

# AMBER data reduction

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AMBER data  
reduction

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What is  
AMBER?

In a few words

In principle

In reality

In questions

Spatial filtering

Interferometric  
Equation

Principle

Analysis

Data reduction

Overview

Calibration

Fluxes

Estimation

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Conclusion

# The AMBER/VLTI instrument

## Interferometer using **single mode waveguides**

↪ Spatial filtering of the turbulent wavefront

## With a multiaxial “all-in-one” recombination scheme

↪ Fringes spatially coded on the detector

↪ All fringes coded together in the same interference pattern

## For 2 or 3 telescopes, in the near infrared

↪ Resp. 1 or 3 baselines

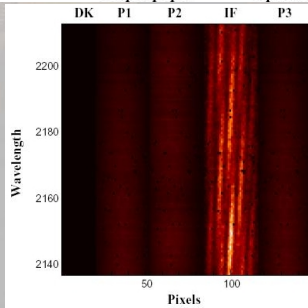
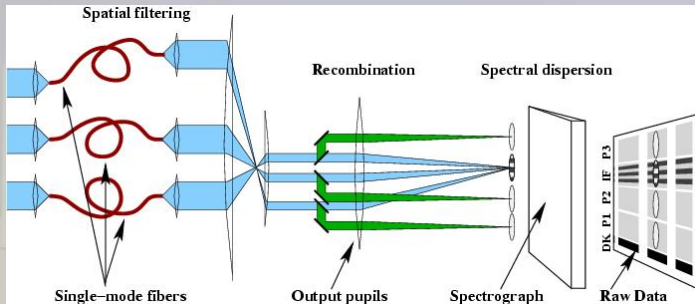
↪ In J ( $1.25\mu\text{m}$ ), H ( $1.65\mu\text{m}$ ) and K ( $2.2\mu\text{m}$ ) bands

↪ Achieves an angular resolution of  $\theta \sim 2\text{mas}$

## Allowing spectral dispersion

↪  $\mathcal{R} = 35, 1500, 10000$

# The signal processing point of view



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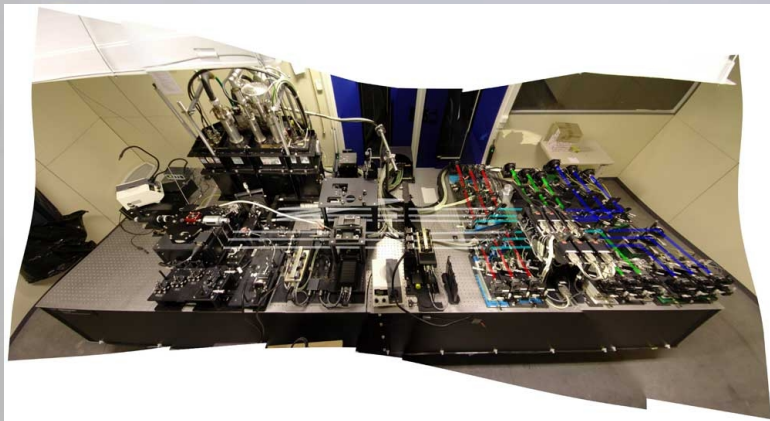
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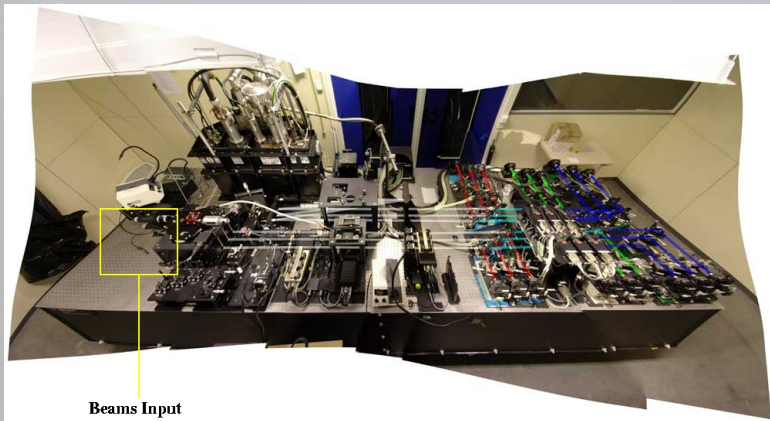
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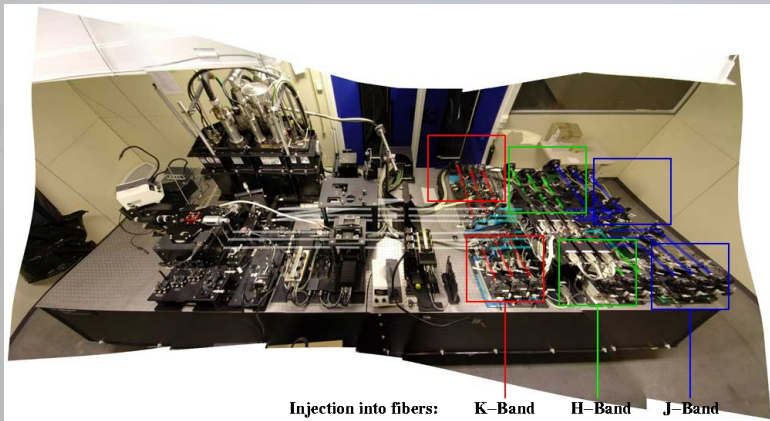
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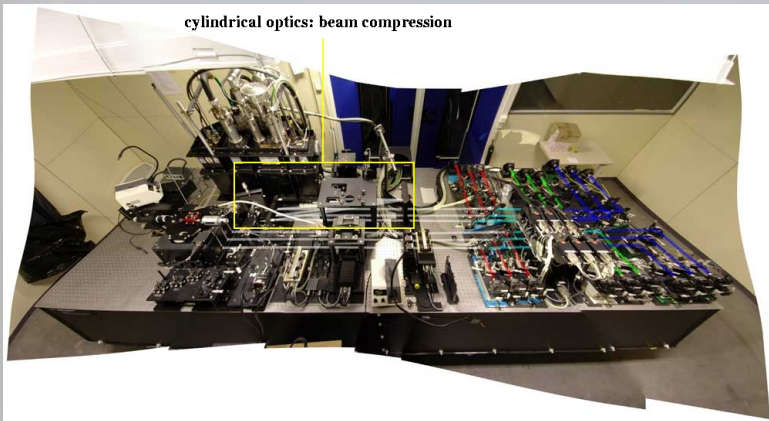
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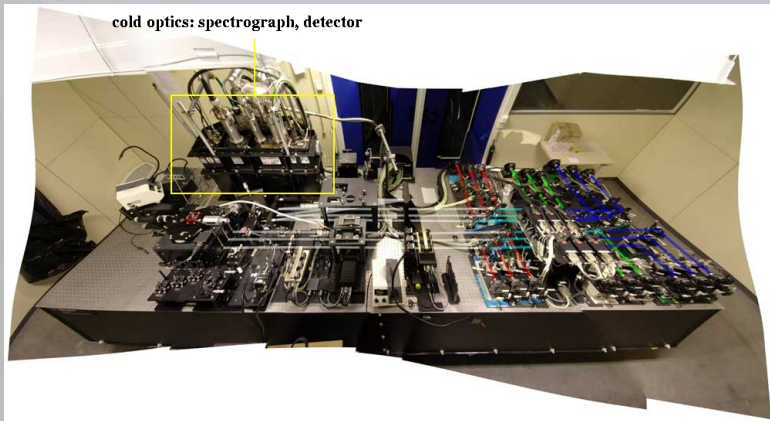
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cylindrical optics: beam compression



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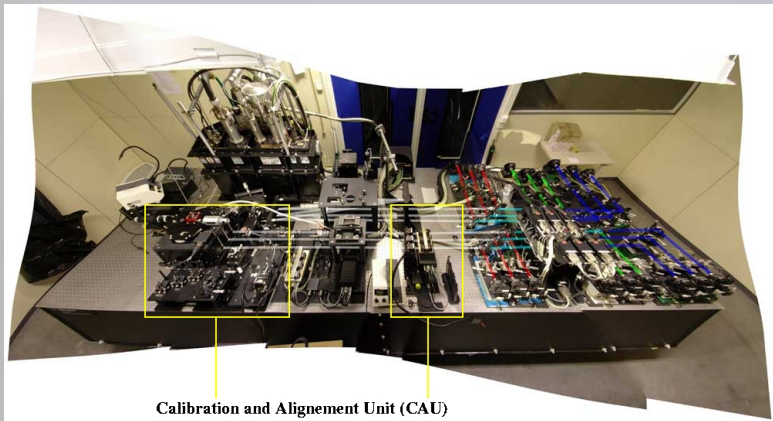
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# The AMBER/VLTI instrument

Interferometer using **single mode** waveguides

With a multiaxial “all-in-one” recombination scheme

for 2 or 3 telescopes, with spectral dispersion

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# The AMBER/VLTI instrument

Interferometer using **single mode waveguides**

**What is their effect on the interferometric signal?**

**How can we use this in the data reduction process?**

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Interferometer using **single mode waveguides**

What is their effect on the interferometric signal?

How can we use this in the data reduction process?

With a multiaxial “all-in-one” recombination scheme

What is the proper AMBER interferometric equation?

What is specific about it?

for 2 or 3 telescopes, with spectral dispersion

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What is the proper AMBER interferometric equation?

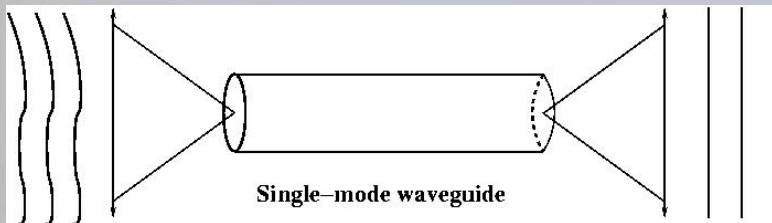
What is specific about it?

for 2 or 3 telescopes, with spectral dispersion

What are the observables of AMBER?

How to estimate them?

# Interferometry with single-mode waveguides



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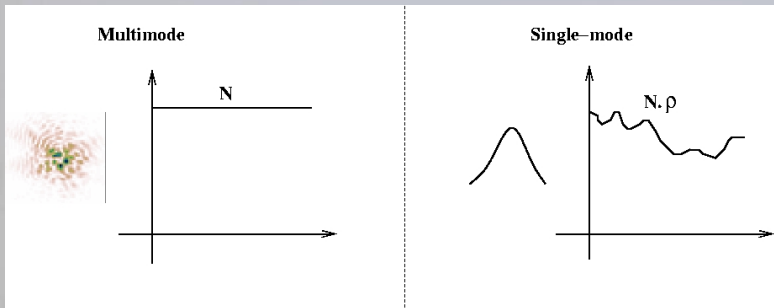
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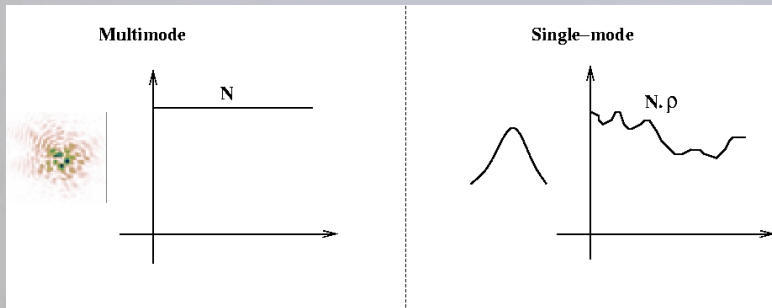
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## At the fiber's output

- The shape of the signal is **deterministic**
- Phase fluctuations → Intensity fluctuations

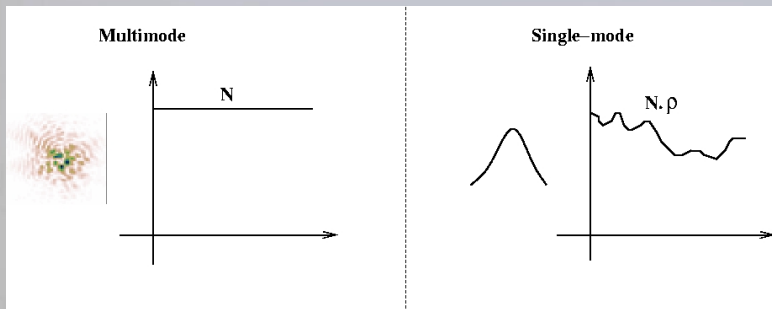
*Coupling coefficient depends on: **turbulence** and **source's extent***



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What do we measure: the modal visibility

→  $V_{ij} \propto \text{TF}[O_*(\alpha)L^{ij}(\alpha)](f_{ij})$

→ Field of view:  $\Theta \sim \frac{\lambda}{D}$

→ The modal visibility is biased

→ For compact sources:  $V_{ij} \sim V_{obj}, \frac{\Delta V}{V} < 10^{-3}$

# Deriving the AMBER interferometric equation

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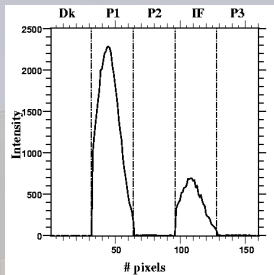
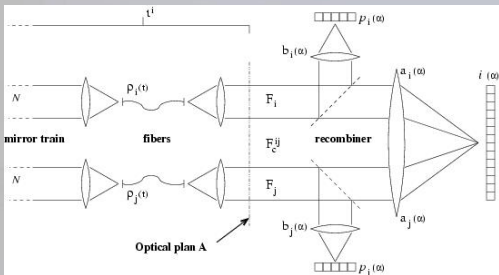
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## Step I: One beam lit

Interferometric channel:  $i_k = F^i a_k^i$

Photometric channel:  $p_k^i = F^i b_k^i$

## Conventions

$k$  in index: pixel coordinate

$i, j$  in exponent: telescope(s)number(s)

## Definitions

$F^i = Nt^i$

photometric flux

$a_k^i, b_k^i$ : intensity profile

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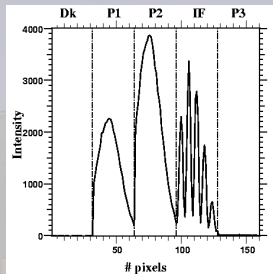
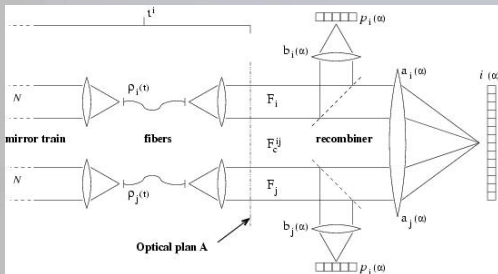
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## Step II: two beams lit

Interferometric channel:

$$i_k = F^i a_k^i + F^j a_k^j +$$

$$\sqrt{a_k^i a_k^j} C_B^{ij} \operatorname{Re} \left[ F_c^{ij} e^{i(2\pi\alpha_k f^{ij} + \phi_s^{ij} + \Phi_B^{ij})} \right]$$

## Definitions

$$F_c^{ij} = 2N\sqrt{t^i t^j} V^{ij} e^{i(\Phi^{ij} + \phi_p^{ij})}$$

coherent flux

$C_B^{ij}, \Phi_B^{ij}$ : polarization

$\phi_s^{ij}$ : instrumental phase

$\alpha_k$ : sampling

$f^{ij}$ : frequency coding

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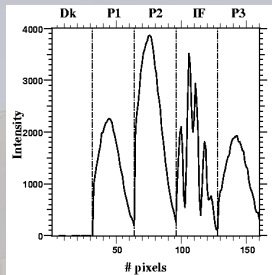
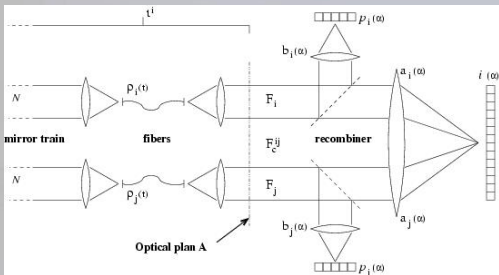
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## Step III: all pairs of beams

Interferometric channel:

$$i_k = \sum_i^{N_{tel}} F^i a_k^i +$$

$$\sum_{i < j}^{N_{tel}} \sqrt{a_k^i a_k^j} C_B^{ij} \operatorname{Re} \left[ F_c^{ij} e^{i(2\pi\alpha_k f^{ij} + \phi_s^{ij} + \phi_B^{ij})} \right]$$

## Definitions

$$F_c^{ij} = 2N\sqrt{t^i t^j} V^{ij} e^{i(\phi^{ij} + \phi_p^{ij})}$$

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# Analyzing the AMBER interferometric equation

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## the AMBER interferometric equation

$$i_k = \underbrace{\sum_i^{N_{tel}} F^i a_k^i}_{DC \text{ component}} = \underbrace{\sum_{i < j}^{N_{tel}} \sqrt{a_k^i a_k^j} C_B^{ij} \operatorname{Re} \left[ F_C^{ij} e^{i(2\pi\alpha_k f^{ij} + \phi_s^{ij} + \Phi_B^{ij})} \right]}_{AC \text{ component}}$$

$$p_k^i = F^i b_k^i \quad \left( P^i = F^i \sum_k^{N_{pix}} b_k^i \right)$$

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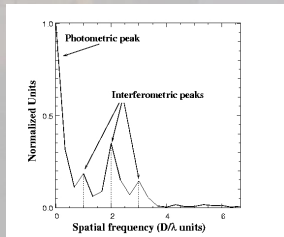
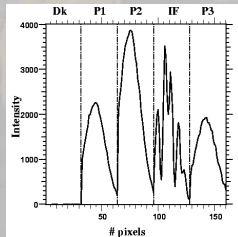
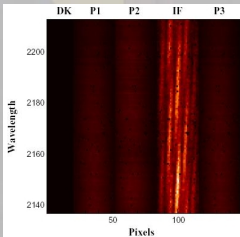
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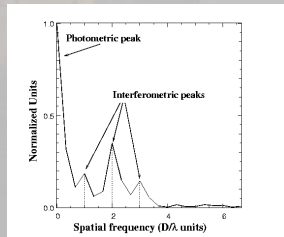
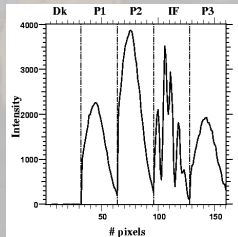
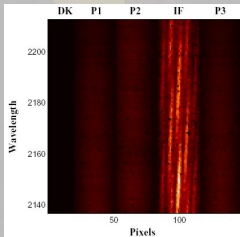
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## the AMBER interferometric equation

$$i_k - \overbrace{\sum_i^{N_{tel}} F^i a_k^i}^{DC \text{ component}} = \overbrace{\sum_{i < j}^{N_{tel}} \sqrt{a_k^i a_k^j} C_B^{ij} \operatorname{Re} \left[ F_c^{ij} e^{i(2\pi\alpha_k f^{ij} + \phi_s^{ij} + \Phi_B^{ij})} \right]}^{AC \text{ component}}$$
$$p_k^i = F^i b_k^i \quad \left( P^i = F^i \sum_k^{N_{pix}} b_k^i \right)$$

A linear relationship between the **measurements** and the **complex visibilities** can be derived

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- Need to estimate the DC component

*The fraction of flux that goes from photometry to DC*

$$P^i v_k^i = F^i a_k^i$$

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- Need to know characteristics of the instrument

*The shape of the interferogram: the carrying waves*

$$c_k^{ij} = C_B^{ij} \frac{\sqrt{a_k^i a_k^j}}{\sqrt{\sum_k a_k^i a_k^j}} \cos(2\pi\alpha_k f^{ij} + \phi_s^{ij} + \Phi_B^{ij})$$

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$$d_k^{ij} = C_B^{ij} \frac{\sqrt{a_k^i a_k^j}}{\sqrt{\sum_k a_k^i a_k^j}} \sin(2\pi\alpha_k f^{ij} + \phi_s^{ij} + \Phi_B^{ij})$$

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A linear relationship between the **measurements** and the **complex visibilities** can be derived

- Requires a calibration of the instrument:  $v_k^i, c_k^{ij}, d_k^{ij}$

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# AMBER data reduction steps

- Modelling the interferogram in the detector plane
- In 5 steps:
  1. Cosmetic (*flatfield, sky...*)
  2. Calibration of the instrument:
    - ↪ *fraction of flux*  $v_k^i$
    - ↪ *carrying waves*  $c_k^{ij}, d_k^{ij}$
  3. Estimation of the photometric  $F^i$  and coherent fluxes  $F_c^{ij}$
  4. Estimation of the observables
  5. Biases correction

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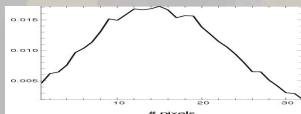
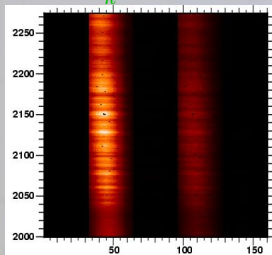
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# Calibration of the instrument

the  $v_k^i$  functions



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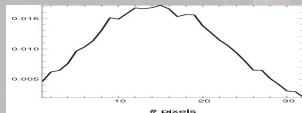
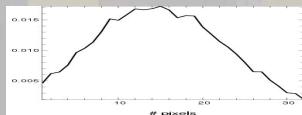
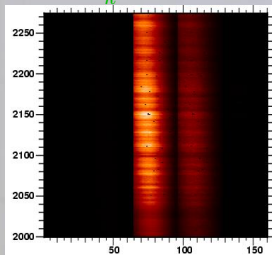
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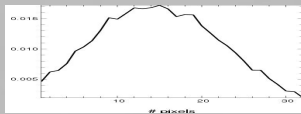
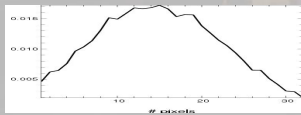
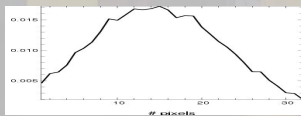
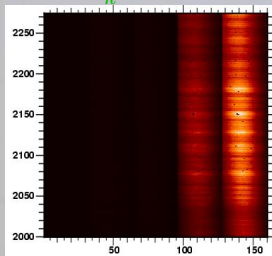
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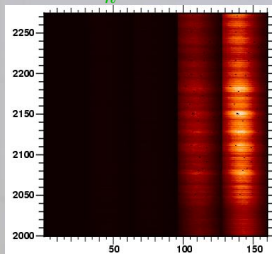
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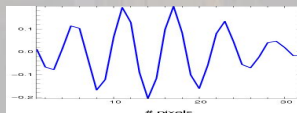
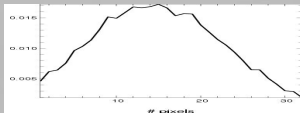
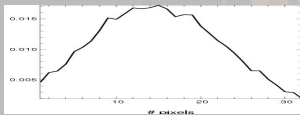
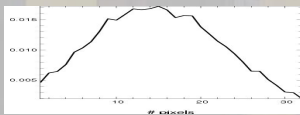
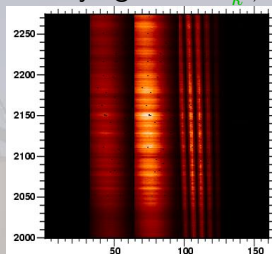
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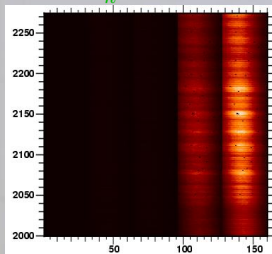
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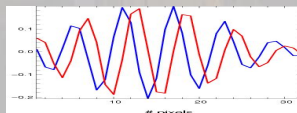
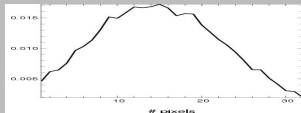
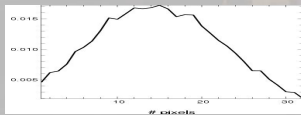
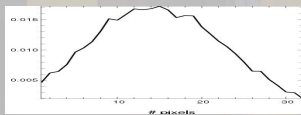
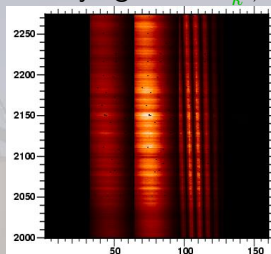
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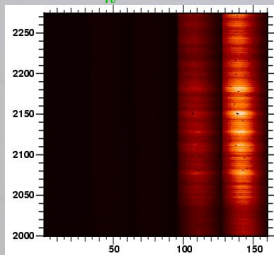


# Calibration of the instrument

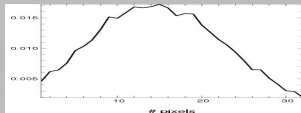
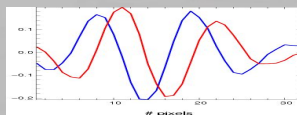
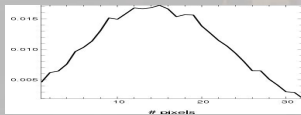
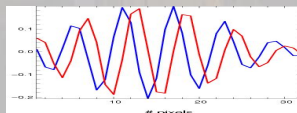
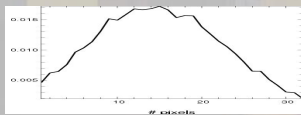
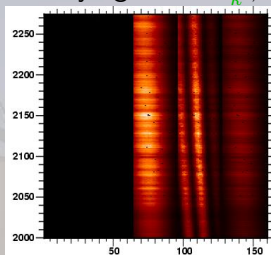
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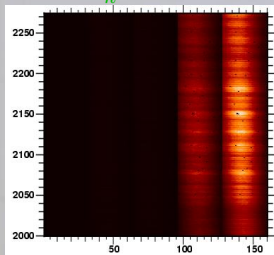
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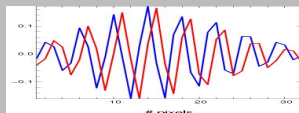
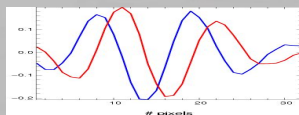
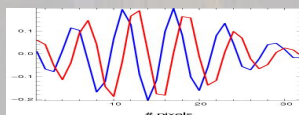
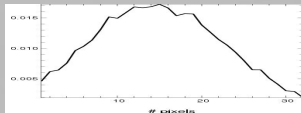
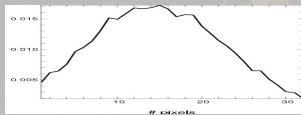
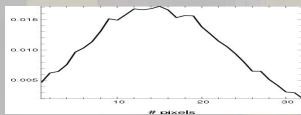
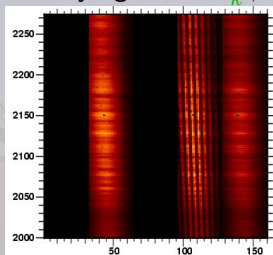
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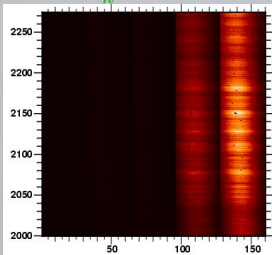
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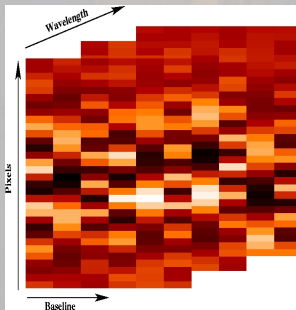
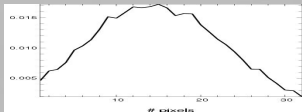
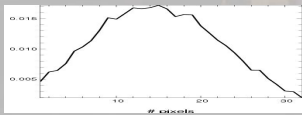
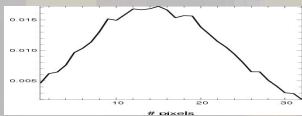
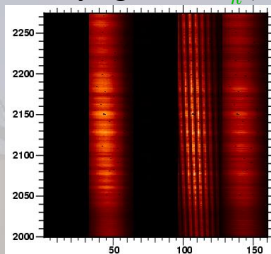
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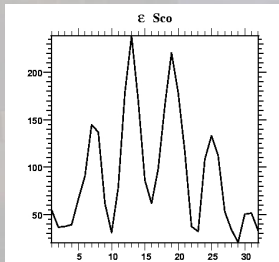
# Photometric and coherent fluxes

$$i_k = \sum_i^{N_{tel}} F^i a_k^i + \sum_{i < j}^{N_{tel}} \sqrt{a_k^i a_k^j} C_B^{ij} \operatorname{Re} \left[ F_c^{ij} e^{i(2\pi\alpha_k f^{ij} + \phi_s^{ij} + \Phi_B^{ij})} \right]$$

## Photometric fluxes

$$F^i a_k^i = P^i v_k^i$$

$$m_k = i_k - \sum_i^{N_{tel}} P^i v_k^i$$



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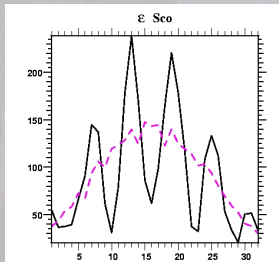
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$$i_k = \sum_i^{N_{tel}} F^i a_k^i + \sum_{i < j}^{N_{tel}} \sqrt{a_k^i a_k^j} C_B^{ij} \operatorname{Re} \left[ F_c^{ij} e^{i(2\pi\alpha_k f^{ij} + \phi_s^{ij} + \Phi_B^{ij})} \right]$$

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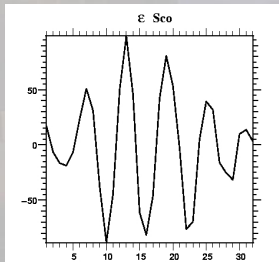
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# Photometric and coherent fluxes

$$m_k = \sum_{i < j}^{N_{tel}} \sqrt{a_k^i a_k^j} C_B^{ij} \operatorname{Re} \left[ F_c^{ij} e^{i(2\pi\alpha_k f^{ij} + \phi_s^{ij} + \Phi_B^{ij})} \right]$$

## Photometric fluxes - DC subtraction

$$F^i a_k^i = P^i v_k^i$$
$$m_k = i_k - \sum_i^{N_{tel}} P^i v_k^i$$



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# Photometric and coherent fluxes

$$m_k = \sum_{i < j}^{N_{tel}} \sqrt{\sum_k a_k^i a_k^j} \left( c_k^{ij} \operatorname{Re} [F_c^{ij}] + d_k^{ij} \operatorname{Im} [F_c^{ij}] \right)$$

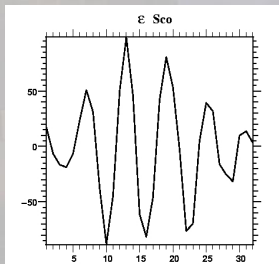
## Coherent flux

$$m_k = \sum_{i < j}^{N_{tel}} c_k^{ij} R^{ij} + d_k^{ij} F_c^{ij}$$

$$R^{ij} = \sqrt{\sum_k a_k^i a_k^j} \operatorname{Re} [F_c^{ij}]$$

$$I^{ij} = \sqrt{\sum_k a_k^i a_k^j} \operatorname{Im} [F_c^{ij}]$$

$$C^{ij} = R^{ij} + iI^{ij} = \sqrt{\sum_k a_k^i a_k^j} F_c^{ij}$$



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$$m_k = \sum_{i < j}^{N_{tel}} \sqrt{\sum_k a_k^i a_k^j \left( c_k^{ij} \operatorname{Re} [F_c^{ij}] + d_k^{ij} \operatorname{Im} [F_c^{ij}] \right)}$$

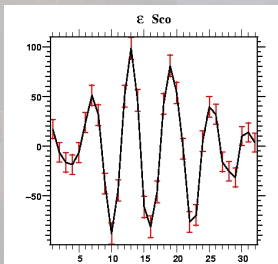
## Coherent flux - Inverting the V2PM

$$m_k = \underbrace{\left[ c_k^{(i,j)}, d_k^{(i,j)} \right]}_{V2PM} \begin{bmatrix} R_{ij} \\ I_{ij} \end{bmatrix}$$

$$R^{ij} = \sqrt{\sum_k a_k^i a_k^j} \operatorname{Re} [F_c^{ij}]$$

$$I^{ij} = \sqrt{\sum_k a_k^i a_k^j} \operatorname{Im} [F_c^{ij}]$$

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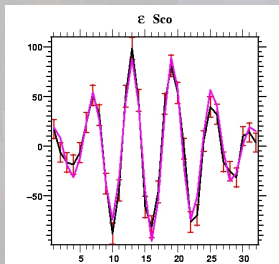
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$$m_k = \underbrace{\begin{bmatrix} c_k^{(i,j)} & d_k^{(i,j)} \end{bmatrix}}_{V2PM} \begin{bmatrix} R_{ij} \\ I_{ij} \end{bmatrix}$$

$$R^{ij} = \sqrt{\sum_k a_k^i a_k^j} \operatorname{Re} [F_c^{ij}]$$

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# The AMBER observables

$$F_c^{ij} = 2N\sqrt{t^i t^j} V^{ij} e^{i(\Phi^{ij} + \phi_p^{ij})}$$

- the modulus of the visibility  
*characteristic size of the source*
  - the phase → *presence of atmospheric piston*
1. the closure phase @ 3 telescopes  
*geometry/asymmetries*
  2. the differential phase @ spectral resolution  
*displacement of the photcenter vs. the wavelength*

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# The phase

$$C^{ij} = R^{ij} + iI^{ij} = \sqrt{\sum_k a_k^i a_k^j} 2N \sqrt{t^i t^j} V^{ij} e^{i(\Phi^{ij} + \phi_p^{ij})}$$

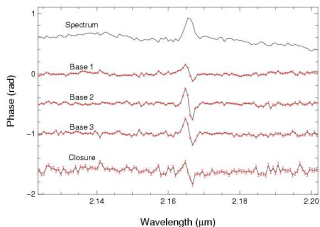
## The closure phase

$$\phi_p^{ij} = \phi_p^i - \phi_p^j$$

$$\tilde{B}^{123} = \langle C^{12} C^{23} C^{13*} \rangle$$

$$\tilde{\phi}_B^{123} = \text{atan} \left[ \frac{\text{Im}(\tilde{B}^{123})}{\text{Re}(\tilde{B}^{123})} \right]$$

$$\tilde{\phi}_B^{123} = \phi^{12} + \phi^{23} - \phi^{13}$$



## The differential phase

$$\widetilde{W}_{12}^{ij} = \langle C_{\lambda_1}^{ij} C_{\lambda_2}^{ij*} \rangle$$

$$\widetilde{\Delta\phi}_{12}^{ij} = \text{atan} \left[ \frac{\text{Im}(\widetilde{W}_{12}^{ij})}{\text{Re}(\widetilde{W}_{12}^{ij})} \right]$$

$$\phi_{\lambda}^{ij} = 2\pi \delta^{ij} \sigma + Cst$$

$$\Delta\phi_{12}^{ij} = \phi_1^{ij} + 2\pi(\sigma_2 - \sigma_1) \delta^{ij}$$

In the continuum:  $\delta^{ij} = \delta_p^{ij}$

In lines:  $\delta^{ij} = \delta_o^{ij} + \delta_p^{ij}$

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# The phase

$$C^{ij} = R^{ij} + iI^{ij} = \sqrt{\sum_k a_k^i a_k^j} 2N \sqrt{t^i t^j} V^{ij} e^{i(\phi^{ij} + \phi_p^{ij})}$$

## The closure phase

$$\phi_p^{ij} = \phi_p^i - \phi_p^j$$

$$\tilde{B}^{123} = \langle C^{12} C^{23} C^{13*} \rangle$$

$$\phi_B^{123} = \text{atan} \left[ \frac{\text{Im}(\tilde{B}^{123})}{\text{Re}(\tilde{B}^{123})} \right]$$

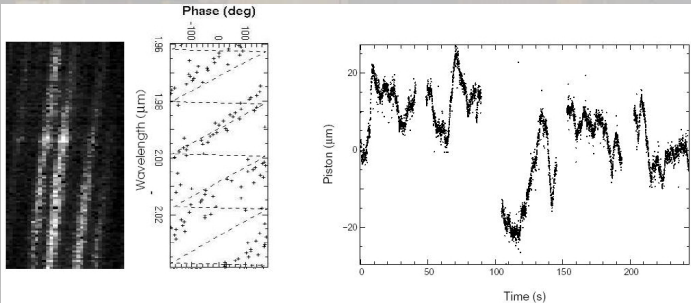
$$\phi_B^{123} = \phi^{12} + \phi^{23} - \phi^{13}$$

## The differential phase

$$\Delta\phi_{12}^{ij} = \phi_1^{ij} + 2\pi(\sigma_2 - \sigma_1)\delta^{ij}$$

$$\text{In the continuum: } \delta^{ij} = \delta_p^{ij}$$

$$\text{In lines: } \delta^{ij} = \delta_o^{ij} + \delta_p^{ij}$$



# The squared visibility

By definition

$$|V^{ij}|^2 = \frac{|F_c^{ij}|^2}{4F^i F^j}$$

- Visibility  $V_c^{ij}$  the internal source (CAU)
- Quadratic bias: photon and detector noise
- Loss of spectral coherence: finite coherence length  $\mathcal{L}_c$
- Atmospheric jitter

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# The squared visibility

By definition

$$|V^{ij}|^2 = \frac{R^{ij^2} + I^{ij^2}}{4P^i P^j \sum_k v_k^i v_k^j}$$

- Visibility  $V_c^{ij}$  the internal source (CAU)
- Quadratic bias: photon and detector noise
- Loss of spectral coherence: finite coherence length  $\mathcal{L}_c$
- Atmospheric jitter

AMBER data  
reduction

E. Tatulli

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# The squared visibility

## Estimation

$$\frac{|\widehat{V_{ij}}|^2}{V_c^{ij^2}} = \frac{\langle R^{ij^2} + I^{ij^2} \rangle}{4 \langle P^i P^j \rangle \sum_k v_k^i v_k^j}$$

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# The squared visibility

## Estimation

$$\frac{|\widehat{V_{ij}}|^2}{V_c^{ij^2}} = \frac{\langle R^{ij^2} + I^{ij^2} \rangle - \text{Bias} \{ R^{ij^2} + I^{ij^2} \}}{4 \langle P^i P^j \rangle \sum_k v_k^i v_k^j}$$

- Visibility  $V_c^{ij}$  the internal source (CAU)
- Quadratic bias: photon and detector noise

$$\text{Bias} \{ R^2 + I^2 \} = \sigma_R^2 + \sigma_I^2$$

$$R = \sum_{k=1}^{N_{pix}} \zeta_k m_k, \quad I = \sum_{k=1}^{N_{pix}} \xi_k^b m_k$$

$$\sigma_R^2 = \sum_k (\zeta_k)^2 \sigma^2(m_k); \quad \sigma_I^2 = \sum_k (\xi_k)^2 \sigma^2(m_k)$$

$$\sigma^2(m_k) = \overline{i_k} + \sigma^2 + \sum_{i=1}^{N_{tel}} [\overline{P_i} + N_{pix} \sigma^2] (v_k^i)^2$$

- Loss of spectral coherence: finite coherence length  $\mathcal{L}_c$
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## Estimation

$$\frac{|\widehat{V_{ij}}|^2}{V_c^{ij^2}} = \frac{\langle R^{ij^2} + I^{ij^2} \rangle - \text{Bias} \{ R^{ij^2} + I^{ij^2} \}}{4 \langle P^i P^j \rangle \sum_k v_k^i v_k^j} < \rho_p^2 >$$

- Visibility  $V_c^{ij}$  the internal source (CAU)
- Quadratic bias: photon and detector noise
- Loss of spectral coherence: finite coherence length  $\mathcal{L}_c$

$$\rho_p = \left| \widehat{\mathcal{F}} \left( \pi \frac{\delta_p + \delta_o}{\mathcal{L}_c} \right) \right|$$

- Atmospheric jitter

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*Fringe motion during the integration time:*

*Must be calibrated on reference source*

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# Error of the visibility

## Semi-empirical formula

$$\frac{\sigma^2(|V^{ij}|^2)}{|V^{ij}|^2} = \frac{1}{M} \left[ \frac{\sigma^2(|C^{ij}|^2)}{|C_{ij}|^2} + \frac{\sigma^2(P^i P^j)}{P^i P^j} \right]$$

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# Error of the visibility

## Semi-empirical formula

$$\frac{\sigma^2(\widetilde{|V^{ij}|^2})}{\widetilde{|V^{ij}|^2}^2} = \frac{1}{M} \left[ \frac{\langle |C^{ij}|^4 \rangle_M - \langle |C^{ij}|^2 \rangle_M^2}{\langle |C^{ij}|^2 \rangle_M^2} + \frac{\langle P^i P^j \rangle_M - \langle P^i P^j \rangle_M^2}{\langle P^i P^j \rangle_M^2} \right]$$

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## Empirical computation

*Bootstrapping!*

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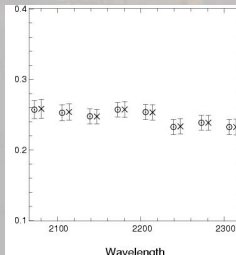
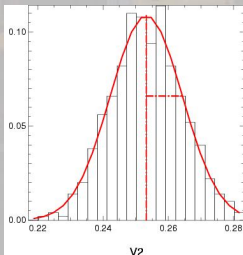
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$$\frac{\sigma^2(\widetilde{|V^{ij}|^2})}{\widetilde{|V^{ij}|^2}^2} = \frac{1}{M} \left[ \frac{\langle |C^{ij}|^4 \rangle_M - \langle |C^{ij}|^2 \rangle_M^2}{\langle |C^{ij}|^2 \rangle_M^2} + \frac{\langle P^i P^j \rangle_M - \langle P^i P^j \rangle_M^2}{\langle P^i P^j \rangle_M^2} \right]$$

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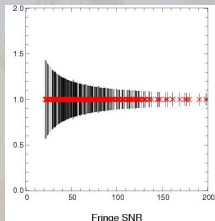
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# Current limitations

- VLTI status: vibrations along the ,
  - no fringe tracker, low limiting magnitude
  - Potentially non stationary: absolute calibration?



- Careful check of evolution of the transfer function (*more than 1 calibrator*)
- Fringe selection + jitter dispersion
- Strong effort from ESO to identify/suppress sources of vibration

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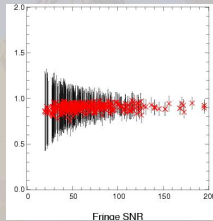
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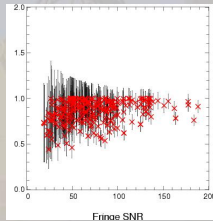
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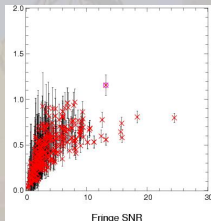
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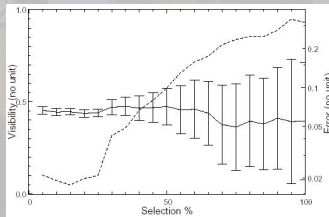
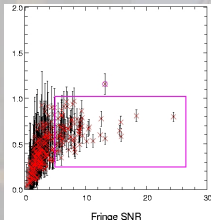
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# In summary

The AMBER data reduction process:

- fit of the interferogram in the detector plane
  - ↪ allows fourier fringe peaks overlapping
- uses *a priori* of the instrument:  $v_k^i, c_k^{ij}, d_k^{ij}$ 
  1. requires a calibration step  $\Leftrightarrow$  the “P2VM” computation
  2. the calibration matrix needs to be **accurate** and **stable**
- $[M] = [MV2P][V] \rightarrow$  Inversion of the calibration matrix
- the observables are:
  1. the modulus of the visibility: *spatial extent*
  2. the closure phase @ 3 telescopes: *geometry/asymmetries*
  3. the differential phase @ spectral resolution: *kinematics*

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