute (blue).

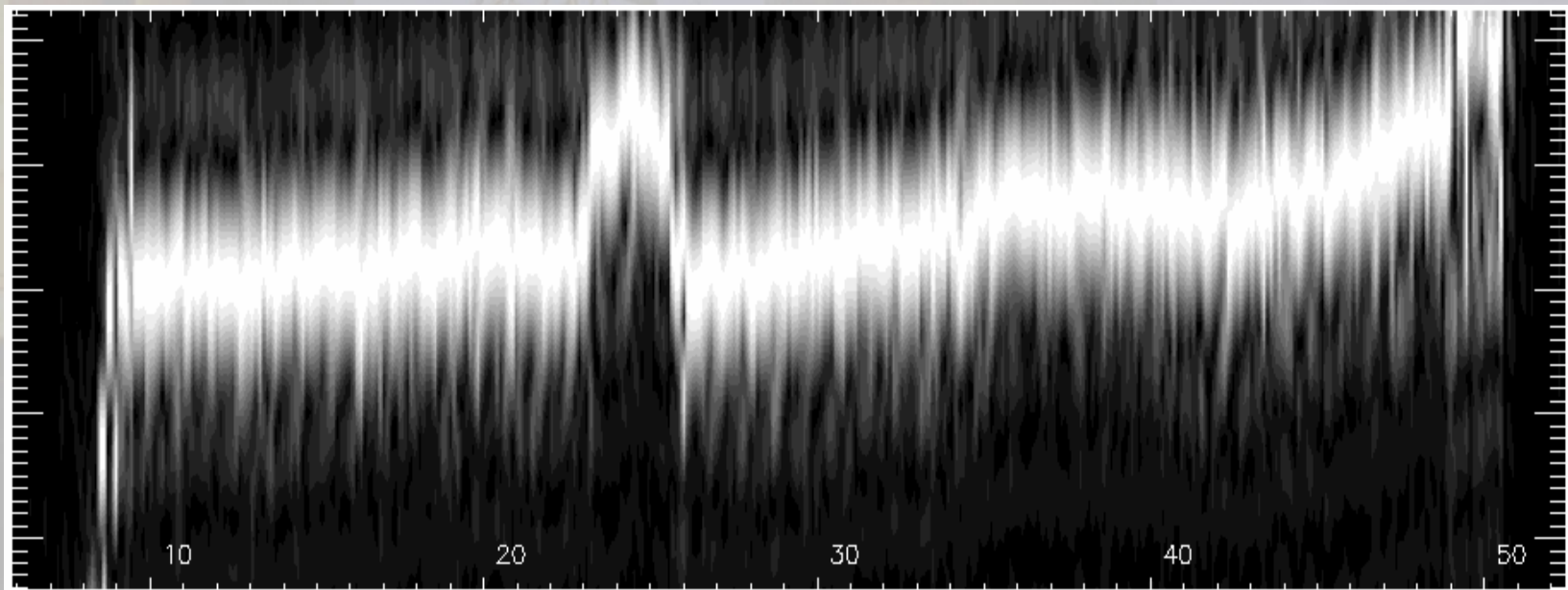
AMBER Commissioning #2 report



OPD stability measured by MIDI

Fringe position as recorded by the MIDI instrument

INFRASTRUCTURE
INSTRUMENTS

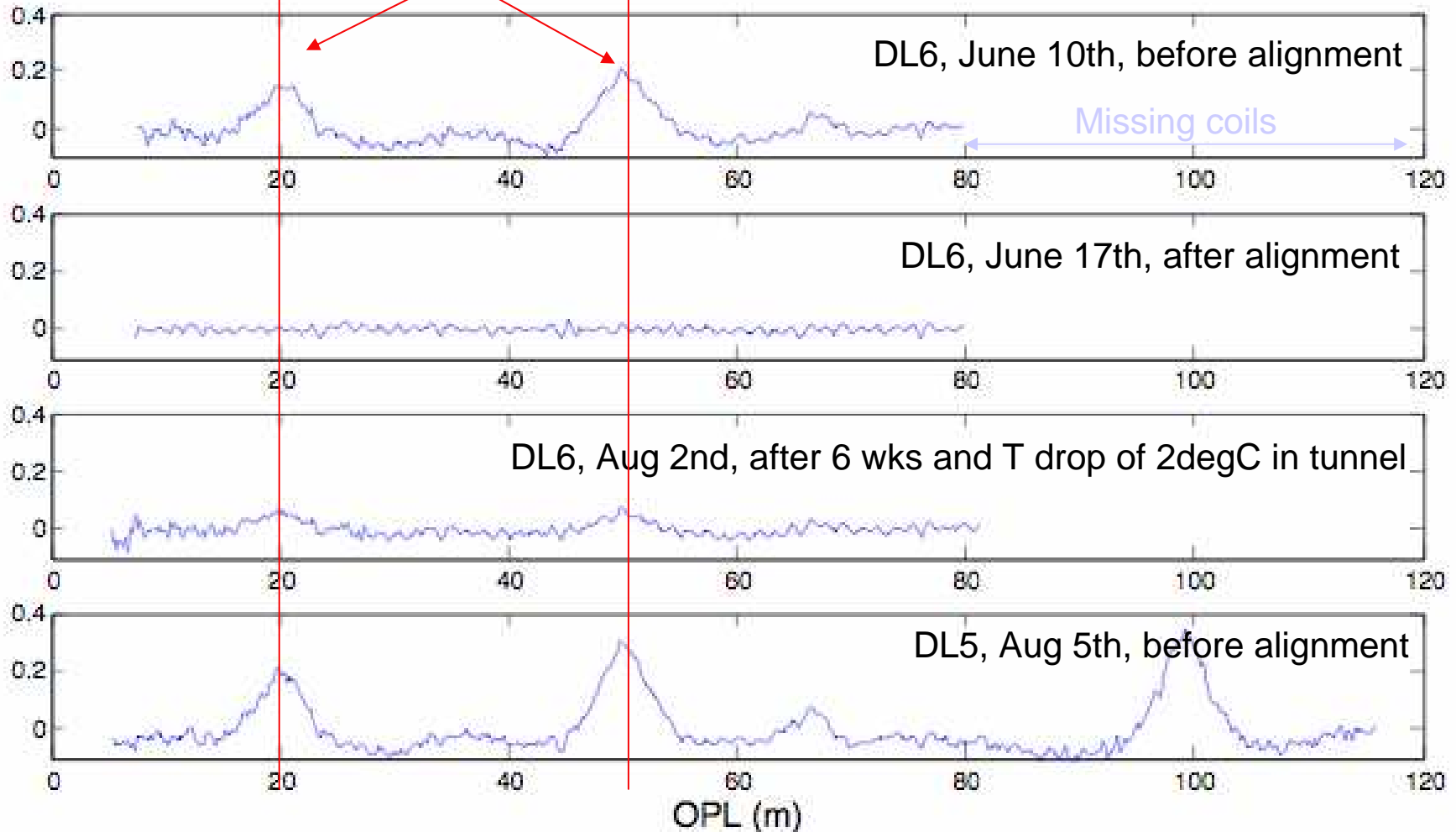


Delay line rail drift

DL6 was aligned in Dec 2004 (summer time)

Concrete
junctions

INFRASTRUCTURE



Iquique Earthquake

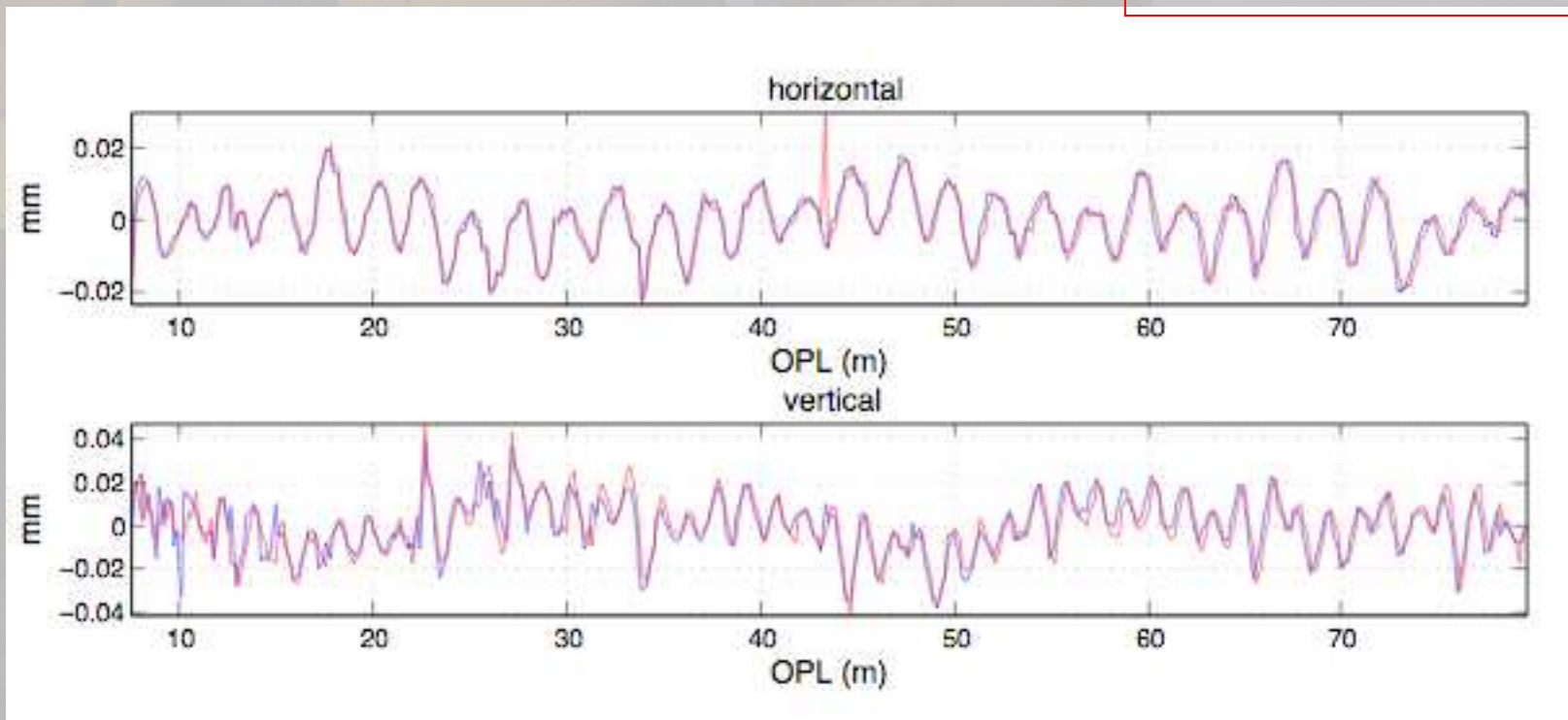
June 13th, 22:44 UT (during rail alignment campaign)

Richter 7.9

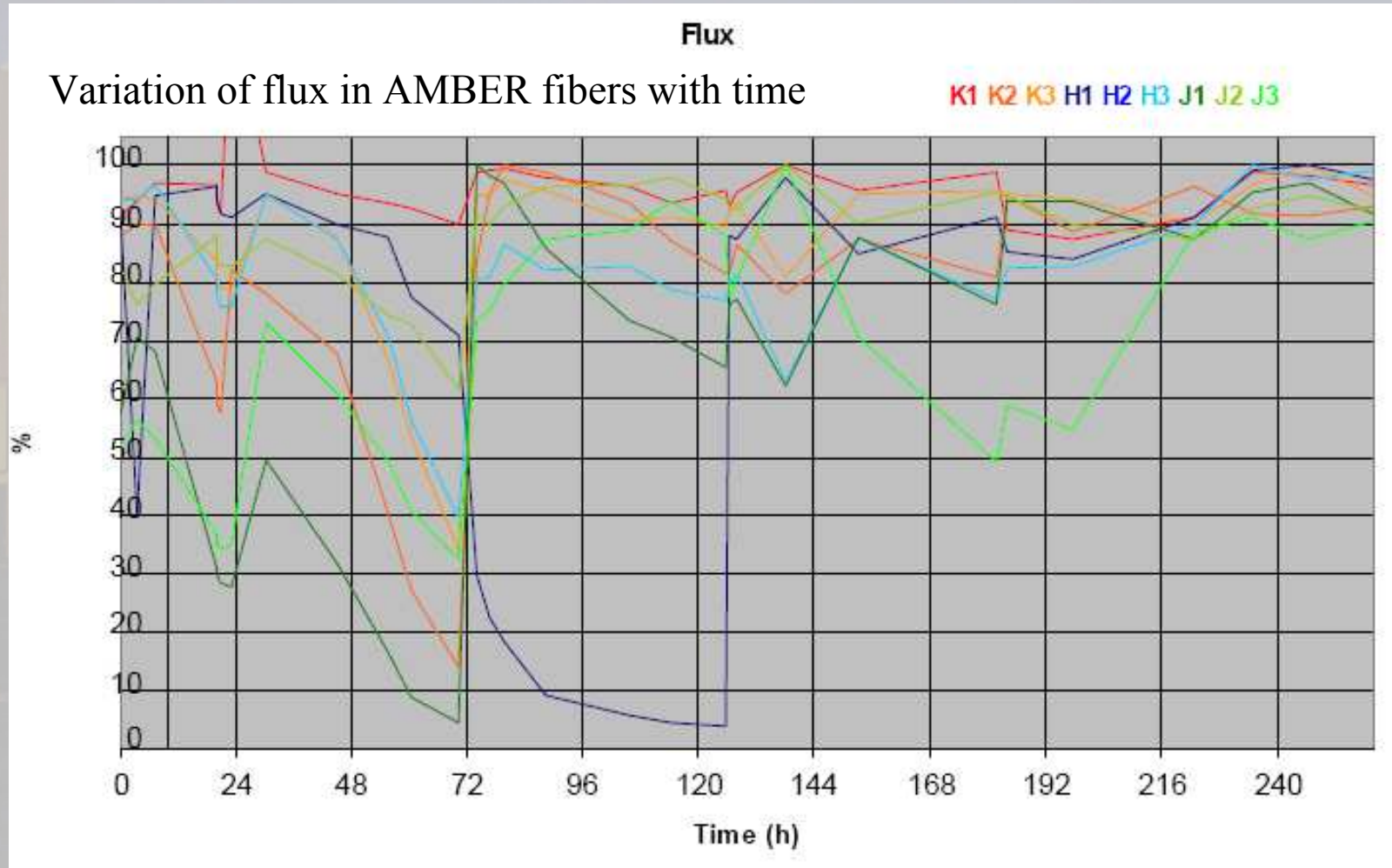
Distance 500 km north (i.e. wf // to rail)

The rail did not deform at all

Blue: DL6 at 08:38 UT
Red: DL6 at 23:23 UT



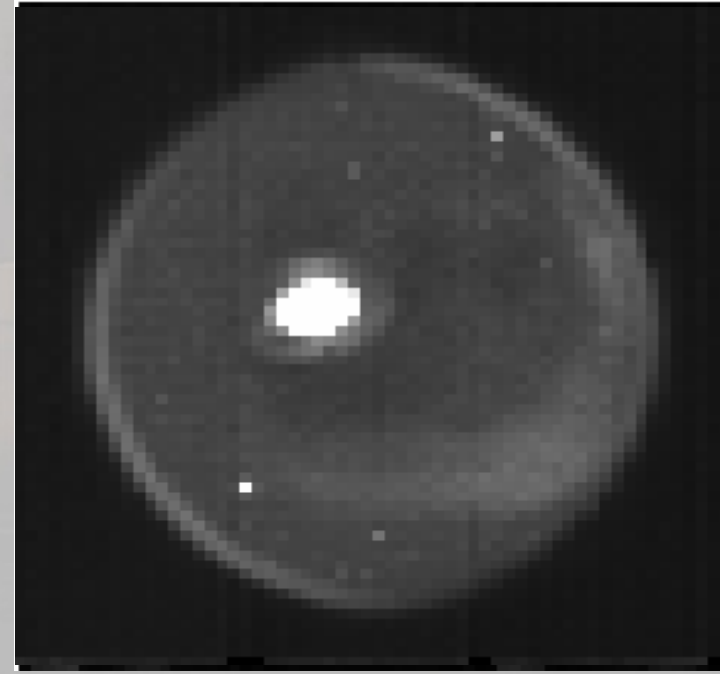
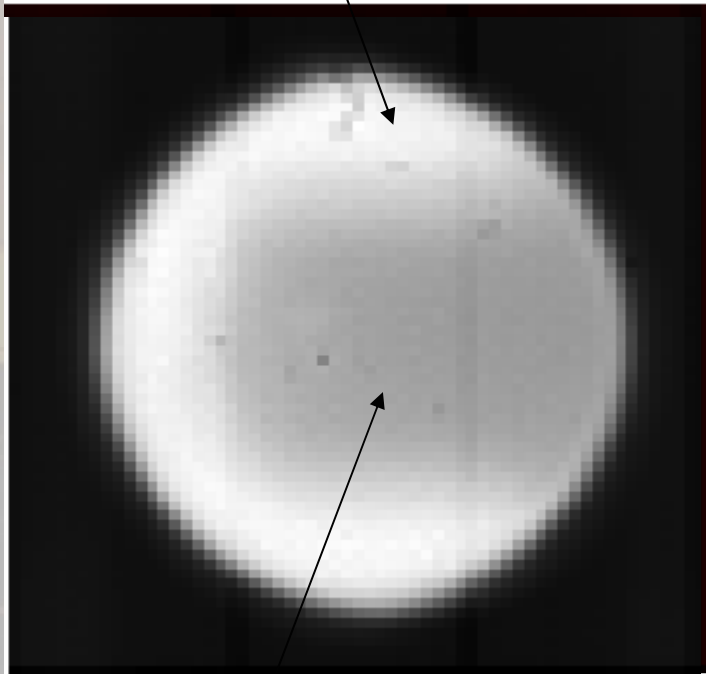
Maintaining optical alignment



AMBER Commissioning #1 report

Thermal background as seen by MIDI

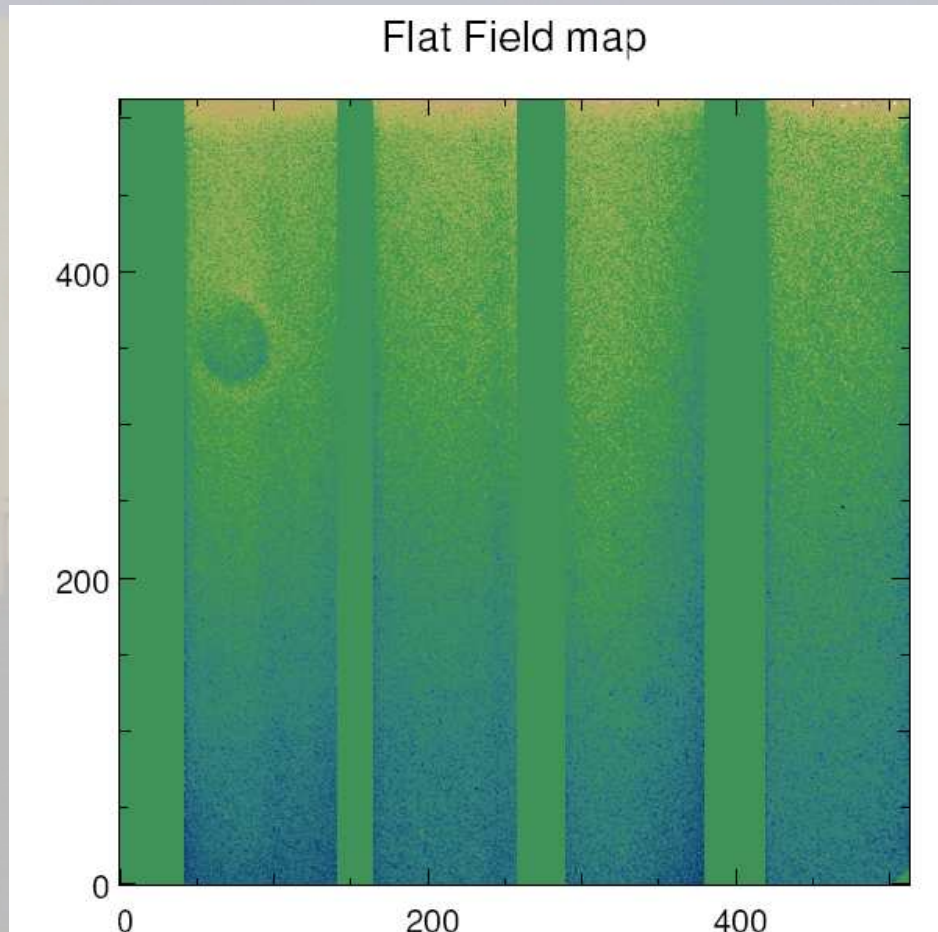
Tunnel background
~17 °C



Sky background: Observing Field Of View (FOV) UT1 Beam A
~5-10 °C UT3 Beam B

INFRASTRUCTURE
INSTRUMENTS

Signal detection



Many issues related to signal detection:

- photon noise
- read-out noise
- dark current
- flat field
- ...

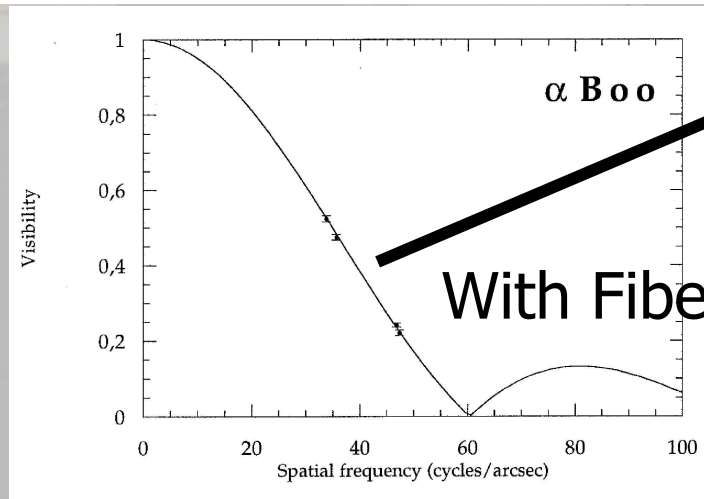
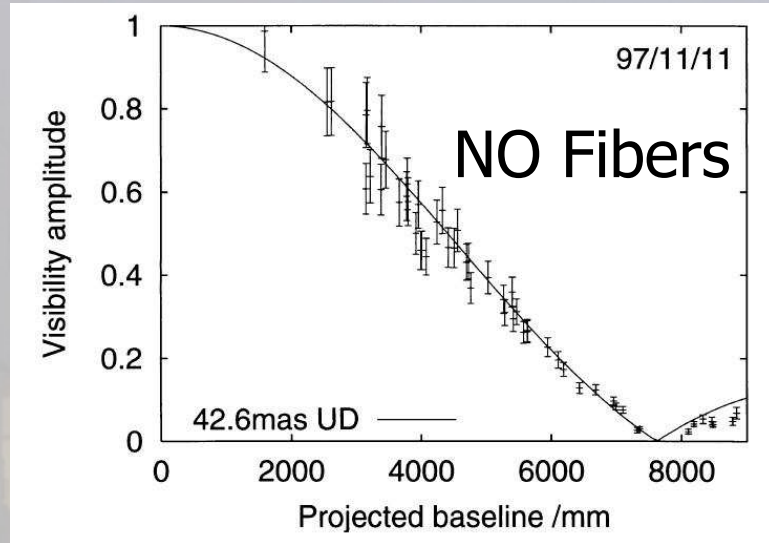
See specific presentations on data reduction next week.



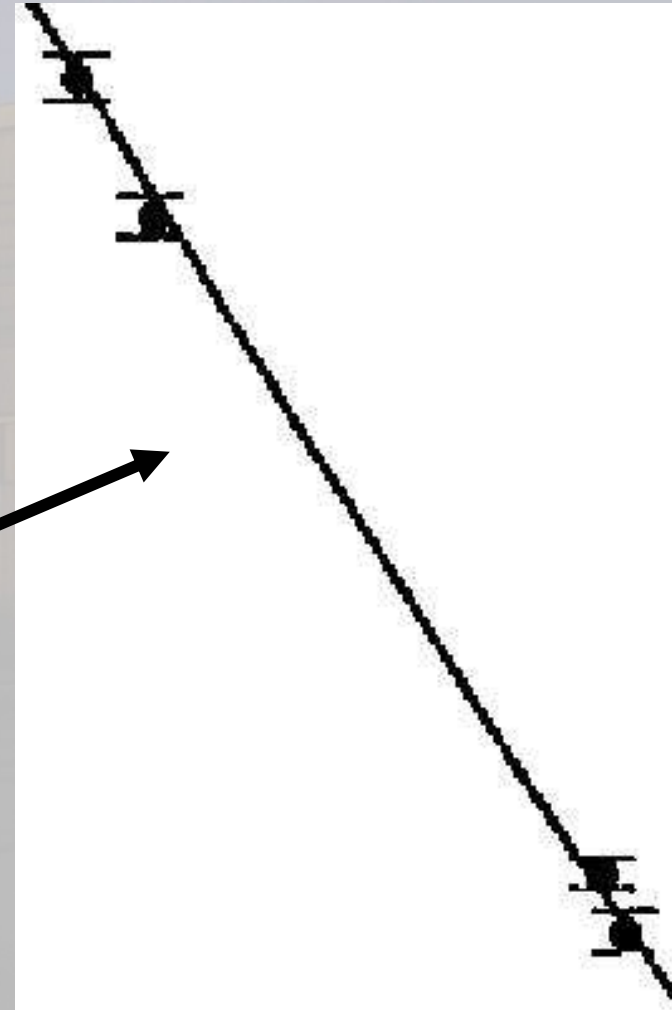
Fighting adverse effects

Spatial filtering with single mode fibers

CALIBRATION

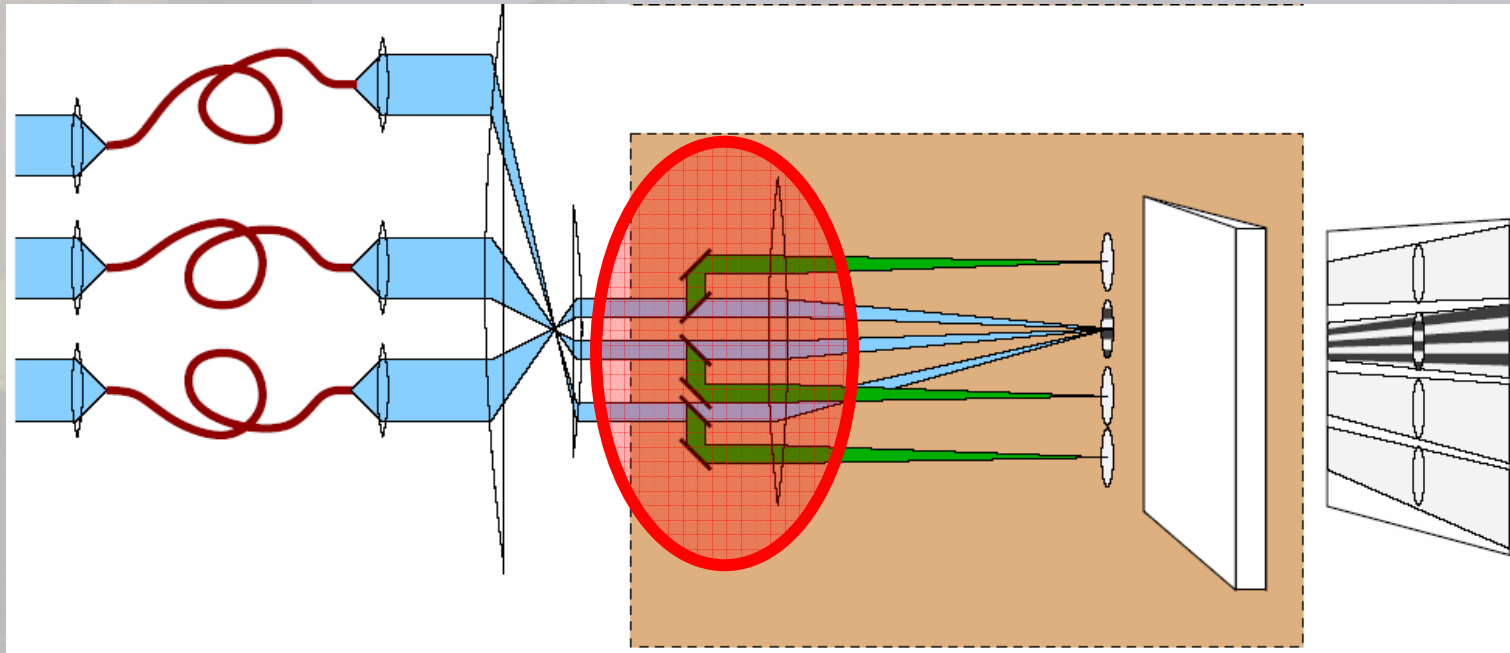


Zoom



Monitoring photometric fluctuations

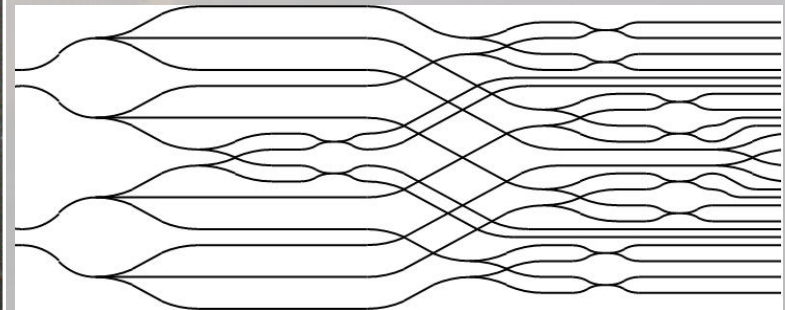
CALIBRATION



Photometric channels monitor the flux in each beam

Instrument stable by construction

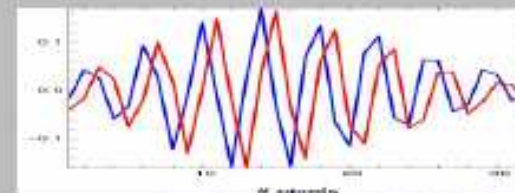
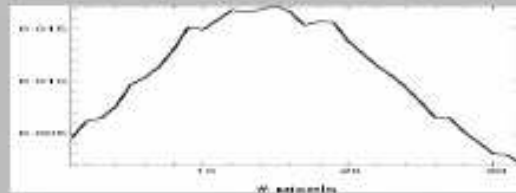
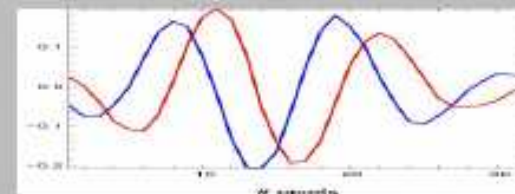
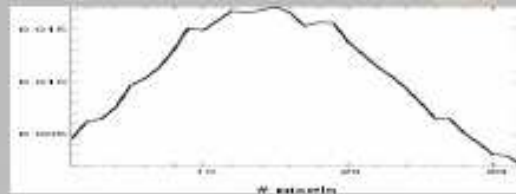
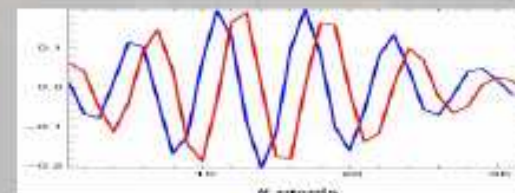
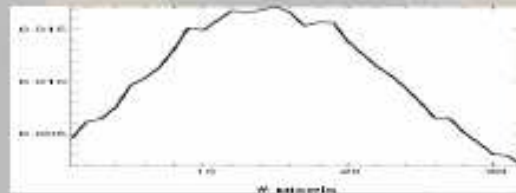
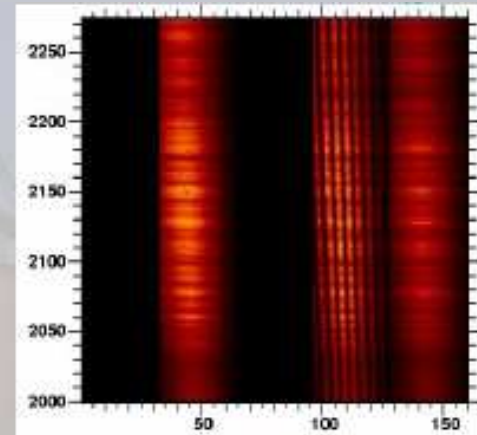
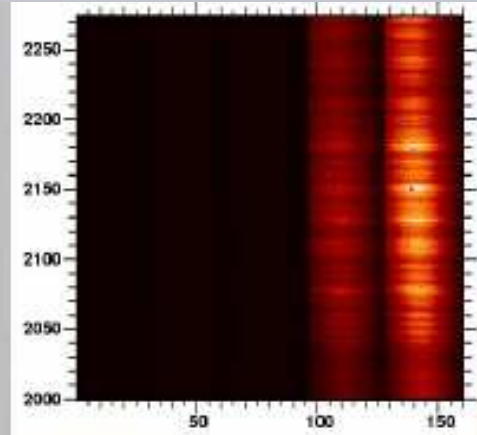
CALIBRATION



IONIC integrated optics used for
the IOTA beam combiner

Appropriate internal calibration and data reduction

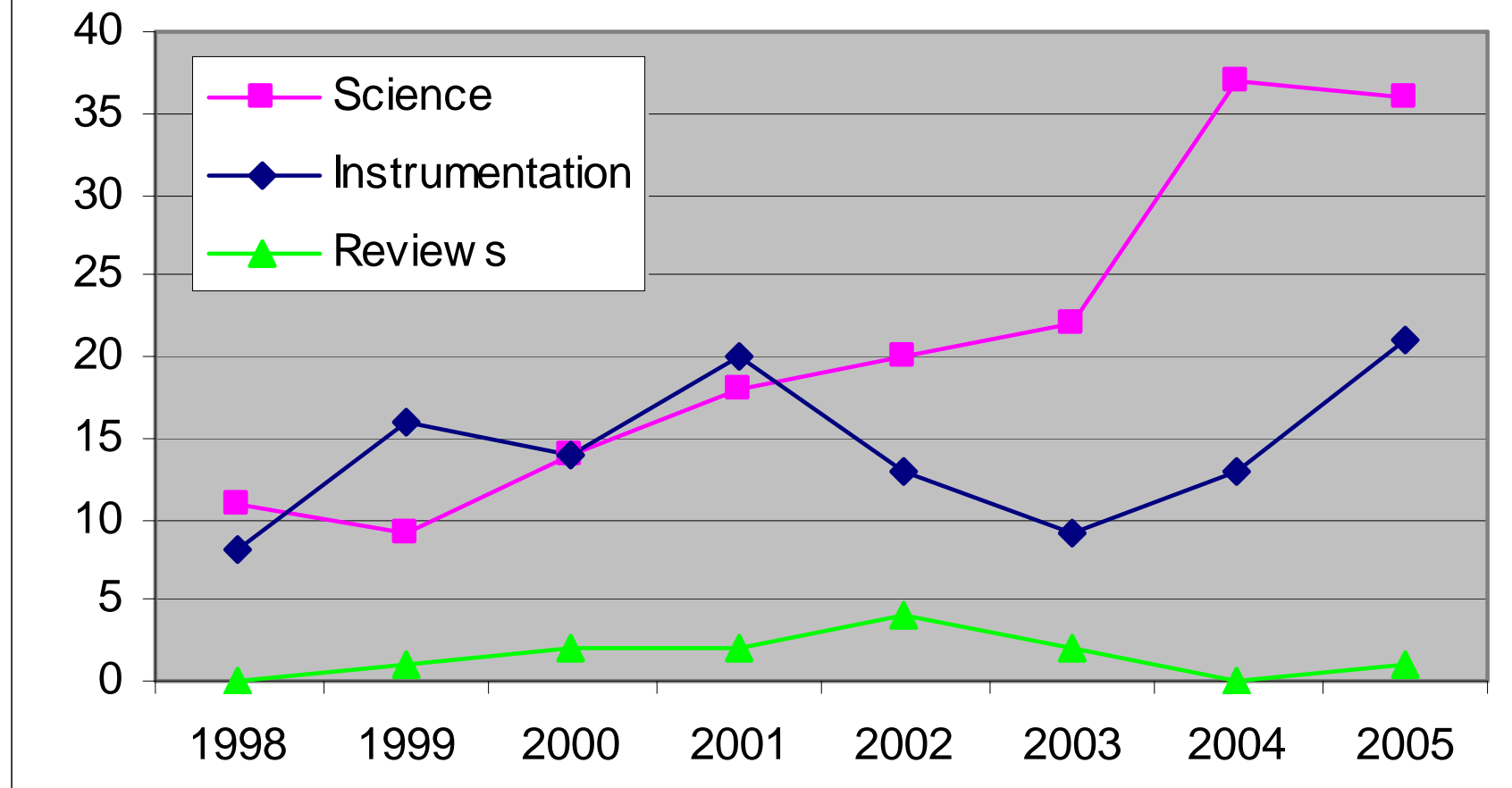
CALIBRATION





Should we be pessimistic?

Interferometry refereed papers



CONCLUSION

There is always a solution when we understand the origin of adverse effects!

We must be patient and keep on working...

- Best if most elements do not move during observations
- Atmosphere is a main contributor
- When increasing complexity, we also increase the potential source of perturbations
- We have many solutions to overcome adverse effects
- It is a daily, or rather a nightly, struggle

One must be aware of these effects and always ready to criticize its own measurements